

Robotics and Intelligent Systems

Bachelor of Science

Subject-specific Examination Regulations for Robotics and Intelligent Systems (Fachspezifische Prüfungsordnung)

The subject-specific examination regulations for Robotics and Intelligent Systems are defined by this program handbook and are valid only in combination with the General Examination Regulations for Undergraduate degree programs (General Examination Regulations = Rahmenprüfungsordnung). This handbook also contains the program-specific Study and Examination Plan (Chapter 6).

Upon graduation, students in this program will receive a Bachelor of Science (BSc) degree with a scope of 180 ECTS (for specifics see Chapter 4 of this handbook).

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1.1 Concept

1.1.1 The Constructor University Educational Concept

Constructor University aims to educate students for both an academic and a professional career by emphasizing three core objectives: academic excellence, personal development, and employability to succeed in the working world. Constructor University offers an excellent research driven education experience across disciplines to prepare students for graduate education as well as career success by combining disciplinary depth and interdisciplinary breadth with supplemental skills education and extra-curricular elements. Through a multi- disciplinary, holistic approach and exposure to cutting-edge technologies and challenges, Constructor University develops and enables the academic excellence, intellectual competences, societal engagement, professional and scientific skills of tomorrows leaders for a sustainable and peaceful future.

In this context, it is Constructor University's aim to educate talented young people from all over the world, regardless of nationality, religion, and material circumstances, to become citizens of the world who are able to take responsible roles for the democratic, peaceful, and sustainable development of the societies in which they live. This is achieved through a high-quality teaching as well as manageable study loads and supportive study conditions. Study programs and related study abroad programs convey academic knowledge as well as the ability to interact positively with other individuals and groups in culturally diverse environments. The ability to succeed in the working world is a core objective for all study programs at Constructor University, both in terms of actual disciplinary subject matter and also to the social skills and intercultural competence. Study-program-specific modules and additional specializations provide the necessary depth, interdisciplinary offerings and the minor option provide breadth while the university-wide general foundation and methods modules, optional German language and Humanities modules, and an extended internship period strengthen the employability of students. The concept of living and learning together on an international campus with many cultural and social activities supplements students' education. In addition, Constructor University offers professional advising and counseling.

Constructor University's educational concept is highly regarded both nationally and internationally. While the university has consistently achieved top marks over the last decade in Germany's most comprehensive and detailed university ranking by the Center for Higher Education (CHE), it has also been listed by one of the most widely observed university rankings, the Times Higher Education (THE) ranking. More details on the current ranking positions found can be at https://constructor.university/more/about-us.

1.1.2 Program Concept

Robotics and intelligent systems are more and more present in everyday life. Artificial intelligence and Machine learning are at the forefront of today's interconnected society.

Automation with some sort of embedded intelligence is now the norm rather than the exception. This program covers engineering methods and technologies that are relevant for freeing artificial mobile systems from permanent human supervision, to enable systems to perform autonomous intelligent operations. Application areas include the automotive and transport industries, robotics and automation, communication technologies, marine technology, and logistics. Hands-on experience with technical systems and methods is provided in first-class labs across the entire program.

During the first year, the foundations of the program are laid out, with programming courses, algorithms, and a comprehensive introduction to robotics and intelligent systems. The second year represents the core of the educational offering of the program, with courses focused on Robotics Systems (Robotics, Machine Learning), Automation and Control (Automation, Embedded Systems, Control Systems), and Intelligent Systems (Computer Vision, Artificial Intelligence). The RIS Lab and RIS project will complement the theoretical education, with use of both robotics simulators and real systems. During the third year, based on their specific interests and career goals, students can choose a variety of specialization courses to complement the core education in depth or breadth. Because robotics science is rooted in mathematics, students will take math methods modules covering calculus, linear algebra, probability theory, and numerical methods or discrete mathematics.

The job market for roboticists and experts in intelligent systems is increasing continuously, and all indications point to the growth of the sector in the near future. Because of the rapid changes in the field, it is important to focus the education on fundamental principles and in subfields of promising future relevance. Cross-disciplinary breadth and flexibility, as well as social and work organization skills are increasingly important. The minor option allows the combination of the education in robotics and intelligent systems with a different discipline, facilitating a cross- disciplinary specialization. The academic qualifications and personal profiles for academic and industrial careers differ. Constructor University's Robotics and Intelligent Systems track designed for students who plan to join the industry, work in / found a start-up, or join graduate programs. A minor track allows students to obtain basic skills in specific application domains, which makes them well suited to work in specific industrial sectors.

1.2 Specific Advantages of Robotics and Intelligent Systems at Constructor University

- Robotics and Intelligent Systems is positioned in the School of Computer Science & Engineering. It has been designed with an interdisciplinary approach, incorporating concepts from various engineering disciplines such as Computer Science, Electrical Engineering, Mechanical Engineering, and Logistics.
- Although programs on Automation, Robotics, and Mechatronics exist in other universities, what makes Robotics and Intelligent Systems stand out is that, in addition to covering the aforementioned areas, it puts a special emphasis on the key concepts of Intelligence and Autonomy, which are important for the man-made systems of the future. Hence, students are given a solid background in fields such as Control Systems, Machine Learning, and Computer Vision.
- The Robotics and Intelligent Systems program is geared toward the world-renowned automation and robotics industry in Germany. As confirmed by keyword-searches on popular job-portals, engineers with additional skills in Vision, Machine Learning, and Robotics are much sought after by the well-established German and European automobile industry. A mandatory internship during the summer before the fifth

semester allows students to gain industrial experience and make contacts for potential future job opportunities.

- Cooperation with universities abroad allows ample choice for students interested in studying a semester abroad.
- The Robotics@Constructor initiative is a unique program to bring undergraduate students close to robotics systems, working with a variety of platforms. State-of-the-art, high-end equipment includes systems working in land, aerial, and marine domains, ranging from underwater robots to autonomous driving, and from humanoids to drones
- Based on their performance and interest, students can team up and participate in robotics competitions, e.g., the European Robotics League, receiving support and guidance from faculty members.
- Many faculty members have research groups that are well-funded by European Union (EU) and German Research Foundation (DFG) projects. Hence, ample opportunities exist for students to get involved and gain research experience.

1.3 Program-Specific Educational Aims

1.3.1 Qualification Aims

The main subject-specific qualification aim is to enable students to take up qualified employment in modern industries involving robotics, autonomous systems, machine learning, artificial intelligence, or to enter related graduate programs. Graduates of the Robotics and Intelligent Systems program have obtained the following competencies:

• Robotics and Intelligent Systems competence

Graduates are able to design and develop autonomous systems in a given application scenario, addressing both electrical engineering and computer science aspects. They can analyze, structure, and properly address complex problems. Graduates have the ability to construct and maintain complex robotics systems using a structured, analytic, and creative approach.

Communication competence

Graduates are able to communicate subject-specific topics convincingly in both spoken and written form to fellow roboticists, experts in intelligent systems, industrial or academic colleagues, as well as to current and potential customers.

• Teamwork and project management competence

Graduates are able to work effectively in a team and to organize workflows in complex development efforts. They are familiar with tools that support the development, testing, and maintenance of complex intelligent systems and they can take design decisions in a constructive way.

Learning competence

Graduates have acquired a solid foundation enabling them to learn effectively and to stay up to date with the latest developments in the fast-changing field of robotics and intelligent systems.

• Personal and professional competence

Graduates are able to develop a professional profile, justify professional decisions on the basis of theoretical and methodical knowledge, and critically on reflect their behavior, also with respect to its consequences for society.

During the design of the program, national guidelines published by the Gesellschaft für Informatik (GI) (GI: Empfehlungen für Bachelor- und Masterprogramme im Studienfach Informatik an Hochschulen, July 2016) and international guidelines published jointly by the Association for Computing Machinery (ACM) and the Institute of Electrical and Electronics Engineers (IEEE) (ACM/IEEE: Computer Science Curricula 2013, December 2013) have been consulted.

1.3.2 Intended Learning Outcomes

By the end of the program, students will be able to

- 1. design basic electronics circuits
- 2. think in an analytic way at multiple levels of abstraction
- 3. develop, analyze and implement algorithms using modern software engineering methods.
- 4. demonstrate knowledge of kinematics and dynamics of multi-body systems
- 5. design and develop linear and nonlinear control systems
- 6. design basic electronics circuits
- 7. examine physical problems, apply mathematical skills to find possible solutions and assess them critically
- 8. show competence about operational principles of motors and drives
- 9. design and develop machine learning algorithms and techniques for pattern-recognition, classification, and decision-making under uncertainty;
- 10. design and develop computer vision algorithms for inferring 3D information from camera images, and for object recognition and localization
- 11. model common mechanical and electrical systems that are part of intelligent mobile systems
- 12. design robotics systems and program them using popular robotics software frameworks
- 13. use academic or scientific methods as appropriate in the field of Robotics and Intelligent Systems such as defining research questions, justifying methods, collecting, assessing and interpreting relevant information, and drawing scientifically founded conclusions that consider social, scientific, and ethical insights
- 14. develop and advance solutions to problems and arguments in their subject area and defend these in discussions with specialists and non-specialists;
- 15. engage ethically with the academic, professional, and wider communities and to actively contribute to a sustainable future, reflecting and respecting different views;
- 16. take responsibility for their own learning, personal, and professional development and role in society, evaluating critical feedback and self-analysis;
- 17. apply their knowledge and understanding to a professional context;
- 18. work effectively in a diverse team and take responsibility in a team;
- 19. adhere to and defend ethical, scientific, and professional standards.

1.4 Career Options and Support

Career options include areas such as research and development or management tracks in the automotive and transport, robotics and automation, communication technologies, marine technology and logistics industries. Given the increasing need for automation of daily life tasks through intelligent mobile systems, there is a significant number of career options in addition to the core options that are covered in the program.

The Robotics and Intelligent Systems program matches scientific content with real-world use cases. This is a strength of Constructor University's offering, to introduce students to real- world applications.

Field trips to and participation in robotics competitions significantly contribute to bringing students closer to the market and to real challenges, in addition to being an excellent opportunity for professional networking.

Companies which hired recent graduates of the IMS program (Intelligent Mobile Systems, the former name of RIS) include Cambio CarSharing Deutschland, Daimler AG, Klöckner Desma GmbH, Objective Software GmbH, and Ubimax.

Several graduate programs have offered a position to IMS students, including the Master in Artificial Intelligence, offered by Universita' della Svizzera Italiana (Switzerland), the Erasmus Mundus Joint Master Degree on Advanced Robotics, offered by Centrale Nantes (France), University of Genoa (Italy), Warsaw University of Technology (Poland), and Jaume I University (Spain), as well as the Master in Robotics, offered by Heriot-Watt University (Scotland, UK).

The Career Service Center (CSC) helps students in their career development. It provides students with high-quality training and coaching in CV creation, cover letter formulation, interview preparation, effective presenting, business etiquette, and employer research as well as in many other aspects, thus helping students identify and follow up on rewarding careers after graduating from Constructor University. Furthermore, the Alumni Office helps students establish a long-lasting and global network which is useful when exploring job options in academia, industry, and elsewhere.

1.5 Admission Requirements

Admission to Constructor University is selective and based on a candidate's school and/or university achievements, recommendations, self-presentation, and performance on standardized tests. Students admitted to Constructor University demonstrate exceptional academic achievements, intellectual creativity, and the desire and motivation to make a difference in the world.

The following documents need to be submitted with the application:

- Recommendation Letter (optional)
- Official or certified copies of high school/university transcripts
- Educational History Form
- Standardized test results (SAT/ACT) if applicable
- Motivation statement
- ZeeMee electronic resume (optional)
- Language proficiency test results (TOEFL Score: 90, IELTS: Level 6.5 or equivalent)

Formal admission requirements are subject to higher education law and are outlined in the Admission and Enrollment Policy of Constructor University.

For more detailed information about the admission visit: https://constructor.university /admission-aid/application-information-undergraduate

1.6 More information and contacts

For more information on the study program please contact the Study Program Coordinator:

Prof. Dr. Francesco Maurelli

Professor of Marine Systems and Robotics Email:

fmaurelli@constructor.university

or visit our website: <u>https://constructor.university/programs/undergraduate-education/robotics-intelligent-systems</u>

For more information on Student Services please visit:

https://constructor.university/student-life/student-services

2 The Curricular Structure

2.1 General

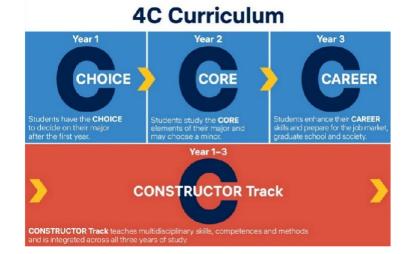
The curricular structure provides multiple elements for enhancing employability, interdisciplinarity, and internationality. The unique CONSTRUCTOR Track, offered across all undergraduate study programs, provides comprehensive tailor-made modules designed to achieve and foster career competency. Additionally, a mandatory internship of at least two months after the second year of study and the possibility to study abroad for one semester give students the opportunity to gain insight into the professional world, apply their intercultural competences and reflect on their roles and ambitions for employment and in a globalized society.

All undergraduate programs at Constructor University are based on a coherently modularized structure, which provides students with an extensive and flexible choice of study plans to meet the educational aims of their major as well as minor study interests and complete their studies within the regular period.

The framework policies and procedures regulating undergraduate study programs at Constructor University can be found on the website (<u>https://constructor.university/student-life/student-services/university-policies</u>).

2.2 The Constructor University 4C Model

Constructor University offers study programs that comply with the regulations of the European Higher Education Area. All study programs are structured according to the European Credit Transfer System (ECTS), which facilitates credit transfer between academic institutions. The three-year undergraduate programs involve six semesters of study with a total of 180 ECTS credit points (CP). The undergraduate curricular structure follows an innovative and student- centered modularization scheme, the 4C Model. It groups the disciplinary content of the study program in three overarching themes, CHOICE-CORE-CAREER according to the year of study, while the university-wide CONSTRUCTOR Track is dedicated to multidisciplinary content dedicated to methods as well as intellectual skills and is integrated across all three years of study. The default module size is 5 CP, with smaller 2.5 CP modules being possible as justified exceptions, e.g., if the learning goals are more suitable for 2.5 CP and the overall student workload is balanced.



2.2.1 Year 1 – CHOICE

The first study year is characterized by a university-specific offering of disciplinary education that builds on and expands upon the students' entrance qualifications. Students select introductory modules for a total of 45 CP from the CHOICE area of a variety of study programs, of which 15-45 CP will belong to their intended major. A unique feature of our curricular structure allows students to select their major freely upon entering Constructor University. The team of Academic Advising Services offers curriculum counseling to all Bachelor students independently of their major, while Academic Advisors, in their capacity as contact persons from the faculty, support students in deciding on their major study program.

To pursue Robotics and Intelligent Systems as a major, the following CHOICE modules (45 CP) need to be taken:

- CHOICE Module: Mathematical and Physical Foundations of Robotics I (m, 7.5 CP)
- CHOICE Module: Mathematical and Physical Foundations of Robotics II (m, 7.5 CP)
- CHOICE Module: Programming in C and C++ (m, 7.5 CP)
- CHOICE Module: Algorithms and Data Structures (m, 7.5 CP)
- CHOICE Module: General Electrical Engineering (m, 7.5 CP)
- CHOICE Module: Digital Systems and Computer Architecture (m, 7.5 CP)

Students can still change to another major at the beginning of their second year of studies, provided they have taken the corresponding mandatory CHOICE modules in their first year of studies. All students must participate in an entry advising session with their Academic Advisors to learn about their major change options and consult their Academic Advisor during the first year of studies prior to changing their major.

To allow further major changes after the first semester the students are strongly recommended to register for the CHOICE modules of one of the following study programs:

- Electrical and Computer Engineering (ECE):
 - CHOICE Module: General Electrical Engineering I (m, 7.5 CP) CHOICE Module: General Electrical Engineering II (m, 7.5 CP) CHOICE Module: Classical Physics (m, 7.5 CP) CHOICE Module: Digital Systems and Computer Architecture (m, 7.5 CP) CHOICE Module: Foundations of Communications and Electronics (m, 7.5 CP)

2.2.2 Year 2 – CORE

In their second year, students take a total of 45 CP from a selection of in-depth, discipline- specific CORE modules. Building on the introductory CHOICE modules and applying the methods and skills acquired so far (see 2.3.1), these modules aim to expand the students' critical understanding of the key theories, principles, and methods in their major for the current state of knowledge and best practice.

To pursue Robotics and Intelligent Systems as a major, 30 CP from the following mandatory (m) and mandatory elective (me) CORE modules need to be taken:

- CORE Module: Robotics (m, 5 CP)
- CORE Module: Artificial Intelligence (m, 5 CP)
- CORE Module: RIS Lab (me, 5 CP)
- CORE Module: Automation (me, 5 CP)
- CORE Module: Embedded Systems (me, 5 CP)

- CORE Module: Control Systems (me, 5 CP)
- CORE Module: Computer Vision (me, 5 CP)
- CORE Module: Machine Learning (m, 5 CP)
- CORE Module: RIS Project (m, 5 CP)

15 CP can be selected according to interest and/or with the aim of pursuing a minor in Computer Science, or students complement their studies by taking all of the above listed mandatory elective CORE modules.

Robotics and Intelligent Systems students can take CORE modules (or more advanced Specialization modules) from other programs, which allows them to incorporate a minor study track into their undergraduate education, within the 180 CP required for a bachelor's degree. The educational aims of a minor are to broaden the students' knowledge and skills, support the critical reflection of statements in complex contexts, foster an interdisciplinary approach to problem-solving, and to develop an individual academic and professional profile in line with students' strengths and interests. This extra qualification will be highlighted in the transcript.

The Academic Advising Coordinator, Academic Advisor, and the Study Program Chair of the minor study program support students in the realization of their minor selection; the consultation with the Academic Advisor is mandatory when choosing a minor.

According to the default study plan RIS students have the option to pursue a minor in Computer Science.

This requires Robotics and Intelligent Systems students to

 substitute the three mandatory elective Robotics and Intelligent Systems CORE modules (15 CP) in the second year with the default minor CORE modules of the Computer Science program.

The requirements for the specific minors are described in the handbook of the study program offering the minor (Chapter 3.2) and are marked in the respective Study and Examination Plans.

2.2.3 Year 3 – CAREER

During their third year, students prepare and make decisions about their career path after graduation. To explore available choices and to gain professional experience, students undertake a mandatory summer internship. The third year of studies allows RIS students to take Specialization modules within their discipline, but also focuses on the responsibility of students beyond their discipline (see CONSTRUCTOR Track).

The fifth semester also opens a mobility window for a diverse range of study abroad options. Finally, the sixth semester is dedicated to fostering the students' research experience by involving them in an extended Bachelor thesis project.

The third year of studies allows RIS students to take Specialization modules within their discipline, but also focuses on the responsibility of students beyond their discipline (see CONSTRUCTOR Track).

2.2.3.1 Internship / Start-up and Career Skills Module

As a core element of Constructor University's employability approach students are required to engage in a mandatory two-month internship of 15 CP that will usually be completed during the summer between the second and third years of study. This gives students the opportunity to gain first-hand practical experience in a professional environment, apply their knowledge and understanding in a professional context, reflect on the relevance of their major to employment and society, reflect on their own role in employment and society, and find a professional orientation. The internship can also establish valuable contacts for the students' Bachelor's thesis project, for the selection of a Master program graduate school or further employment after graduation. This module is complemented by career advising and several career skills workshops throughout all six semesters that prepare students for the transition from student life to professional life. As an alternative to the full-time internship, students interested in setting up their own company can apply for a start-up option to focus on developing of their business plans.

For further information, please contact the Career Service Center (CSC) (https://constructor.university/student-life/career-services).

2.2.3.2 Specialization Modules

In the third year of their studies, students take 15 CP from major-specific or major-related, advanced Specialization Modules to consolidate their knowledge and to be exposed to state-of- the-art research in the areas of their interest. This curricular component is offered as a portfolio of modules, from which students can make free selections during their fifth and sixth semester. The default Specialization Module size is 5 CP, with smaller 2.5 CP modules being possible as justified exceptions.

To pursue RIS as a major, 15 CP from the following mandatory elective Specialization Modules need to be taken:

- RIS Specialization: Human Computer Interaction (me, 5 CP)
- RIS Specialization: Marine Robotics (me, 5 CP)
- RIS Specialization: Optimization (me, 5 CP)
- CS Specialization: Distributed Algorithms (me, 5 CP)
- CS Specialization: Computer Graphics (me, 5 CP)
- CS Specialization: Web Application Development (me, 5 CP)
- CS CORE: Software Engineering (me, 7.5 CP)
- CS CORE: Databases (me, 7.5 CP)
- ECE Specialization: Digital Design (me, 5 CP)
- ECE CORE: PCB design and measurement automation (me, 5 CP)
- ECE CORE: Information Theory (me, 5 CP)
- MATH Specialization: Stochastic Processes (me, 5 CP)
- MATH Specialization: Stochastic Modeling and Financial Mathematics (me, 5 CP)
- IEM CORE: Operations Research (me, 5 CP)
- DE ELECTIVE: Parallel and Distributed Computing (me, 5 CP)

Available for RIS students minoring in the respective study program that meet the pre-requisites / co-requisites $^{\rm 1}$

- CS Specialization: Image Processing (me, 5 CP)
- CS Specialization: Automata, Computability, and Complexity (me, 7.5 CP)
- CS Specialization: Computer Networks (me, 5 CP)
- CS Specialization: Operating Systems (me, 7.5 CP)
- ECE Specialization: Electronics (me, 5 CP)

¹ For module descriptions, see the respective handbook offering the modules.

- ECE Specialization: Digital Signal Processing (me, 7.5 CP)
- ECE Specialization: Signals and Systems (me, 7.5 CP)
- IEM Specialization: Industry 4.0 and Blockchain Technologies (me, 5 CP)
- IEM Specialization: Process Modeling and Simulation (me, 5 CP)

In case of students pursuing a minor, the CORE modules of the Robotics and Intelligent Systems program which are substituted for the minor modules are also eligible Specialization Modules.

2.2.3.3 Study Abroad

Students have the opportunity to study abroad for a semester to extend their knowledge and abilities, broaden their horizons and reflect on their values and behavior in a different context as well as on their role in a global society. For a semester abroad (usually the 5th semester), modules related to the major with a workload equivalent to 22.5 CP must be completed. Modules recognized as study abroad CP need to be pre-approved according to Constructor University study abroad procedures. Several exchange programs allow students to directly enroll at prestigious partner institutions worldwide. Constructor University's participation in Erasmus+, the European Union's exchange program, provides an exchange semester at a number of European universities that include Erasmus study abroad funding.

For further information, please contact the International Office (<u>https://constructor.university/</u><u>student-life/study-abroad/international-office</u>).

RIS students that wish to pursue a study abroad in their 5th semester are required to select their modules at the study abroad partners such that they can be used to substitute between 10-15 CP of major-specific Specialization modules and between 5-15 CP of modules equivalent to the non-disciplinary New Skills modules (see CONSTRUCTOR Track). In their 6th semester, according to the study plan, returning study-abroad students complete the Bachelor Thesis/Seminar module (see next section), they take any missing Specialization modules to reach the required 15 CP in this area, and they take any missing New Skills modules to reach 15 CP in this area.

2.2.3.4 Bachelor Thesis/Seminar Module

This module is a mandatory graduation requirement for all undergraduate students. It consists of two module components in the major study program guided by a Constructor faculty member: the Bachelor Thesis (12 CP) and a Seminar (3 CP). The title of the thesis will appear on the students' transcripts.

Within this module, students apply the knowledge skills, and methods they have acquired in their major discipline to become acquainted with actual research topics, ranging from the identification of suitable (short-term) research projects, preparatory literature searches, the realization of discipline-specific research, and the documentation, discussion, and interpretation of the results.

With their Bachelor Thesis students demonstrate mastery of the contents and methods of their majorspecific research field. Furthermore, students show the ability to analyze and solve a well- defined problem with scientific approaches, a critical reflection of the status quo in scientific literature, and the original development of their own ideas. With the permission of a Constructor Faculty Supervisor, the Bachelor Thesis can also have an interdisciplinary nature. In the seminar, students present and discuss their theses in a course environment and reflect on their theoretical or experimental approach and conduct. They learn to present their chosen research topics concisely and comprehensively in front of an audience and to explain their methods, solutions, and results to both specialists and non-specialists.

2.3 The CONSTRUCTOR Track

The CONSTRUCTOR Track is another important feature of Constructor University's educational model. The Constructor Track runs orthogonal to the disciplinary CHOICE, CORE, and CAREER modules across all study years and is an integral part of all undergraduate study programs. It provides an intellectual tool kit for lifelong learning and encourages the use of diverse methodologies to approach crossdisciplinary problems. The CONSTRUCTOR track contains Methods, New Skills and German Language and Humanities modules.

2.3.1 Methods Modules

Methods such as mathematics, statistics, programming, data handling, presentation skills, academic writing, and scientific and experimental skills are offered to all students as part of the Methods area in their curriculum. The modules that are specifically assigned to each study programs equip students with transferable academic skills. They convey and practice specific methods that are indispensable for each students' chosen study program. Students are required to take 20 CP in the Methods area. The size of all Methods modules is 5 CP.

To pursue Robotics and Intelligent Systems as a major, the following Methods modules (20 CP) are mandatory

- Methods Module: Elements of Linear Algebra (me, 5 CP)
- Methods Module: Elements of Calculus (me, 5 CP)
- Methods Module: Probability and Random Processes (m, 5 CP)

Students who have a strong mathematical background can also choose Matrix Algebra and Advanced Calculus I and II (me, 5 CP each) instead of Elements of Linear Algebra and Elements of Calculus.

For the remaining 5 CP RIS students can choose between the Methods modules

• Methods Module: Numerical Methods (me, 5 CP)

and the Mathematics CORE module:

• CORE Module: Discrete Mathematics (me, 5 CP)

2.3.2 New Skills Modules

This part of the curriculum constitutes an intellectual and conceptual tool kit that cultivates the capacity for a particular set of intellectual dispositions including curiosity, imagination, critical thought, and transferability. It nurtures a range of individual and societal capacities, such as self-reflection, argumentation and communication. Finally, it introduces students to the normative aspects of inquiry and research, including the norms governing sourcing, sharing, withholding materials and research results as well as others governing the responsibilities of expertise as well as the professional point of view.

All students are required to take the following modules in their second year:

- New Skills Module: Logic (m, 2.5 CP)
- New Skills Module: Causation and Correlation (m, 2.5 CP)

These modules will be offered with two different perspectives of which the students can choose. The module perspectives are independent modules which examine the topic from different point of views. Please see the module description for more details.

In the third year, students take three 5 CP modules that build upon previous modules in the track and are partially constituted by modules that are more closely linked to each student's disciplinary field of study. The following module is mandatory for all students:

• New Skills Module: Argumentation, Data Visualization and Communication (m, 5 CP)

This module will also be offered with two different perspectives of which the students can choose.

In their fifth semester, students may choose between:

- New Skills Module: Linear Model/Matrices (me, 5 CP) and
- New Skills Module: Complex Problem Solving (me, 5 CP).

The sixth semester also contains the choice between two modules, namely:

- New Skills Module: Agency, Leadership and Accountability (me, 5 CP) and
- New Skills Module: Community Impact Project (me, 5 CP).

Students who study abroad during the fifth semester and are not substituting the mandatory Argumentation, Data Visualization and Communication module, are required to take this module during their sixth semester. Students who remain on campus are free to take the Argumentation, Data Visualization and Communication module in person in either the fifth or sixth.

2.3.3 German Language and Humanities Modules

German language abilities foster students' intercultural awareness and enhance their employability in their host country. They are also beneficial for securing mandatory internships (between the 2nd and 3rd year) in German companies and academic institutions. Constructor University supports its students in acquiring basic as well as advanced German skills in the first year of the Constructor Track. Non-native speakers of German are encouraged to take 2 German modules (2.5 CP each) but are not obliged to do so. Native speakers and other students not taking advantage of this offering take alternative modules in Humanities in each of the first two semesters:

- Humanities Module: Introduction to Philosophical Ethics (me, 2.5 CP)
- Humanities Module: Introduction to the Philosophy of Science (me, 2.5 CP)
- Humanities Module: Introduction to Visual Culture (me, 2.5 CP)

3 Robotics and Intelligent Systems as a Minor

3.1 Qualification Aims

Students obtaining a minor in Robotics and Intelligent Systems learn the basic principles of intelligent systems, including elements of both hardware and software. They obtain an understanding of how current robotics systems are designed and function. Upon completion of the minor, they will have obtained sufficient knowledge about robotics and intelligent systems concepts such that they can effectively work together with professional roboticists and experts in intelligent systems. Students obtaining a minor in Robotics and Intelligent Systems can help to drive and advise on the automation processes, which are at the forefront of industrial interest currently and are expected to remain so for the foreseeable future.

3.1.1 Intended Learning Outcomes

With a minor in Robotics and Intelligent Systems, students will be able to

- 1. develop solutions to problems in the automation, robotics, and intelligent systems domains in close collaboration with professionals;
- 2. design and develop software of moderate complexity for robotics and intelligent systems;
- 3. design and develop basic algorithms and techniques for pattern-recognition, classification, and decision-making under uncertainty.

3.2 Module Requirements

A minor in Robotics and Intelligent Systems requires 30 CP. The default option to obtain a minor in Robotics and Intelligent Systems is marked in the Study and Examination Plan. It includes the following mandatory CHOICE and CORE modules:

- CHOICE Module: Mathematical and Physical Foundations of Robotics I (m, 7.5 CP)
- CHOICE Module: Mathematical and Physical Foundations of Robotics II (m, 7.5 CP)
- CORE Module: Robotics (m, 5 CP)
- CORE Module: Artificial Intelligence (m, 5 CP)
- CORE Module: RIS Lab (m, 5 CP)

Upon consultation with the Academic Advisor and the RIS Study Program Chair, individual CORE modules from the default minor can be replaced by other advanced modules (CORE or Specialization) from the RIS major.

3.3 Degree

After successful completion, the minor in Robotics and Intelligent Systems will be listed on the final transcript under PROGRAM OF STUDY and BA/BSc – [name of the major] as "(Minor: Robotics and Intelligent Systems)."

4 Robotics and Intelligent Systems Undergraduate Program Regulations

4.1 Scope of these Regulations

The regulations in this handbook are valid for all students who entered the Robotics and Intelligent Systems undergraduate program at Constructor University in Fall 2024. In case of a conflict between the regulations in this handbook and the general Policies for Bachelor Studies, the latter shall applies (https://constructor.university/student-life/student-services/university-policies).

In exceptional cases, certain necessary deviations from the regulations of this study handbook might occur during the course of study (e.g., change of the semester sequence, assessment type, or the teaching mode of courses).

In general, Constructor University reserves therefore the right to change or modify the regulations of the program handbook according to relevant policies and processes also after its publication at any time and in its sole discretion.

4.2 Degree

Upon successful completion of the study program, students are awarded a Bachelor of Science degree in Robotics and Intelligent Systems.

4.3 Graduation Requirements

In order to graduate, students need to obtain 180 CP. In addition, the following graduation requirements apply:

Students need to complete all mandatory components of the program as indicated in the Study and Examination Plan in Chapter 6 of this handbook.

Schematic Study Plan for Robotics and Intelligent Systems

Figure 2 shows schematically the sequence and types of modules required for the study program. A more detailed description, including the assessment types, is given in the Study and Examination Plans in the following section.

C>ONSTRUCTOR

C>ONSTRUCTOR UNIVERSITY

Robotics and Intelligent Systems (180 CP)

| | | | CHOICE | / CORE / | CAREER | | 3 x 45 = : | 135 CP | CONST | RUCTO | R Track 45 CP |
|-----------------|---|------------------------------------|--|------------------------------|-----------------------------------|---|--|----------------------|--|----------------------------|--|
| 3 rd | | Bachelor The (research c | | ar | m, 15 CP | | Internship / Sta | rt-Up | Argumentation, Data Visualization | Account | ncy, Leadership & ability OR Community mpact Project me, 5 CP |
| Year CAREER | Specialization I me, 5 CP | | lization II Specialization III me, 5 CP me, 5 CP m, 15 CP | | and Communication** m, 5 CP | | odel and Matrices OR ex Problem Solving me, 5 CP | | | | |
| 2 nd | Artificial Intelligence m, 5 CP | RIS Lab | Autor | mation me, 5 CP | Machine | L earning m, 5 CP | RIS Proje e r | ct n, 5 CP | Numerical Methods OR Discrete Mathematics me, 5 CP | | Causation / Correlation** m, 2.5 CP |
| Year CORE | Robotics m, 5 CP | me, 5 CP | Embedde | Embedded Systems me, 5 CP | | Systems me, 5 CP Computer Vision me, 5 CP | | | Probability and Random Processes m, 5 CP | | Logic** m, 2.5 CP |
| 1 st | Mathematical and I Foundations of Ro | Physical botics II m, 7.5 CP | Algorithm | s and Data S | Structures m, 7.5 CP | Digital S | ystems and Comp Architecture m, | outer 7.5 CP | Elements of Ca | l culus ne, 5 CP | German / Humanities me, 2.5 CP |
| Year CHOICE | Mathematical and I Foundations of Ro | | General E | lectrical Eng | ineering I m, 7.5 CP | Progra | mming in C and (m, | C++ 7.5 CP | Elements of Li Algebra n | near ne, 5 CP | German / Humanities me, 2.5 CP |
| | Minor Option in RI | S (30 CP) | C | CP: Credit Poi | | mandatory : mandatory | | • | ad Option in 5 th 22.5 CP) | **Differen perspec | t module tives available |

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Figure 2: Schematic Study Plan for RIS

Robotics and Intelligent Systems (RIS) BSc

| Matriculation | n Fall 2024 | | | | | | | | | | | | | | |
|----------------------|---|---------------------|-------------------------|----------------------|---------------------|------|----------|------------------------|--|------------------|---------------------|--------------------|---------------------|------|-----|
| | Program-Specific Modules | Туре | Assessment | Period | Status ¹ | Sem. | СР | | CONSTRUCTOR Track Modules (General Education) | Туре | Assessment | Period | Status ¹ | Sem. | СР |
| Year 1 - CHO | DICE | | | | | | 45 | | | | | | | | 15 |
| Take the manda | tory CHOICE modules listed below | | | | | | | | | | | | | | 15 |
| | | | | | | | 15 | | Unit: Methods | | | | | | 10 |
| | Module: Mathematical and Physical Foundations of Robotics I | | | | | | | | Module: Elements of Linear Algebra | | | | me | 1 | 5 |
| CH-221 CH-221-A | (default minor) Mathematical and Physical Foundations of Robotics I | Lecture | Written examination | Examination period | m | 1 | 7.5 | CTMS-MAT-24 CTMS-24 | Elements of Linear Algebra | Lecture | Written examination | Examination period | | | |
| CH-221-A CH-221-B | Mathematical and Physical Foundations of Robotics I - Lab | Lecture | written examination | Examination period | | | 2.5 | | Module: Elements of Calculus | Lecture | written examination | Examination period | me | 2 | 5 |
| 011 221 15 | Module: Mathematics and Physical Foundations of Robotics II | Luo | | | 1 | | 2.0 | CTMS-25 | Elements of Calculus | | | | inc | | 0 |
| CH-222 | (de fault minor) | | | | m | 2 | 7.5 | - | | Lecture | Written examination | Examination period | | | |
| CH-222-A | Mathematical and Physical Foundations of Robotics II | Lecture | Written examination | Examination period | | | 5 | | a strong mathematical background can also choose: | | | | | | |
| CH-222-B | Mathematical and Physical Foundations of Robotics II - Lab | Lab | | | | | 2.5 | | Module: Matrix Algebra & Advanced Calculus I | | | | me | 1 | 5 |
| СН-234 | Module: Digital Systems and Computer Architecture | | | 1 | m | 2 | 7.5 | CTMS-22 | Matrix Algebra & Advanced Calculus I | Lecture | Written examination | Examination period | | | |
| CH-234-A | Digital Systems and Computer Architecture | Lecture | Written examination | Examination period | | | 5 | | Module: Matrix Algebra & Advanced Calculus II | T. A | With the | E 1.4 11 | me | 2 | 5 |
| CH-234-B | Digital Systems and Computer Architecture Tutorial | Tutorial | | | | | 2.5 | CTMS-23 | Matrix Algebra & Advanced Calculus II | Lecture | Written examination | Examination period | | | |
| CH-210 | Module: General Electrical Engineering I | | | | m | 1 | 7.5 | | | | | | | | |
| CH-210-A | General Electrical Engineering I | Lecture | Written examination | Examination period | | | 5 | | Unit: German Language and Humanities (choose one module for each semen | nster) | | | | | 5 |
| CH-210-B | General Electrical Engineering Lab I | Lab | Laboratory report | During the semester | | | 2.5 | | anguage and open to Non-German speakers (on campus and online). ⁵ | | | | | | |
| CH-230 CH-230-A | Module: Programming in C and C++ Programming in C and C++ | Lecture | Written examination | Examination period | m | 1 | 7.5 5 | CTLA-xxx CTLA-xxx | Module: Language 1 Language 1 | Seminar | Various | Various | me | 1 | 2,5 |
| CH-230-A CH-230-B | Programming in C and C++ Tutorial | Tutorial | Program code | During the semester | | | 2.5 | CTLA-XXX | Module: Language 2 | Seminar | v ai ious | v arious | me | 2 | 2,5 |
| CH-231 | Module: Algorithms and Data Structures | T GIOT ET | 1 logram code | During the seriester | m | 2 | 7.5 | CTLA-XXX | Language 2 | Seminar | Various | Various | ш | | 2,0 |
| CH-231-A | Algorithms and Data Structures | Lecture | Written examination | Examination period | | | | CTHU-HUM-001 | Humanities Module: Introduction to Philosophical Ethics | | | | me | 2 | 2,5 |
| | | | | | | | | CTHU-001 | Introduction to Philosophical Ethics | Lecture (online) | Written examination | Examination period | | | - |
| | | | | | | | | | Humanities Module: Introduction to the Philosophy of Science | | | | me | 1 | 2,5 |
| | | | | | | | | CTHU-002 | Introduction to the Philosophy of Science | Lecture (online) | Written examination | Examination period | | | |
| | | | | | | | | | Humanities Module: Introduction to Visual Culture | | | | me | 2 | 2,5 |
| | | | | | | | _ | CTHU-003 | Introduction to Visual Culture | Lecture (online | Written examination | Examination period | | | |
| Year 2 - COR | | | | _ ? | | | 45 | | | | | | | | 15 |
| Take all CORE n | modules listed below or replace mandatory elective ("me") modules with th Unit: Robotics | ne default minor CO | TRE modules of Computer | Science." | | | 15 | | Unit: Methods | | | | | | 10 |
| | Module: Robotics (default minor) | | | | | - | | CTMS-MAT-12 | | | | | | | |
| CO-540 CO-540-A | Robotics | Lecture | Written examination | B 1.4 11 | m | 3 | 5 | CTMS-MAT-12 CTMS-12 | Module: Probability and Random Processes Probability and Random Processes | Lecture | Written examination | Examination period | m | 3 | 5 |
| CO-540-A | Module: Machine Learning | Lecture | written examination | Examination period | m | 4 | 5 | Choose one of the f | | Lecture | written examination | Examination period | | | |
| CO-541-A | Machine Learning | Lecture | Written examination | Examination period | | 4 | 3 | | Module: Numerical Methods | | | | me | 4 | 5 |
| CO-542 | Module: Robotics and Intelligent Systems Lab (default minor) | Licetare | Winter externation | Estamination period | me/m ⁴ | 3-4 | 5 | CTMS-13 | Numerical Methods | Lecture | Written examination | Examination period | inc | | |
| CO-542-A | RIS lab I | Lecture/Lab | Laboratory Report | During the semester | | 3 | 2.5 | CO-501-A | Module: Discrete Mathematics | | | | me | 4 | 5 |
| CO-542-B | RIS Lab II | Lecture/Lab | Laboratory Report | | | 4 | 2.5 | CO-501-A | Discrete Mathematics | Lecture | Written examination | Examination period | | | |
| | Unit: Automation and Control | | | | | | 15 | | Unit: New Skills | | | | | | 5 |
| CO-543 | Module: Automation | | | | me | 4 | 5 | Choose one of the t | | | | | | | |
| CO-543-A | Automation | Lecture | Written examination | Examination period | | | | CTNS-NSK-01 | Module: Logic (perspective I) | | | | me | 3 | 2,5 |
| CO-544 CO-544-A | Module: Embedded Systems Embedded Systems | Lecture/Lab | D i th | Did (| me | 3 | 5 | CTNS-01 CTNS-NSK-02 | Logic (perspective I) | Lecture (online) | Written Examination | Examination period | | | 2.5 |
| CO-544-A CO-545 | Module: Control Systems | Lecture/Lab | Project Assessment | During the semester | me | 3 | 5 | CTNS-NSK-02 CTNS-02 | Module: Logic (perspective II) Logic (perspective II) | Laatura (anlina) | Written Examination | Examination period | me | | 2,5 |
| CO-545-A | Control Systems | Lecture | Written examination | Examination period | inc | 5 | 5 | Choose one of the t | | Eccture (online) | WIRten Examination | Examination period | | | |
| | Unit: Intelligent Systems | | | | | | 15 | CTNS-NSK-03 | Module: Causation and Correlation (perspective I) | | | | me | 4 | 2,5 |
| CO-546 | Module: Computer Vision | | | | me | 3 | 5 | CTNS-03 | Causation and Correlation (perspective I) | Lecture (online) | Written Examination | Examination period | | | |
| CO-546-A | Computer Vision | Lecture/Lab | Written examination | Examination period | | | | CTNS-NSK-04 | Module: Causation and Correlation (perspective II) | | | | me | 4 | 2,5 |
| CO-547 | Module: Artificial Intelligence (default minor) | | | | m | 4 | 5 | CTNS-04 | Causation and Correlation (perspective II) | Lecture (online) | Written Examination | Examination period | | | |
| CO-547-A | Artificial Intelligence | Lecture | Written examination | Examination period | | | | | | | | | | | |
| CO-548 | Module: RIS project | | 1 | | m | 4 | 5 | | | | | | | | |
| CO-548-A | RIS Project | Project/Lab | Project Report / | During the semester | | | | | | | | | | | |
| | | | Presentation | 5 | | | | | | | | | | | |

| Year 3 - CARI | EER | | | | | | 45 | | | | | 15 |
|--------------------|---|-------------|--|-------------------------------------|----|-----|----|-------------------|--|----|-----|-----|
| CA-INT-900 | Module: Summer Internship | | | | m | 4/5 | 15 | | Unit: New Skills | | | 10 |
| CA-INT-900-0 | Summer Internship | Internship | Report/Business Plan and Presentation | During the 5 th Semester | | | | Choose one of the | wo modules | | | |
| CA-RIS-800 | Module: Thesis / Seminar RIS | | | | m | 6 | 15 | CTNS-NSK-05 | Module: Linear Model and Matrices | me | 5 | 5 |
| CA-RIS-800-T | Thesis RIS | Thesis | Thesis and Presentation | 15th of May | | | 12 | CTNS-05 | Linear Model and Matrices Seminar (online) Written examination period | | | |
| CA-RIS-800-S | Thesis Seminar RIS | Seminar | | During the semester | | | 3 | CTNS-NSK-06 | Module: Complex Problem Solving | me | 5 | 5 |
| | Unit: Specialization RIS | | | | m | 5/6 | 15 | CTNS-06 | Complex Problem Solving Lecture (online) Written examination Examination period | | | |
| Take a total of 15 | CP of specialization modules | | | | | | | Choose one of the | wo modules | | | |
| CA-S-RIS-801 | Marine Robotics | Lecture/Lab | Oral examination | Examination period | me | 6 | 5 | CTNS-NSK-07 | Module: Argumentation, Data Visualization and Communication (perspective I) | me | 5/6 | 5 |
| CS-S-RIS-802 | Human Computer Interaction | Lecture | Project Assessment | Examination period | me | 5 | 5 | CTNS-07 | Argumentation, Data Visualization and Communication (perspective I) Lecture (online) Written examination Examination period | | 5 | |
| CS-S-RIS-803 | Optimization | Lecture | Written examination | Examination period | me | 6 | 5 | CTNS-NSK-08 | Module: Argumentation, Data Visualization and Communication (perspective II) | me | 5/6 | 5 |
| CA-S-xxx | Specialization elective (from CS, ECE, MMDA, IEM, DE study programs)^3 $$ | Various | Various | Various | me | 5/6 | 5 | CTNS-08 | Argumentation, Data Visualization and Communication (perspective II) Lecture (online) Written examination Examination period | | 6 | |
| | | | | | | | | Choose one of the | wo modules | | | |
| | | | | | | | | CTNS-NSK-09 | Module : Agency, Leadership, and Accountability | me | 6 | 5 |
| | | | | | | | | CTNS-09 | Agency, Leadership, and Accountability Lecture (online) Written examination period | | | |
| | | | | | | | | CTNS-CIP-10 | Module: Community Impact Project | me | 6 | 5 |
| | | | | | | | | CTNS-10 | Community Impact Project Project During the Semenstr | r | | |
| Total CP | | | | | | | | | | | | 180 |

Status (m = mandatory, me = mandatory elective)
 Status (m = mandatory, and a status (m = mandatory) elective)
 For a full listing of all CHOICE / CORE / CAREER / CONSTRUCTOR Track modules please consult the CampusNet online catalogue and /or the study program handbooks.

³ For details please see the program handbook

⁴ This module is me for students majoring in RIS, but m for students minoring in RIS

⁵ German native speakers will have alternatives to the language courses (in the field of Humanities).

Figure 3: Study and Examination Plan

7 Robotics and Intelligent Systems Modules

7.1 Mathematical and Physical Foundations of Robotics I

| Module Name | | Module Code | Level (type) | СР |
|---------------------------------|---|------------------------------|----------------------|------------------|
| Mathematical and Ph | ysical Foundations of Robotics I | CH-221 | Year 1 | 7.5 |
| | | | (CHOICE) | |
| Module Components | | | | |
| Number | Name | | Туре | СР |
| CH-221-A | Mathematical and Physical Foun | dations of Robotics I | Lecture | 5 |
| CH-221-B | Mathematical and Physical Foun | dations of Robotics I - Lab | Lab | 2.5 |
| Module Coordinator | Program Affiliation | | Mandatory State | ıs |
| Prof. Dr. Francesco Maurelli | Robotics and Intelligent Syst | tems (RIS) | Mandatory for RIS | RIS and mino |
| Entry Requirements | | Frequency | Forms of Lea | rning and |
| Pre-requisites | Co-requisites Knowledge, Ak | pilities, or Annually (Fall) | Teaching | |
| The requisites | Skills | , undury (runy | Lecture (3) | 35 hours) |
| 🗵 None | 🗵 None | | • Lab (17.5 | - |
| | | | Private st | udy (115 |
| | | | hours) | |
| | | | | paration (20 |
| | | | hours) | |
| | | Duration | Workload | |
| | | 1 semester | 187.5 hours | |
| Recommendations for P | reparation | | | |
| Review basic mathem | atical concents | | | |
| | | | | |
| Content and Educationa | i Aims | | | |
| Th : | an en tratal trata de atom de actor | | | - f t h t |
| | its an initial introduction to robotics to simple robotics scenarios. It wil | | - | |
| | e will then cover kinematics of a p | | • | |
| - | | | | |

systems. The module will then cover kinematics of a point and of a rigid body. Students will then learn the basics of trajectory planning and robotic systems. The lab is designed to guide students through practical hands-on work with various components of intelligent systems. It will focus on the interfacing of a microcontroller with commonly used sensors and actuators.

Intended Learning Outcomes

By the end of this module, successful students will be able to

- 1. compute 3D transformations;
- 2. understand and apply quaternion operations;
- 3. understand and apply kinematics laws of a point;
- 4. understand and apply kinematics laws of a rigid body;
- 5. understand and apply trajectory planning techniques;
- 6. program the open-source electronic prototyping platform Arduino;
- 7. interface Arduino to several different sensors and actuators.

Indicative Literature

- R. V. Roy, Advanced Engineering Dynamics. R. V. Roy, 2015.
- R. N. Jazar, Theory of Applied Robotics. Springer, 2010.

Usability and Relationship to other Modules

• This module is the foundation of the CORE modules in the following years.

Examination Type: Module Examination

Assessment Type: Written examination

Scope: All intended learning outcomes of the module

Module achievement: Lab report

Completion: To pass this module, the examination has to be passed with at least 45%.

Duration: 120 min Weight: 100%

7.2 Mathematical and Physical Foundations of Robotics II

| Module Name | | Module Code | Level (type) | СР |
|------------------------|--|--------------------------|--|---------------|
| Mathematical and Pl | nysical Foundations of Robotics II | CH-222 | Year 1 (CHOICE) | 7.5 |
| Module Components | | | () | |
| Number | Name | | Туре | СР |
| CH-222-A | Mathematical and Physical Foundations | s of Robotics II | Lecture | 5 |
| СН-222-В | Mathematical and Physical Foundations | s of Robotics II - Lab | Lab | 2.5 |
| Module Coordinator | Program Affiliation | | Mandatory Statu | s |
| Dr. Mathias Bode | Robotics and Intelligent Systems (R | IS) | Mandatory for I RIS | RIS and minor |
| Entry Requirements | | Frequency | Forms of Lear | ning and |
| Due un su inite e | | | Teaching | |
| Pre-requisites | Co-requisites Knowledge, Abilities, Skills | or Annually (Spring) | Lecture (3) | 5 hours) |
| 🗵 None | ⊠ None | | Lab (17.5 | |
| | | | Private stu | idy (115 |
| | | | hours) | |
| | | | Exam prep hours) | aration (20 |
| | | Duration | Workload | |
| | | 1 semester | 187.5 hours | |
| Recommendations for P | reparation | | | |
| Review basic mathem | atical concepts. | | | |
| Content and Educationa | • | | | |
| | | | | |
| | introduction to modeling, and design of lir | | | |
| | mportant introductory aspects of control s (odes). Students learn how to analyze ar | | | |
| | epts covered include time and frequency r | | - | |
| | o design feedback control systems, in par | | | |
| course. Practical exp | perience will be gained based on numer | ous examples, analysis | and design tasks | supported by |
| numerical methods. | The lab is designed to guide students through | ugh practical hands-on v | work with various | components of |

intelligent systems. It will focus on the interfacing of a microcontroller with commonly used sensors and actuators.

Intended Learning Outcomes

By the end of this module, successful students will be able to

- 1. Model simple common mechanical and electrical systems which are part of robots
- 2. Solve linear systems and tune their behavior in simulation and analytically
- 3. Understand and be able to apply the uni-lateral Laplace transforms and its inverse
- 4. Understand basic approaches and methods related to feedback control systems
- 5. Create an electromechanical model of a brushed DC motor in Simulink and study its properties;
- 6. Design and tune PID controllers for motor-speed control and for servo control;
- 7. Present and justify their work appropriately in accordance with scientific standards.

Indicative Literature

Norman S. Nise (2012), Control Systems Engineering

Usability and Relationship to other Modules

• This module is the foundation of the CORE modules in the following years.

Examination Type: Module Examination

Assessment Type: Written examination

Scope: All intended learning outcomes of the module

Module achievement: Lab report

Completion: To pass this module, the examination has to be passed with at least 45%.

Duration: 120 min Weight: 100%

7.3 Programming in C and C++

| Module Name | | | Module Code | Level (type) | СР | |
|-----------------------|---------------------|--|------------------|---|--------|--|
| Programming in C a | nd C++ | | CH-230 | Year 1 7.5 (CHOICE) | | |
| Module Components | 5 | | | | | |
| Number | Name | | | Туре | СР | |
| CH-230-A | Programming in C | and C++ | | Lecture | 5 | |
| СН-230-В | Programming in C | and C++ - Tutorial | | Tutorial | 2,5 | |
| Module Coordinator | Program Affiliation | | Mandatory Status | | | |
| Dr. Kinga Lipskoch | Computer Sc | Mandatory for CS, SDT, R ECE, minor CS, minor RIS a minor Software Developme | | | | |
| Entry Requirements | | | Frequency | Forms of Learni Teaching | ng and | |
| Pre-requisites | Co-requisites | Knowledge, Abilities, or Skills | Annually (Fall) | Lecture atter (35 hours) Tutorial atter (17.5 hours) | | |
| ⊠ None | ⊠ None | | | Independent (115 hours) Exam prepar hours) | · | |
| | | | Duration | Workload | | |
| | | | 1 semester | 187.5 hours | | |

Recommendations for Preparation

It is recommended that students install a suitable programming environment on their notebooks. It is recommended to install a Linux system such as Ubuntu, which comes with open-source compilers such as gcc and g++ and editors such as vim or emacs. Alternatively, the open-source Code: Blocks integrated development environment can be installed to solve programming problems.

Content and Educational Aims

This course offers an introduction to programming using the programming languages C and C++. After a short overview of the program development cycle (editing, preprocessing, compiling, linking, executing), the module presents the basics of C programming. Fundamental imperative programming concepts such as variables, loops, and function calls are introduced in a hands-on manner. Afterwards, basic data structures such as multidimensional arrays, structures, and pointers are introduced and dynamically allocated multidimensional arrays and linked lists and trees are used for solving simple practical problems. The relationships between pointers and arrays, pointers and structures, and pointers are described, and they are illustrated using examples that also introduce recursive functions, file handling, and dynamic memory allocation.

The module then introduces basic concepts of object-oriented programming languages using the programming language C++ in a hands-on manner. Concepts such as classes and objects, data abstractions, and information hiding are introduced. C++ mechanisms for defining and using objects, methods, and operators are introduced and the relevance of constructors, copy constructors, and destructors for dynamically created objects is explained. Finally, concepts such as inheritance, polymorphism, virtual functions, and overloading are introduced. The learned concepts are applied by solving programming problems.

Intended Learning Outcomes

By the end of this module, students will be able to

- 1. explain basic concepts of imperative programming languages such as variables, assignments, loops, and function calls;
- 2. write, test, and debug programs in the procedural programming language C using basic C library functions;
- 3. demonstrate how to use pointers to create dynamically allocated data structures such as linked lists;
- 4. explain the relationship between pointers and arrays;
- 5. illustrate basic object-oriented programming concepts such as objects, classes, information hiding, and inheritance;
- 6. give original examples of function and operator overloading and polymorphism;
- 7. write, test, and debug programs in the object-oriented programming language C++.

Indicative Literature

Brian Kernighan, Dennis Ritchie: The C Programming Language, 2nd edition, Prentice Hall Professional Technical Reference, 1988.

Steve Oualline: Practical C Programming, 3rd edition, O'Reilly Media, 1997. Bruce

Eckel: Thinking in C++: Introduction to Standard C++, Prentice Hall, 2000.

Bruce Eckel, Chuck Allison: Thinking in C++: Practical Programming, Prentice Hall, 2004. Bjarne

Stroustrup: The C++ Programming Language, 4th edition, Addison Wesley, 2013.

Michael Dawson: Beginning C++ Through Game Programming, 4th edition, Delmar Learning, 2014.

Usability and Relationship to other Modules

• This module introduces the programming languages C and C++ and several other modules build on this foundation. Certain features of C++ such as templates and generic data structures and an overview of the standard template library will be covered in the Algorithms and Data Structures module.

Examination Type: Module Component Examinations Component

1: Lecture

Assessment types: Written examination

Weight: 67%

Scope: All theoretical intended learning outcomes of the module

Component 2: Tutorial

Assessment: Program Code

Scope: All practical intended learning outcomes of the module

Completion: To pass this module, the examination of each module component has to be passed with at least 45%.

Duration: 120 min

Weight: 33%

7.4 General Electrical Engineering I

| Module Name | | | | Module Code | Level (type) | СР |
|------------------|-------------------|--------------------------|-----------------|-------------|----------------|------------|
| General Electric | cal Engineering I | | | CH-210 | Year 1 | 7.5 |
| | | | | | (CHOICE) | |
| Module Compon | ients | | | | | |
| Number | | Name | | | Туре | СР |
| CH-210-A | General Electri | cal Engineering I | | | Lecture | 5.0 |
| СН-210-В | General Electri | cal Engineering Lab I | | | Lab | 2.5 |
| Module | Program Affiliati | on | | | Mandatory Stat | us |
| Coordinator | - | | | | | |
| | Electrical | and Computer Engineering | (ECE) | | Mandatory | for ECE, |
| Prof. Dr. | | | | | minor ECE and | d RIS |
| Giuseppe | | | | | | |
| Abreu | | | | | | |
| Entry | | | Frequency | | Forms of Lear | ning and |
| Requirements | | | | | Teaching | |
| | | | Annually (Fall) | | | |
| Pre-requisites | Co-requisites | Knowledge, Abilities, or | | | Lecture (| 35 hours) |
| _ | _ | Skills | | | • Lab (25.5 | • |
| 🖾 None | 🛛 None | Basic | | | | tudy (127) |
| | | mathematics, | Duration | | Workload | |
| | | including notions | | | | |
| | | of vectors, | 1 semester | | 187.5 hours | |
| | | matrices | | | | |
| | | functions, and | | | | |
| | | complex | | | | |
| | | numbers | | | | |

Recommendations for Preparation

It is highly recommended that students familiarize themselves with the contents of the appendices of a typical introductory textbook on Electrical Engineering (e.g. "Fundamentals of Electric Circuits", by Alexander and Sadiku and "Basic Engineering Circuit Analysis", by Irwin and Nelms), including Complex Numbers and basic Linear Algebra (in particular the solution of simultaneous linear equations). In addition, it is recommended that students acquire Calculus basics (differentiation and integration of simple functions).

Content and Educational Aims

The module, consisting of a lecture, supported by corresponding lab experiments, comprises the classical introduction to Electrical and Computer Engineering (ECE), starting from the basics of the electric phenomenon, its fundamental elements (charge, current, potential, energy, etc.), its interaction with materials (conductivity, capacitance, inductance, etc.) and its manipulation by man-made structures (electronic components and circuits). The module then develops into a wide set of general principles, laws and analytical tools to understand electric circuits and electric systems in general. The module also offers a solid foundation on which specialization areas in EE (e.g. Communications, Control, etc.) are built. The emphasis is the analysis of circuits in DC steady state and transient modes. Classic material include (but are not limited to): Kirchhoff's Laws, Volta's Law (capacitance), Faraday's Law (inductance), Thevenin and Norton's Theorem, Tellegen's Theorem, deltywye transformation, source transformations, basics of non-linear electronic components (diodes and transistors), OpAmp circuits, State-space Method, Laplace Transform applied to the analysis of higher-order circuits, Laplace impedances and transfer functions. In the lab portion of the module, users will familiarize themselves with electronic components (resistors, capacitors, inductors, diodes, OpAmps, transistors, etc.) and circuits, and learn how to utilize typical

lab equipment (such as breadboards, digital multimeters, voltage and current sources and function generators) required for the assembly and analysis of electric circuits.

Intended Learning Outcomes

By the end of this module, students should be able to

- 1. describe the fundamental physical principles of electric quantities (charge, current, potential, energy and its conservation, etc.);
- 2. explain how the aforementioned quantities relate to each other and interact with matter, including corresponding mathematical models;
- 3. explain how the aforementioned models can be utilized to manipulate electric quantities and phenomenon in the form of electric and electronic circuits or machines that perform several tasks and functions according to intended designs;
- 4. employ various theoretical and practical tools to analyze electric circuits including resistive circuits, reactive circuits, and OpAmp circuits, both in DC steady-state and transient modes.

In addition to the aforementioned outcomes, fundamental to a career in ECE, students will also have acquired:

- 5. analytical and mathematical modeling skills useful to study other physical systems (e.g. in other areas of Engineering, Physics, Robotics, etc.)
- 6. the ability to work in a lab environment and operate lab equipment, as required in other professions (e.g. Physics, Biology, Chemistry etc.).

Usability and Relationship to other Modules

Indicative Literature

Charles K. Alexander and Matthew N. O. Sadiku, Fundamentals of Electric Circuits, 3rd ed., McGraw-Hill, 2008 (Primary Textbook).

J. David Irwin and R. Mark Nelms, Basic Engineering Circuit Analysis, 10th ed., Wiley, 2010 (Recommended Reference).

James Nilsson and Susan Riedel, Electric Circuits, 10th ed., Pearson, 2015 (Extra Reference).

A. Agarwal and J. Lang, Foundations of Analog and Digital Electronic Circuits, 1st ed., Elsevier, 2005 (Advanced Reference for selected topics).

Examination Type: Module Component Examinations

Module Component 1: Lecture Assessment Type: Written examination

Scope: Intended learning outcomes of the lecture (1-3,5)

Module Component 2: Lab

Assessment Type: Laboratory reports

Scope: Intended learning outcomes of the lab (3-4, 6).

Duration: 120 min Weight: 67%

Length: 5-10 pages per experiment session Weight: 33%

Completion: To pass this module, the examination of each module component has to be passed with at least 45%.

7.5 Algorithms and Data Structures

| Algorithms and Dat | a Structures | | Module Code CH-231 | Level (type) Year 1 (CHOICE) | СР 7.5 |
|----------------------------------|---------------------|------------------------------------|-----------------------|---|------------------|
| Module Component | s | | | | |
| Number | Name | | | Туре | СР |
| CH-231-A | Algorithms and D | Data Structures | | Lecture | 7.5 |
| Module Coordinator | Program Affiliation | | | Mandatory Status | |
| Dr. Kinga Lipskoch | • | Computer Science (CS) | | Mandatory for CS minor in CS | , RIS, and |
| Entry Requirements | | | Frequency | Forms of Learning a | nd Teaching |
| Pre-requisites | Co-requisites | Knowledge, Abilities, or Skills | Annually (Spring) | • Class attenda hours) | |
| ⊠ Programming in C and C++ | ⊠ None | | | Independent hours) Exam prepara hours) | , , |
| | | | Duration | Workload | |
| | | | 1 semester | 187.5 hours | |

Students should refresh their knowledge of the C and C++ programming language and be able to solve simple programming problems in C and C++. Students are expected to have a working programming environment.

Content and Educational Aims

Algorithms and data structures are the core of computer science. An algorithm is an effective description for calculations using a finite list of instructions that can be executed by a computer. A data structure is a concept for organizing data in a computer such that data can be used efficiently. This introductory module allows students to learn about fundamenta algorithms for solving problems efficiently. It introduces basic algorithmic concepts; fundamental data structures for efficiently storing, accessing, and modifying data; and techniques that can be used for the analysis of algorithms and data structures with respect to their computational and memory complexities. The presented concepts and techniques form the basis of almost all computer programs.

Intended Learning Outcomes

By the end of this module, students will be able to

- 1. explain asymptotic (time and memory) complexities and respective notations;
- 2. able to prove asymptotic complexities of algorithms;
- 3. illustrate basic data structures such as arrays, lists, queues, stacks, trees, and hash tables;
- 4. describe algorithmic design concepts and apply them to new problems;
- 5. explain basic algorithms (sorting, searching, graph algorithms, computational geometry) and their complexities;
- 6. summarize and apply C++ templates and generic data structures provided by the standard C++ template library.

Indicative Literature

Thomas H. Cormen, Charles E. Leiserson, Ronald L. Rivest, and Clifford Stein: Introduction to Algorithms, 3rd edition, MIT Press, 2009.

Donald E. Knuth: The Art of Computer Programming: Fundamental Algorithms, volume 1, 3rd edition, Addison Wesley Longman Publishing, 1997.

Usability and Relationship to other Modules

• Familiarity with basic algorithms and data structures is fundamental for almost all advanced modules in computer science. This module additionally introduces advanced concepts of the C++ programming language that are needed ir advanced programming-oriented modules in the 2nd and 3rd years of the CS and RIS programs.

Examination Type: Module Examination

Assessment Type: Written examination

Scope: All intended learning outcomes of the module

Completion: To pass this module, the examination has to be passed with at least 45%

Duration: 120 min Weight: 100%

7.6 Digital Systems and Computer Architecture

| Module Name Digital Systems and Computer Architecture | | Module Code CH-234 | Level (type) Year 1 (CHOICE) | СР 7.5 |
|--|--|------------------------------|---|------------------|
| Module Compone | nts | l | | |
| Number | Name | | Туре | СР |
| CH-234-A | Digital Systems and Computer Architecture | | Lecture | 5.0 |
| CH-234-B | Digital Systems and Computer Architecture Tutorial | | Tutorial 2.5 | |
| Module Coordinator Prof. Dr. Jürgen Schöwälder | Program Affiliation Computer Science (CS) | | Mandatory Status Mandatory for CS, RIS and ECE Mandatory elective for SDT | |
| Entry Requirements | | Frequency Annually | Forms of Learning Lecture attended | |
| Pre-requisites | Co-requisites Knowledge, Abilities, or Skills | (Spring) | (35 hours)Tutorial attendance (17.5 hours) | |
| ⊠ None | ⊠ None | | Independent study (115 hours) Exam preparation (20 hours) | |
| | | Duration | Workload | |
| | | 1 semester | 187.5 hours | |
| Recommendations | for Preparation | | | |
| Content and Educa | | | | |

The module introduces the essential hardware components of a digital computer system. Students will learn how useful digital circuits to add numbers or to store data can be constructed out of basic logic gates. Using these building blocks, the module will introduce how a simple processor can be constructed and how it interacts with memory systems and other components of a computer system. Students will practice the basics of assembler programming to understand program execution at the hardware level.

Intended Learning Outcomes

By the end of this module, students will be able to

- 1. Understand the architecture of a digital computer;
- 2. explain the representation of numbers (integers and floats);
- 3. summarize basic laws of Boolean algebra;
- 4. describe basic logic gates and which Boolean functions they implement;
- 5. construct and analyze basic combinational digital circuits (e.g., adder, comparator, multiplexer);
- 6. design and analyze basic sequential digital circuits (e.g., latches, flip-flops);
- 7. outline the basic structure of the von Neumann computer architecture;
- 8. explain the execution of machine instructions on a von Neumann computer;
- 9. develop simple programs in an assembler language such as the RISC-V;
- 10. demonstrate how function calls are executed and the role of the stack;
- 11. understand microarchitectural concepts and the importance of the memory hierarchy;
- 12. explain the purpose and principles of operation of the components of a computer system.

Indicative Literature

- John L Hennessy, David A. Patterson: Computer Architecture: A Quantitative Approach, 6th edition, Morgan Kaufmann, 2017
- Sarah Harris, David Harris: Digital Design and Computer Architecture: RISC-V Edition, Morgan Kaufmann, 2021

Usability and Relationship to other Modules

This module introduces students to the digital hardware components of a computer system. Students attain an understanding of program execution at the hardware level. Other modules requiring an understanding of program execution at the hardware level may require this module as a prerequisite.

Duration: 120 min Weight: 100%

Examination Type: Module Examination

Assessment Type: Written examination

Scope: All intended learning outcomes of the module

Module achievement: 50% of ten weekly assignments correctly solved. Two additional assignments are offered during the semester and another assignment is offered in August to makeup missing points.

Completion: To pass this module, the examination has to be passed with at least 45%.

7.7 Robotics

| Module Name | | Module Code | Level (type) | СР |
|--|--|---------------------------------|--|----|
| Robotics | | CO-540 | Year 2 (CORE) | 5 |
| Module Components | S | | | |
| Number | Name | | Туре | СР |
| CO-540-A | Robotics | | Lecture | 5 |
| Module Coordinator | Program Affiliation | | Mandatory Status | |
| Prof. Dr. Andreas Birk | Robotics and Intelligent Systems (RIS) | | Mandatory for RIS and minor RIS Mandatory elective for CS | |
| Entry Requirements Pre-requisites ☑ Programming in C/C++ ☑ Mathematical and Physical Foundations of Robotics I | Co-requisites Knowledge, Abilities, or Skills ⊠ None | Frequency Annually (Fall) | Forms of Learning and Teaching Class attendance (35 hours) Private study (70 hours) Exam preparation (20 hours) | |
| Robotics I | | Duration | Workload | |
| | | 1 semester | 125 hours | |
| Recommendations for | r Preparation | | | |
| Revise content of th | ne pre-requisite modules. | | | |
| Content and Educatio | nal Aims | | | |
| Content and Educatio Robotics is an area | | | | |

provide an understanding of the formal foundations of this area as well as its technological state of the art and future directions. The course accordingly gives an introduction to the core algorithmic, mathematical, and engineering concepts and methods of robotics. This includes concepts and methods that are used for well- established tools of factory automation, especially in the form of robot-arms, as well as increasingly relevant intelligent mobile systems such as autonomous cars or autonomous transport systems.

Intended Learning Outcomes

By the end of this module, students should be able to

- 1. outline and explain the history, general developments, and application areas of robotics;
- 2. apply the concepts and methods to describe space and motions therein including homogeneous coordinates and transforms as well as quaternions;
- 3. use the spatial concepts and methods for the forward kinematics (FK) of robot-arms;
- 4. explain basic concepts of simple actuators, including electrical motors and gear systems;
- 5. apply concepts and methods to derive the inverse kinematics of robot-arms and related systems such as legs in analytical and numerical forms;
- 6. apply concepts and methods of wheeled locomotion including FK and IK of the differential and of the omnidirectional drive;
- 7. use basic concepts and methods of dynamics;
- 8. Explain and use core concepts and methods of global localization, e.g., multilateration and multidimensional scaling;
- 9. use the basic concepts and methods of error propagation estimation in the context of relative localization with dead-reckoning;
- 10. outline and compare the basic concepts and methods of mapping.

Indicative Literature

J. J. Craig, Introduction to robotics - Mechanics and control, Prentice Hall, 2005.

- G. Dudek and M. Jenkin, Computational Principles of Mobile Robotics, Cambridge University Press, 2000.
- R. Siegwart and I. R. Nourbakhsh, Introduction to Autonomous Mobile Robots, The MIT Press, 2004.
- S. Thrun, W. Burgard, and D. Fox, Probabilistic Robotics, MIT Press, 2005.

H. Choset, K. M. Lynch, S. Hutchinson, G. Kantor, W. Burgard, L. E. Kavraki, and S. Thrun, Principles of Robot Motion, MIT Press, 2005.

Usability and Relationship to other Modules

- This module serves as a third Year Specialization module for CS major students.
- This module gives an introduction to Robotics, which is a core discipline of Robotics and Intelligent System (RIS) and an important area of possible future employment.

Examination Type: Module Examination

Assessment Type: Written examination

Duration: 120 min Weight: 100%

Scope: All intended learning outcomes of the module

7.8 Machine Learning

| Module Name | | | Module Code | Level (type) | СР |
|--|--|--|--|--|---|
| Machine Learning | | | CO-541 | Year 2 (CORE) | 5 |
| Module Component | S | | | | |
| Number | Name | | | Туре | СР |
| CO-541-A | Machine Learning | | | Lecture | 5 |
| Module Coordinator | Program Affiliation | | | Mandatory Status | |
| Prof. Dr. Francesco Maurelli | Robotics and | Intelligent Systems (RIS) | | Mandatory for PHDS, SDT and Software Develop Mandatory electi | d minor i oment |
| Entry Requirements | | | Frequency | Forms of Learni | ng and |
| | | | | Teaching | |
| | | | Annually | | |
| Dro roquisitos | Co requisitos | Knowledge Abilities or | (Spring) | Class attend hours) | ance (35 |
| Pre-requisites | Co-requisites | Knowledge, Abilities, or Skills | | Private study | (70 |
| 🗵 None | ⊠None | Knowledge and | | hours) | , (, 0 |
| | | command of | | Exam prepar | ation (20 |
| | | probability theory | | hours) | |
| | | and methods, as | Duration | Workload | |
| | | in the module | 1 comoctor | 125 hours | |
| | | "Probability and Random Process" | 1 semester | 125 hours | |
| compressed "mod which the robot lea language model; t | (ML) concerns algor el" of the data. An ex rns a model of its env he input data are sp | ithms that are fed with (large ample is the "world model" of ironment, which is needed, for eech recordings, from which ech recognition systems. There | a robot; the input instance, for naviga ML methods build | data are sensor data ition. Another examp a model of spoken E | streams, fro le is a spoke nglish; this |
| | | f learning algorithms. Howeve | | | |
| | | se formalisms and algorithms. | | | |
| | | entary model formalisms (line | | - | |
| | - | ilters, neural networks, or h | lidden Markov mo | dels). Furthermore, | the lectur |
| also tre-initionice | | theory and linear algebra. | | | |
| also (re-)introduce mathematical mat | chunn onn probublinty | | | | |
| | · · · · | | | | |
| mathematical mat | · · · · | ould be able to | | | |
| mathematical mat Intended Learning Ou By the end of this r | itcomes nodule, students sho | ould be able to ability spaces and random varia | ables; | | |
| mathematical mat Intended Learning Ou By the end of this r 1. understar | nodule, students sho | | | | |
| mathematical mat Intended Learning Ou By the end of this r 1. understar 2. understar 3. understar | nodule, students sho nodule, students sho nd the notion of prob nd basic linear model nd the fundamental n | ability spaces and random varia ing and estimation techniques nature of the "curse of dimension | ; onality;" | | |
| mathematical mat Intended Learning Ou By the end of this r 1. understar 2. understar 3. understar 4. understar | nodule, students sho nodule, students sho nd the notion of prob nd basic linear model nd the fundamental n nd the fundamental n | ability spaces and random varia | ; onality;" blem and standard (| | |

multilayer perceptrons);

6. implement an end-to-end learning suite, including feature extraction and objective function optimization with regularization based on cross-validation.

Indicative Literature

T. Hastie, R. Tibshirani, J. Friedman, The Elements of Statistical Learning: Data Mining, Inference, and Prediction, 2nd edition, Springer, 2008.

S. Shalev-Shwartz, Shai Ben-David: Understanding Machine Learning, Cambridge University Press, 2014.

C. Bishop, Pattern Recognition and Machine Learning, Springer, 2006.

T.M. Mitchell, Machine Learning, Mc Graw Hill India, 2017.

Usability and Relationship to other Modules

This module gives a thorough introduction to the basics of machine learning. It complements the Artificial Intelligence module.

Examination Type: Module Examination

Assessment Type: Written examination

Duration: 120 min Weight: 100%

Scope: All intended learning outcomes of the module

7.9 RIS Lab

| BICL I | | Module Code | Level (type) | СР |
|--|--|--|---|-------------------|
| RIS Lab | | CO-542 | Year 2 (CORE) | 5 |
| Module Component | S | | | |
| Number | Name | | Туре | СР |
| CO-542-A | RIS Lab I | | Lecture/lab | 2.5 |
| CO-542-B | RIS Lab II | | Lecture/lab | 2.5 |
| Module Coordinator | Program Affiliation | | Mandatory Status | |
| Prof. Dr. Francesco Maurelli | Robotics and Intelligent Systems (RIS) | | Mandatory mino Mandatory electi | |
| Entry Requirements Pre-requisites ⊠ Programming in C/C++ | Co-requisites Knowledge, Abilities, or ⊠ None Skills | Frequency Annually (Fall) Duration | Forms of Learn Teaching Class attend hours) Private study hours) Report prepa hours) Workload | ance (35 7 (70 |
| | | | | |
| | | 2 semesters | 125 hours | |
| Recommendations fo | r Preparation | | | |
| None Content and Education | | | | |
| RIS Lab I focuses o and on the introdu | n robotics middleware such as the Robot Operati actory course, it presents ways in which different y in simulation, using the ROS Gazebo package or e students to apply what they learned in simulation | units of a robotic sy similar. with real robotics sy | ystem can share info | rmation. The |
| world adds a layer | of complexity which students will face for the first ti king with real systems, will learn how to integrate s ientific manner. | - | | - |
| world adds a layer of simulation and wor their journey in a sc | king with real systems, will learn how to integrate s | oftware to run real | time and to articulate | and describe |
| world adds a layer of simulation and wor their journey in a sc | king with real systems, will learn how to integrate s ientific manner. htroduced to and practice technical and scientific v | oftware to run real | time and to articulate | and describe |
| world adds a layer of simulation and wor their journey in a sc Students are also in Intended Learning Ou | king with real systems, will learn how to integrate s ientific manner. htroduced to and practice technical and scientific v | oftware to run real | time and to articulate | and describe |

 Indicative Literature

 A. Koubaa, Robot Operating System (ROS), The Complete Reference Vol 1, Springer, 2018.

 Usability and Relationship to other Modules

 Examination Type: Module Component Examination Module

 Component 1: Lab 1

 Assessment Type: Laboratory report

 Length: approx. 10 pages

 Weight: 50%

 Scope: Intended learning outcomes of RIS Lab I - 1, 2, 3, 6.

 Module Component 2: Lab 2

 Assessment Type: Laboratory report

 Length: approx. 10 pages

 Weight: 50%

 Scope: Intended learning outcomes of RIS Lab II - 4, 5.

 Completion: To pass this module, both module component examinations have to be passed with at least 45%.

7.10 Automation

| Module Name | | | Module Code | Level (type) | СР |
|--|---|--|--|---|--|
| Automation | | | CO-543 | Year 2 (CORE) | 5 |
| Module Components | | | | | |
| Number | Name | | | Туре | СР |
| CO-543-A | Automation | | | Lecture | 5 |
| Module Coordinator | Program Affiliation | | | Mandatory Status | |
| | | | | Walluatory Status | |
| Prof. Dr. Francesco Maurelli | Robotics and | d Intelligent Systems (RIS) | | Mandatory elec RIS | ctive for |
| Entry Requirements | | | Frequency | Forms of Learnin | ig and |
| | | | | Teaching | |
| Pre-requisites | Co-requisites | Knowledge, Abilities, or | Annually (Spring) | Lectures (3 | 0 hours) |
| The requisites | corequisites | Skills | | Lab (5 hour | |
| ⊠ Programming | 🛛 None | • Understanding of the | | Private stud | |
| C/C++ | | basics of electronics | | hours) | |
| Mathematical and | | Calculus | | Exam prepa (20 haven) | aration |
| Physical Foundations of Robotics I | | basic C/C++/Python basic | | (20 hours) | |
| | | • Dasic MATLAB/Simulink or | Duration | Workload | |
| | | SciLab | | | |
| | | | 1 semester | 125 hours | |
| Recommendations for P | reparation | | | | |
| Review material of En | nbedded Systems L | ab. | | | |
| Content and Educationa | I Aims | | | | |
| Automation is the ap | plication of science | e and technology to control me | chanical systems, incl | uding situations in | which this |
| | | f a human operator or even exc | ceeds them. Industria | l automation conce | entrates on |
| solutions in the prod | | of products and services. | | 11 | |
| | | ole overlap with the fields of (| Lontrol and Robotics. | | tinguishing |
| The field of automat | | | | ant focus on robu | stness and |
| The field of automat aspect is the emphase | sis on an industrial | performance and setting, alor | | ant focus on robu | stness and |
| The field of automat aspect is the emphase efficiency under factor | sis on an industrial ory conditions. | | ng with the concomita | | |
| The field of automat aspect is the emphase efficiency under factor The topics covered in estimation; types of | sis on an industrial ory conditions. this course include actuators and de | performance and setting, alor an introduction to sensors and tails about the operation of | ng with the concomit d their scientific princi industrial motors an | ples; filtering, data Id drives; an intro | fusion and duction to |
| The field of automat aspect is the emphase efficiency under factor The topics covered in estimation; types of programmable logic of | sis on an industrial pry conditions. this course include actuators and de controllers (PLCs); th | performance and setting, alor an introduction to sensors and stails about the operation of heir hierarchy and different PLC | ng with the concomits d their scientific princi industrial motors an C programming paradig | ples; filtering, data Id drives; an intro | fusion and oduction to |
| The field of automat aspect is the emphase efficiency under factor The topics covered in estimation; types of programmable logic of | sis on an industrial pry conditions. this course include actuators and de controllers (PLCs); th | performance and setting, alor an introduction to sensors and tails about the operation of | ng with the concomits d their scientific princi industrial motors an C programming paradig | ples; filtering, data Id drives; an intro | fusion and oduction to |
| The field of automat aspect is the emphase efficiency under factor The topics covered in estimation; types of programmable logic of | sis on an industrial ory conditions. this course include actuators and de controllers (PLCs); the automation, such a | performance and setting, alor an introduction to sensors and stails about the operation of heir hierarchy and different PLC | ng with the concomits d their scientific princi industrial motors an C programming paradig | ples; filtering, data Id drives; an intro | fusion and oduction to |
| The field of automat aspect is the emphase efficiency under factor The topics covered in estimation; types of programmable logic of (AI) concepts used in Intended Learning Outco | sis on an industrial ory conditions. this course include actuators and de controllers (PLCs); th automation, such a | performance and setting, alor an introduction to sensors and etails about the operation of heir hierarchy and different PLC as state machines and sensor da | ng with the concomits d their scientific princi industrial motors an C programming paradig | ples; filtering, data Id drives; an intro | fusion and oduction to |
| The field of automat aspect is the emphase efficiency under factor The topics covered in estimation; types of programmable logic of (AI) concepts used in Intended Learning Outco By the end of this mo | sis on an industrial ory conditions. this course include actuators and de controllers (PLCs); th automation, such a omes dule, students show | performance and setting, alor an introduction to sensors and etails about the operation of heir hierarchy and different PLC as state machines and sensor da | ng with the concomit d their scientific princi industrial motors an programming paradig ata processing. | ples; filtering, data d drives; an intro gms; and artificial i | fusion and oduction to ntelligence |
| The field of automat aspect is the emphase efficiency under factor The topics covered in estimation; types of programmable logic of (AI) concepts used in Intended Learning Outcor By the end of this moo 1. explain the of | sis on an industrial ory conditions. this course include cactuators and de controllers (PLCs); th automation, such a omes dule, students shou characteristics and p | performance and setting, alor early an introduction to sensors and early about the operation of heir hierarchy and different PLC as state machines and sensor da uld be able to principles of a number of indust | ng with the concomit d their scientific princi industrial motors an programming paradig ata processing. | ples; filtering, data Id drives; an intro gms; and artificial i | fusion and oduction to ntelligence |
| The field of automat aspect is the emphase efficiency under factor The topics covered in estimation; types of programmable logic of (AI) concepts used in Intended Learning Outco By the end of this mo 1. explain the of overall para 2. apply this kr | sis on an industrial ory conditions. this course include actuators and de controllers (PLCs); th automation, such a omes dule, students shou characteristics and p meters such as acco nowledge to transla nd processing strat | performance and setting, alor an introduction to sensors and etails about the operation of heir hierarchy and different PLC as state machines and sensor da | ng with the concomit d their scientific princi industrial motors an programming paradig ata processing. trial sensors and elect e the reasons for the ns into an automatior | ples; filtering, data Id drives; an intro gms; and artificial i ric motors, comme calibration process problem in terms | fusion and oduction to ntelligence ent on their |

- 3. apply a family of filtering and estimation techniques covered in the lectures to systems similar to those used in the examples; recall the analysis of their stability and duplicate it in the case of the presented system;
- 4. apply the state machine concept to simple processes and routines;
- 5. explain the strengths, principles, and programming paradigms of PLCs;
- 6. recall the currently used concept in organizing a factory-wide automation pyramid and understand the working of at least one automation communication protocol in detail;
- 7. combine the skills mentioned above in proposing solutions to simple industrial problem examples.

Indicative Literature

N. Zuech, Handbook of Intelligent Sensors for Industrial Automation, Addison-Wesley, 1992.

A. Hughes, Electric Motors and Drives, 3rd edition, 2006.

K. Collins, PLC Programming for Industrial Automation, 2007.

Usability and Relationship to other Modules

- A portion of the knowledge is complementary with the Control Systems course
- The robotics course completes the information given in this course with respect to mobile machinery.

Examination Type: Module Examination

Assessment Type: Written examination

Duration: 150 min Weight: 100%

Scope: The course material excluding programming skills.

The exam will provide a number of multiple choice of true/false questions, where students will be expected to recall facts and principles covered in the class.

Sample problems will be given, similar to those given in class, where the students will be expected to duplicate the calculations and choice principles explained in the class.

An open-ended question will test their understanding of the entire concepts such as calibration or state machine.

7.11 Embedded Systems

| Module Name | | Module Code | Level (type) | СР |
|--|---|---|--|---|
| Embedded Systems | i | CO-544 | Year 2 (CORE) | 5 |
| Module Components | 5 | | | |
| Number | Name | | Туре | СР |
| CO-544-A | Embedded Systems | | Lecture/Lab | 5 |
| Module Coordinator | Program Affiliation | | Mandatory Status | |
| Dr. Fangning Hu | Robotics and Intelligent Systems (RIS) | | Mandatory electi | ve for RIS |
| Entry Requirements Pre-requisites | Co-requisites Knowledge, Abilities, or Skills | Frequency Annually (Fall) | Forms of Learn Teaching Lecture/Lab Private stud |) (35 hours) |
| Programming in C/C++ | ⊠ None | Duration | hours) Workload | |
| | | 1 semester | 125 hours | |
| Content and Educatio Microcontrollers are with considerable c rapidly growing tee AVR/ARM processo tablets, and various sound introduction a series of design ta memory, and I/O | ing in C and the binary number systems. nal Aims e core components of modern devices. Designed to omputational power at relatively low cost and with chnological environment, in particular, when it of based on the RISC-architecture, which is becom forms of embedded systems, owing to its small siz to these nearly ubiquitous devices and guides the basks. The list of topics includes the basic architect interface; the concepts of working registers, a such as embedded C and assembler, as we | I limited power cons comes to mobile s ning increasingly po te and low power co students in an app cure of a microcont interrupt vectors, a | sumption, they are en ystems. We are goin opular with its use in onsumption. The cou lication-oriented ma roller with its ALU, ti and program counte | nablers of or ng to use th smartphone rse provides inner throug mer/counte ers; necessa |
| reading/controlling | ; various sensors/actuators, processing internal/e At the end of the course, students should be al ions on | external interrupts, | , generation of PWN | /I signals, ar |
| Intended Learning Out | tcomes | | | |
| • | this module, students should be able to cribe the architecture of a microcontroller; | | | |

- 2. understand the datasheet of a microcontroller;
- 3. program a microcontroller to read/control sensors/actuators, process interrupters, generate PWM, and perform AD/DA conversion;
- 4. design a solution for an embedded application by microcontroller.

Indicative Literature

Online resources and manuals provided by the Instructor of Records.

M. Michalkiewics et. al, AVR C Runtime Library, <u>http://savannah.nongnu.org/projects/avr-libc/</u>, accessed 3 March 2020.

Usability and Relationship to other Modules

• This module introduces the architecture of an AVR/ARM-based microcontroller and how to program it. It could also serve as a specialization course for students from Electrical and Computer Engineering and Computer Science.

Examination Type: Module Examination

Assessment Type: Project Assessment

Duration: 180 min Weight: 100%

Scope: All intended learning outcomes of the module

7.12 Control Systems

| | | | Module Code | Level (type) | СР |
|--|--|--|--|--|--|
| Control Systems | | | CO-545 | Year 2 (CORE) | 5 |
| Module Components | 5 | | | | |
| Number | Name | | | Туре | СР |
| CO-545-A | Control Systems | | | Lecture | 5 |
| Module Coordinator | Program Affiliation | | | Mandatory Status | |
| Prof. Dr. Mathias Bode | Robotics and | Intelligent Systems (RIS) | | Mandatory Elect | ive for RIS |
| Entry Requirements | | | Frequency Annually (Fall) | Forms of Learn Teaching | - |
| Pre-requisites | Co-requisites | Knowledge, Abilities, or Skills • Transfer functions | | Lecture (35 Private stud hours) | |
| Elements of Linear Algebra | | Transfer functionsLaplace transforms | Duration | Workload | |
| Elements of Calculus (or the Matrix version) | | | 1 semester | 125 hours | |
| Mathematical and Physical Foundations of Robotics II | | | | | |
| course pages for de Content and Educatio This course offers introduction to RIS includes (different) stability, the role o the response of a g tools will be the Ny | ear algebra, Laplace f etails. a systematic walk t course, new conce state space represe f disturbances, and given system via lea rquist plot and techn | transforms, and obtain the contransforms, and obtain the contransforms, and obtain the contract of the perspectives, and skills with the related question technique the related question of sensit and lag compensators, inclusion of sensit of and lag compensators, inclusion of the complexes of the | f control theory for will be introduced es for larger block d ivity. We will also s | linear systems. Bu and discussed. In p iagrams, the BIBO p tudy new approache | ilding on the articular, this erspective or es to improve |
| - | ourse, successful stu | idents will be able to ental concepts from linear con | trol theory; lyze systems for stal | silitye | |

Indicative Literature

N.S. Nise: Control Systems Engineering, John Wiley & Sons, 2010.

Usability and Relationship to other Modules

This module introduces the students to the field of automatic control and is strongly related to the embedded systems, automation, and robotics modules. However, it also helps to better understand how systems in general, be they mechanical, electrical, biological, or even social, such as smart cities, can be maintained under stable conditions and with desired response characteristics.

Examination Type: Module Examination

Assessment Type: Written examination

Duration: 120 min Weight: 100%

Scope: All intended learning outcomes of the module

7.13 Computer Vision

| Computer Vision | | | | |
|--|---|--|---|--|
| - | | CO-546 | Year 2 (CORE) | 5 |
| Module Components | | | | |
| Number | Name | | Туре | СР |
| CO-546-A | Computer Vision | | Lecture/lab | 5 |
| Module Coordinator | Program Affiliation | | Mandatory Status | |
| Prof. Dr. Francesco Maurelli | Robotics and Intelligent Systems (RIS) | | Mandatory electi | ive for RIS, C |
| Entry Requirements | | Frequency | Forms of Learn Teaching | ing and |
| Pre-requisites ☑ Mathematical and Physical Foundations of Robotics I ☑ Programming in C/C++ | Co- requisites Knowledge, Abilities, or Skills Basic knowledge of robotics middleware (RIS Lab I) | Annually (Fall) | Class attend hours) Private study hours) Exam prepar hours) | y (70 |
| | | Duration | Workload | |
| | | 1 semester | 125 hours | |
| Content and Educational A Computer Vision algori 3D model building (ph represent elegant app recapitulation of relevant | ming skills in MATLAB and/or Python Aims ithms are used in a variety of real-world applic notogrammetry), and object recognition. Apa lications of linear algebra and optimization to nt linear algebra, introduction to face-recognitio ructure from motion, color-spaces, segmentat | art from their visu techniques. Topics on, camera calibratio | al appeal, these alg covered in this cou on, stitched panoran | gorithms also irse include a nas, edge and |
| Intended Learning Outcom | | | | |
| describe image calibrate came compute image discriminate and Properly use compared | ule, students should be able e formation and camera models; eras; ge histograms, and basic image processing; mong visual features (e.g., corner, edge, blob); omputer vision libraries; mputer vision applications. | | | |
| Indicative Literature | | | | |
| D.A. Forsyth and J. Pone | ce, Computer Vision: A Modern Approach. 2nd | edition, 2011. | | |
| R. Szeliski, Computer V | ision: Algorithms and Applications, Springer, h | ttp://szeliski.org/Bo | ook, 2010. Ma et | |
| | | | , | |

Usability and Relationship to other Modules

- Giving the foundation of computer vision, this module is important for RIS project and for advanced specialization courses.
- This module serves as a third year Specialization module for CS major students.
- This module belongs to the Data Science Track in the MSc AST

Examination Type: Module Examination

Assessment Type: Written examination

Duration: 120 min

Weight: 100%

Scope: All intended learning outcomes of the module

Module achievements: 50% if the assignments correctly solved

7.14 Artificial Intelligence

| Module Name | | Module Code | Level (type) | СР |
|--|---|--|--|-------------------------------|
| Artificial Intelligen | ce | CO-547 | Year 2 (CORE) | 5 |
| Module Component | s | | | |
| Number | Name | | Туре | СР |
| CO-547-A | Artificial Intelligence | | Lecture | 5 |
| Module Coordinator | Program Affiliation | | Mandatory Status | |
| Prof. Dr. Andreas Birk | Robotics and Intelligent Systems (RIS) | | Mandatory for R in RIS Mandatory electi SDT | |
| Entry Requirements | | Frequency | Forms of Learn | ing and |
| | | Annually | Teaching | |
| Pre-requisites Algorithms and data structures or Core Algorithms | Co-requisites Knowledge, Abilities, or Skills ⊠ None | Annually (Spring) | Class attend hours) Private stud hours) Exam prepar hours) | y (70 |
| and Data | | Duration | Workload | |
| Structures | | 1 semester | 125 hours | |
| Recommendations for | r Preparation | | | |
| Revise content of the | ne pre-requisite modules. | | | |
| Artificial Intelligence performance of tas there is an increasi | ee (AI) is an important subdiscipline of Computer S sks that are usually associated with intelligence. A ng interest and need to generate artificial systems out permanent human supervision. The module t | N methods have a s s that can carry out | significant application complex missions in | n potential, a unstructure |
| AI. In addition to | general-purpose techniques and algorithms, it a al systems such as intelligent mobile robots or auto | llso includes aspec | | |
| Intended Learning Ou | tcomes | | | |
| By the end of this m | nodule, students should be able to | | | |
| apply the use conce explain the | nd explain the history, general developments, and basic concepts and methods of behavior-oriented epts and methods of search algorithms for problem ne basic concepts of path-planning as an application | AI; n-solving; on example for dom | nain-specific search; | |
| | ic path-planning algorithms and to compare their r l explain concepts of propositional and first-order l | - | search algorithms; | |

- 6. write and explain concepts of propositional and first-order logic;
- 7. use logic representations and inference for basic examples of artificial planning systems.

Indicative Literature

- S. Russell and P. Norvig, Artificial Intelligence: A Modern Approach, Prentice Hall, 2009.
- S. M. LaValle, Planning Algorithms. Cambridge University Press, 2006. J.-C.

Latombe, Robot Motion Planning, Springer, 1991.

Usability and Relationship to other Modules

• This module gives an introduction to Artificial Intelligence (AI) excluding the aspects of machine learning (ML), which are covered in a dedicated module that complements this one.

Examination Type: Module Examination

Assessment Type: Written examination

Scope: All intended learning outcomes of the module

Duration: 120 min Weight: 100%

7.15 RIS Project

| Module Name | | | Module Code | Level (type) | СР |
|--|---|--|--------------------------------------|--|--------------------------------|
| RIS Project | | | CO-548 | Year 2 (CORE) | 5 |
| Module Component | s | | | | |
| Number | Name | | | Туре | СР |
| CO-548-A | RIS Project | | | Lecture/lab | 5 |
| Module Coordinator Prof. Dr. Francesco Maurelli | Program Affiliation Robotics and Intellige | ent Systems (RIS) | | Mandatory Status | 5 |
| Entry Requirements Pre-requisites Mathematical and Physical Foundations of Robotics I Programming in | Skills ⊠ None • E r (| vledge, Abilities, or Basic knowledge of robotics middleware RIS Lab I) | Frequency Annually (Spring) | Forms of Learning Class attend hours) Private study hours) Report prep hours) | ance (35 y (70 |
| C/C++ Recommendations fo | r Prenaration | | Duration 1 semester | Workload 125 hours | |
| | rreparation | | | | |
| None | | | | | |
| a project that is related to focus on, involves systems competence | ect is to use real robotics sy ated to one or more modules ving a combination of robo ces. The lecture part of the m ncluding basic health and sa | s of the RIS program. St tics, computer vision, nodule will focus on the | udents will work in machine learning | groups and will choc , artificial intelligence | ose a scenari e, and contro |
| Intended Learning Ou | tcomes | | | | |
| By the end of this n | nodule, students should be a | able to | | | |
| develop r integrate design ar work in a | ilable libraries to real roboti new robotics functionalities; new functionalities in robot d plan a project over several team, overcoming challenge cientific results in an adequa | tics systems; weeks; s; | | | |
| Indicative Literature | | | | | |
| Not specified | | | | | |

Not specified

Usability and Relationship to other Modules

• This module represents a glue among various different core modules, focusing on the design and implementation of a project with real robotics systems. It is pivotal for advanced courses in the third year and lays the foundation for the competence skills required for the thesis.

Examination Type: Module Examination

Assessment Component 1: Project report

Scope: Intended learning outcomes of the lecture 1, 2, 3, 4, 5).

Assessment Component 2: Presentation

Scope: Intended learning outcomes of the lab 4, 5, 6.

Length: approx. 15 pages Weight: 75%

Duration: approx. 15 min Weight: 25%

Completion: This module is passed with an assessment-component weighted average grade of 45% or higher.

7.16 Marine Robotics

| Module Name | | | Module Code | Level (type) | СР |
|--|---|--|--|--|-------------------------------|
| Marine Robotics | | | CA-S-RIS-801 | Year 3 (Specialization) | 5 |
| Module Components | 5 | | | | |
| Number | Name | | | Туре | СР |
| CA-RIS-801 | Marine Robotics | | | Lecture/lab | 5 |
| Module Coordinator | Program AffiliationRobotics and I | ntelligent Systems (RIS) | | Mandatory Status Mandatory Elect | ive for RIS |
| Prof. Dr. Francesco Maurelli | | | | | |
| Entry Requirements Pre-requisites Mathematical and Physical Foundations of Robotics I | Co-requisites ⊠ None | Knowledge, Abilities, or Skills Basic knowledge of robotics middleware (RIS Lab I) | Frequency Annually (Spring) Duration | Forms of Learn Teaching Class attend hours) Private stud hours) Exam prepa hours) Workload | dance (35 ly (70 |
| Programming in C/C++ Recommendations for | | | 1 semester | 125 hours | |
| None | | | | | |
| Content and Educatio | nal Aims | | | | |
| environments (envi estimated that the than €400 billion ar This module builds | ironment assessment economic impact of t nnually, with more th on the CORE courses | role in the exploitation of n .), and security applications he "blue" economy, which co an €150 billion in activities d of the second year with a sp echnical solutions, and curren | (harbor protection) onsiders all activitie irectly related to m ecialization on (inte |). The European Co as linked to the sea, i arine activities. | mmission has is worth more |
| | by this module includ d multivehicle coope | e ROV and AUV operations, u ration. | inderwater acoustic | c, underwater sensir | ng, navigation, |
| The module will ha excursions. | ve a practical compo | nent, with the possibility of | visiting nearby inst | itutions and particip | oating in field |
| Intended Learning Out | tcomes | | | | |
| By the end of this m | nodule, students shou | Id be able to | | | |
| analyze the develop ac | e functioning of acous Ivanced functionalitie | e marine domain for robotics stic devices for robot autonon es for a marine robot in a simu es for a marine robot in the fie | ny; Ilation; | | |

Indicative Literature

•

L. Jaulin et. al, Marine Robotics and Applications , Springer, 2018.

S. W. Moore, Underwater Robotics: Science, Design & Fabrication, 2010.

B. Siciliano O. Khatib, Springer Handbook of Robotics, Springer, 2008.

Usability and Relationship to other Modules

This module is a robotics-oriented specialization course, with the possibility to work with real robots.

Examination Type: Module Examination

Assessment Type: Oral examination

Scope: All intended learning outcomes of the module

Duration: approx. 15 min Weight: 100%

7.17 Human Computer Interaction

| Module Name | | | Module Code | Level (type) | СР |
|------------------------------------|--------------------|------------------------------------|-----------------|---|-----------------|
| Human Computer I | nteraction | | CA-S-RIS-802 | Year 3 (Specialization) | 5 |
| Module Components | S | | | | |
| Number | Name | | | Туре | СР |
| CA-RIS-802 | Human Compute | er Interaction | | Lecture | 5 |
| Module Coordinator | Program Affiliatio | n | | Mandatory Status | |
| Prof. Dr. Francesco Maurelli | Robotics ar | nd Intelligent Systems (RIS) | | Mandatory electi | ive for RIS, CS |
| Entry Requirements | | | Frequency | Forms of Learni | ing and |
| Pre-requisites | Co-requisites | Knowledge, Abilities, or Skills | Annually (Fall) | Class attend hours) | ance (35 |
| ⊠ None | ⊠ None | • None | | Private study hours) Exam preparhours) | , . |
| | | | Duration | Workload | |
| | | | 1 semester | 125 hours | |

None

Content and Educational Aims

Computer systems often interact with human beings. The design of a good human–computer interface is often crucial for the acceptance and the success of a software system. Human–computer interface designs have to satisfy several requirements such as usability, learnability, efficiency, accessibility, and safety. The module discusses the evolution of human–computer interaction models and introduces design principles for graphical user interfaces and other types of interaction (e.g., visual, voice, gesture). Human–computer interaction designs are often evaluated using prototypes or mockups that can be given to test candidates to evaluate the effectiveness of the design. The module introduces evaluation strategies as well as tools and techniques that can be used to prototype human–computer interfaces.

Intended Learning Outcomes

By the end of this module, students should be able to

- 1. explain the evolution of human–computer interaction models;
- 2. design and implement simple graphical user interfaces;
- 3. explain ergonomic principles guiding the design of user interfaces;
- 4. illustrate different types of interaction (e.g., visual, voice, gestures) and their usability aspects;
- 5. evaluate aspects of and tradeoffs between usability, learnability, efficiency, and safety;
- 6. apply scientific methods to evaluate interfaces with respect to their usability and other desirable properties;
- 7. use prototyping tools that can be employed to create mockups of user interfaces during the early stages of a software project.

Indicative Literature

Alan Dix, Janet Finlay, Gregory D. Abowd, and Russell Beale: Human-Computer Interaction, 3rd edition, Pearson, 2004

Ben Shneiderman, Catherine Plaisant, Maxine Cohen, Steven Jacobs, Niklas Elmqvist, Nicholas Diakopoulos: Designing the User Interface: Strategies for Effective Human-Computer Interaction, 6th edition, Pearson, 2016

Céline Jost, Brigitte Le Pévédic, Tony Belpaeme, Cindy Bethel, Dimitrios Chrysostomou, Nigel Crook, Marine Grandgeorge, Nicole Mirnig, Human-Robot Interaction, Evaluation Methods and Their Standardization, Springer 2020 ISBN: 978-3-030-42306-3

Usability and Relationship to other Modules

• Students with a strong interest in graphical user interfaces are encouraged to also select the Computer Graphics specialization module, which introduces methods and technologies for creating computer graphics and animations.

Examination Type: Module Examination

Assessment Type: Project assessment

Duration: 120 min

Scope: All intended learning outcomes of the module

Weight: 100%

7.18 Optimization

| Module Name | | Module Code | Level (type) | СР |
|---|---|---|--|--|
| Optimization | | CA-S-RIS-803 | Year 3 (Specialization) | 5 |
| Module Componen | ts | | | |
| Number | Name | | Туре | СР |
| CA-RIS-803 | Optimization | | Lecture | 5 |
| Module Coordinator Prof. Dr. Mathias Bode | Program Affiliation Robotics and Intelligent Systems (RIS) | | Mandatory Status Mandatory electi | ve for RIS |
| Entry Requirements Pre-requisites SElements of Linear Algebra | Co- requisites Knowledge, Abilities, or Skills ⊠ None | Frequency Annually (Spring) | Forms of Learni Teaching Lecture (35) Private studhours) | hours) |
| \boxtimes Elements of | | Duration | Workload | |
| Calculus (or the Matrix version) | | 1 semester | 125 hours | |
| Content and Educati Optimization is a calculus applied t perspective of th programming met particular, in the c search methods, i | d linear algebra from your first year. onal Aims key step in the design of systems and processes. to unconstrained problems. It then focuses on ea e Lagrange formalism and introduces the KKT th chods are covered as important application-oriente ase of semidefinite programming. The last part of th ntroducing the ideas of genetic algorithms. The co ctronics, decision-making, machine learning, and o | quality- and inequali neorem for convex ed examples. Special ne course is devoted to purse provides a wid | ity- constrained ca problems. Linear a emphasis is placed to deterministic and | ses from the ind quadrati on duality, in probabilisti |
| Intended Learning O By the end of this | utcomes course, successful students will be able to | | | |
| apply an phrase c | assical search techniques; d understand the Lagrange formalism; optimization problems in terms of suitable standard timization problems by means of dedicated software | | nem accordingly; | |
| - | denberghe, Convex Optimization, Cambridge Unive | | | |
| J. Brinkhuis & V. T | ikhomiriv, Optimization: Insights and Applications, | Princeton University | Press, 2005. | |

Usability and Relationship to other Modules

• This module builds on the first year Calc/LA modules and prepares the students for more challenging optimization aspects, which will be relevant in many third year projects, particularly in the fields of machine learning, robotics, control, and communication.

Examination Type: Module Examination

Type: Written examination

Scope: Intended Learning Outcomes 1–3

Duration: 120 min Weight: 100%

Intended Learning Outcome 4 will be assessed through non graded tasks during the lecture.

7.19 Distributed Algorithms

| Module Name | | Module Code | Level (type) | ç |
|---|--|--|---|--|
| Distributed Algorithms | ms | CA-S-CS-803 | Year 3 (Specialization) | л |
| Module Components | | | | |
| Number | Name | | Туре | CP |
| CA-CS-803 | Distributed Algorithms | | Lecture | л |
| Module Coordinator | Program Affiliation | | Mandatory Status | |
| Dr. Kinga Lipskoch | Computer Science (CS) | | Mandatory elective for CS, SDT and RIS | e for CS, |
| Entry Requirements | | Frequency | Forms of Learning Teaching | g and |
| Pre-requisites | Co-requisites Knowledge, Abilities, or Skills | Annually (Fall or Spring) | Class attendance (35 hours) | nce (35 |
| ☑ Algorithms and Data | | | Private study (70 hours) | (70 |
| Structures or Core Algorithms | | | Exam preparation (20 hours) | tion (20 |
| and Data Structures | | Duration 1 semester | Workload 125 hours | |
| Recommendations for Preparation | Preparation | | | |
| None Content and Educational Aims | nal Aims | | | |
| Distributed algorith knowledge of a glot course introduces I transition system. Th election algorithms, as another formalisr | Distributed algorithms are the foundation of modern distributed computing systems. They are characterized by a lack of knowledge of a global state, a lack of knowledge of a global time, and inherent non-determinism in their execution. The course introduces basic distributed algorithms using an abstract formal model, which is centered on the notion of a transition system. The topics covered are logical clocks, distributed snapshots, mutual exclusion algorithms, wave algorithms, and distributed consensus algorithms. Process algebras are introduced as another formalism to describe distributed and concurrent systems. | puting systems. The d inherent non-dete rmal model, which shots, mutual exclus nsensus algorithms. | ey are characterized erminism in their exe is centered on the ion algorithms, wave Process algebras are | by a lack of ecution. The notion of a algorithms, e introduced |
| The distributed algo and fault-tolerant, recommended for s | The distributed algorithms introduced in this module form the foundation of computing systems that have to be scalable and fault-tolerant, e.g., large-scale distributed non-standard databases or distributed file systems. The course is recommended for students interested in the design of scalable distributed computing systems. | ition of computing s bases or distribute uted computing sys | systems that have to ed file systems. The stems. | be scalable e course is |
| Intended Learning Outcomes By the end of this m | ded Learning Outcomes By the end of this module, students will be able to | | | |
| describe ar explain diff illustrate the second second | describe and analyze distributed algorithms using formal methods such as transition systems; explain different algorithms to solve election problems; illustrate the limitations of time to order events and how logical clocks and vector clocks overcome these | nods such as transiti al clocks and vector | on systems; clocks overcome the | ese |
| apply distri describe th analyze and use a proce algorithms. | apply distributed algorithms to produce consistent snapshots of distributed computations describe the differences among wave algorithms for different topologies; analyze and implement distributed consensus algorithms such as Paxos and Raft; use a process algebra such as communicating sequential processes or -calcu⊠s to model algorithms. | of distributed comp copologies; 1 as Paxos and Raft; esses or <i>-</i> calcuᢂs t | uted computations; s; s and Raft; -calcu잾s to model distributed | |
| , | | | | |

Indicative Literature

Maarten van Steen, Andrew S. Tanenbaum: Distributed Systems, 3rd edition, Pearson Education, 2017. Nancy A.

Lynch: Distributed Algorithms, Morgan Kaufmann, 1996.

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment Type: Written examination

Duration: 120 min Weight: 100%

Scope: All intended learning outcomes of the module

7.20 Computer Graphics

| Module Name | | Module Code | Level (type) | СР |
|---|--|---|--|------------------------------|
| Computer Graphics | | CA-S-CS-801 | Year 3 (Specialization) | 5 |
| Module Components | 5 | | | |
| Number | Name | | Туре | СР |
| CA-CS-801 | Computer Graphics | | Lecture | 5 |
| Module Coordinator | Program Affiliation | | Mandatory Status | |
| Prof. Dr. Jürgen Schönwälder | Computer Science (CS) | | Mandatory elective for CS and RIS | |
| Entry Requirements | | Frequency | Forms of Learning and Teaching | |
| Pre-requisites | | Annually (Fall) | | |
| | Co-requisites Knowledge, Abilities, or | | Class attendance (35 hours) Private study (70 | |
| \boxtimes | Skills | | | |
| Algorithms and | ⊠ None | | | |
| Data Structures or Core | | | hours) | |
| Algorithms and | | Exam preparation hours) | | ration (20 |
| Data Structures | | Duration | Workload | |
| | | 1 semester | 125 hours | |
| Recommendations for | Preparation | | | |
| None | | | | |
| Content and Educatio | nal Aims | | | |
| spans from the creater graphics are geome | vith the digital synthesis and manipulation of visua ation of a three-dimensional (3D) scene to displayi try processing, rendering, and animation. Geometry d their modeling. Rendering is concerned with tra | ng or storing it digi y processing is conc | tally. Prominent task erned with object rep | s in compute presentation |

such as surfaces and their modeling. Rendering is concerned with transforming a model of the virtual world into a set of pixels by applying models of light propagation and sampling algorithms. Animation is concerned with descriptions of objects that move or deform over time. This is an introductory module covering the concepts and techniques of 3D (interactive) computer graphics. It covers mathematical foundations, basic algorithms and principles, and some advanced methods and concepts. An introduction to the implementation of simple programs using a mainstream computer graphics library completes this module.

Intended Learning Outcomes

By the end of this module, students will be able to

- 1. construct 3D geometry representations;
- 2. apply 3D transformations;
- 3. understand the algorithms and optimizations applied by graphics rendering systems;
- 4. explain the stages of modern computer graphics programmable pipelines
- 5. implement simple computer graphics applications using graphics frameworks such as OpenGL;
- 6. illustrate the techniques used to create animations.

Indicative Literature

John Hughes, Andries van Dam, Morgan McGuire, David F. Sklar, James D. Foley, Steven K. Feiner, Kurt Akeley, Computer Graphics - Principles and Practice, 3rd edition, Addison-Wesley, 2013.

Peter Shirley, Steve Marschner, Fundamentals of Computer Graphics, 4th edition, Taylor and Francis Ltd, 2016.

Matt Pharr, Wenzel Jakob, Greg Humphreys, Physically Based Rendering: From Theory to Implementation, 3rd edition, Morgan Kaufmann, 2016.

Usability and Relationship to other Modules

• Students with a strong interest in graphical user interfaces are encouraged to also select the Human– Computer Interaction specialization module, which discusses among other things how computer graphics can be used as a component of interactive graphical user interfaces.

Examination Type: Module Examination

Assessment Type: Written examination

Duration: 120 min Weight: 100%

Scope: All intended learning outcomes of the module

7.21 Software Engineering

| Module Name Software Engineering | | | Module Code CO-561 | Level (type) Year 2 (CORE) | СР 7.5 |
|-------------------------------------|-----------------------|------------------------------------|------------------------------|--|-----------------------------|
| Module Component | | | | | |
| Number | Name | | | Туре | СР |
| CO-561-A | Software Engineerin | g | | Lecture | 2.5 |
| CO-561-B | Software Engineerin | g Project | | Project | 5 |
| Module Coordinator | Program Affiliation | | Mandatory Status | | |
| Prof. Dr. Peter Baumann | Computer Science (CS) | | | Mandatory for CS and minor CS Mandatory elective for RIS | |
| Entry Requirements | | | Frequency Annually | Forms of Learni Teaching | ing and |
| Pre-requisites | | Knowledge, Abilities, or Skills | (Spring) | Class attend hours) Independen hours) Developmen (132.5 hours) Exam prepar hours) | t study (10 t work s) |
| | | | Duration | Workload | |
| | | | 1 semester | 187.5 hours | |

Students are expected to be able to develop software using an object-oriented programming language such as C++, and they should have access to a Linux system and associated software development tools.

Content and Educational Aims

This module is an introduction to software engineering and object-oriented software design. The lecture focuses on software quality and the methods to achieve and maintain it in environments of "multi-person construction of multi-version software." Based on their pre-existing knowledge of an object-oriented programming language, students are familiarized with software architectures, design patterns and frameworks, software components and middleware. Unified Modeling Language (UML)-based modelling, and validation by testing. Furthermore, the course addresses the more organizational topics of project management and version control.

The lectures are accompanied by a software project in which students have to develop a software solution to a given problem. The problem is described from the viewpoint of a customer and students working in teams have to execute a whole software project lifecycle. The teams have to create a suitable software architecture and software design, implement the components, and integrate the components. The teams have to ensure that basic quality requirements for the solution and the components are defined and satisfied. The students produce various artifacts such as design documents, source code, test cases and user documentation. All artifacts need to be maintained in a version control system and the commits should allow the instructor and other team members to track in a meaningful way the changes and who has been contributing them.

Intended Learning Outcomes

By the end of this module, students will be able to

- 1. understand and apply object-oriented design patterns;
- 2. read and write UML diagrams;
- 3. contrast the benefits and drawbacks of different software development models;
- 4. design and plan a larger software project involving a team development effort;
- 5. translate requirements formulated by a customer into computer science terminology;
- 6. evaluate the applicability of different software engineering models for a given software development project;
- 7. assess the quality of a software design and its implementation;
- 8. apply tools that assist in the various stages of a software development process;
- 9. work effectively in a team toward the goals of the team.

Indicative Literature

Ian Sommerville: Software Engineering, Pearson, 2010.

Roger Pressman: Software Engineering – a Practitioner's Approach, McGraw-Hill, 2014.

Usability and Relationship to other Modules

Examination Type: Module Component Examinations Module

Component 1: Lecture

Assessment Type: Written examination

Duration: 60 min Weight: 33%

Scope: The first three intended learning outcomes of the module (the lecture module component)

Module Component 2: Project

Assessment Type: Project Assessment

Weight: 66% Scope:

The remaining intended learning outcomes of the module (the project module component)

Completion: To pass this module, the examination of each module component has to be passed with at least 45%.

7.22 Databases

| Module Name Databases | | Module Code | Level (type) Year 2 (CORE) | СР 7.5 |
|---|---|--|--|--------------------------|
| Module Componen | ts | 0-500 | | 7.5 |
| Number | Name | | Туре | СР |
| CO-560-A | Databases | | Lecture | 5 |
| СО-560-В | Databases - Project | Project | 2.5 | |
| Module Coordinator Prof. Dr. Peter Baumann | Program AffiliationComputer Science (CS) | | Mandatory Status Mandatory for CS and minor CS Mandatory elective for RIS | |
| Entry Requirements Pre-requisites | Co-requisites Knowledge, Abilities, or Skills | Frequency Annually (Fall) | Forms of Learning Class attenda Project (97.5) Independent hours) | nce (35 hours) hours) |
| Data Structures | ⊠ None | Duration | , | aration (20 |
| | | 1 semester | 187.5 hours | |

Recommendations for Preparation

Working knowledge of basic data structures, such as trees, is required as well as familiarity with an object-oriented programming language. Basic knowledge of algebra is useful. For the project work, students benefit from having basic hands-on skills using Linux (the server platform in the project).

Content and Educational Aims

This module offers an introduction to databases, with emphasis on practically applicable knowledge and skills. The course starts with conceptual database design using the Entity Relationship (ER) model, followed by the relational model and SQL for querying relations. On that occasion, structures for storing relations on disk are inspected. After that, tuning opportunities are discussed, including Normal Forms, indexing, transaction management, and views, and finally – based on a brief look at Relational Algebra – query processing and optimization in the server. As today databases often are used for Web services an excursion is made to inspect the server side of Web request processing in the context of databases. This in turn prompts security considerations in databases. Concluding the relational part, the travel leads into NoSQL and NewSQL world. This widens the perspective towards data models beyond tables and redefined transaction concepts. Towards the semester end, OLAP datacubes are introduced as a practically important database application with special needs, concepts, and technology.

A hands-on group project complements the theoretical aspects: on a self-chosen topic, teams of 3 – 4 students implement the core of a web-accessible information system using python (or PHP), MariaDB, and Linux, in a guided sequence of homework assignments.

| Intended Learning Outcomes | | | | | | |
|--|--|--|--|--|--|--|
| By the end of this module, students will be able to | | | | | | |
| write SQL queries and understand their evaluation know common tuning methods in relational datab explain the concept of transactions and how to us explain core security and privacy issues in the context | design and normalize schemas for relational databases; write SQL queries and understand their evaluation in a database server; know common tuning methods in relational databases; explain the concept of transactions and how to use transactions in application design; | | | | | |
| describe differences of selected NoSQL data mode describe the concept of datacubes and how datab develop database-backed Web-enabled information | ases can support it; | | | | | |
| Indicative Literature | Shi systems, considering security aspects. | | | | | |
| Hector Garcia-Molina, Jeffrey D. Ullman, Jennifer D. 2008. Elvis C. Foster, Shripad V. Godbole: Database System Miguel Grinberg: Flask Web Development: Develo Jon Duckett: PHP & MySQL: Server-side Web Development | ping Web Applications with Python. O'Reilly, 2018 | | | | | |
| Usability and Relationship to other Modules | | | | | | |
| | mation-hungry society, and given the emphasis on practical aspects, udents can apply their knowledge in the Software Engineering module. nodule. | | | | | |
| Examination Type: Module Component Examinations | | | | | | |
| Module Component 1: Lecture | | | | | | |
| Assessment Type: Written examination | Duration: 120 min Weight: 67% | | | | | |
| Scope: Intended learning outcomes #1 - #8 | | | | | | |
| Module Component 2: Project | | | | | | |
| Assessment Type: Project assessment | Waight, 220/ | | | | | |
| Scope: Intended learning outcome #9 | Weight: 33% | | | | | |
| Completion: To pass this module, the examination of each module component has to be passed with at least 45%. | | | | | | |

7.23 Digital Design

| Module Name | | Module Code | Level (type) | СР | | |
|---|---|--|-----------------------|--------------|--|--|
| Digital Design | | CA-S-ECE-803 | Year 3 | 5 | | |
| | | | (Specialization) | | | |
| Module Components | 5 | | | | | |
| Number | Name | | Туре | СР | | |
| CA-ECE-803 | Digital Design | | Lecture/Lab | 5 | | |
| Module Coordinator | Program Affiliation | | Mandatory Status | | | |
| Dr. Fangning Hu | Electrical and Computer Engineering (ECE) | Mandatory elective for ECE, RIS and CS | | | | |
| Entry Requirements | | Frequency | | rning and | | |
| Pre-requisites | | Annually (Fall) | Teaching | | | |
| Fielequisites | Co-requisites Knowledge, Abilities, or | | Lecture/Lab (| 35 hours) | | |
| 🛛 None | Skills | | Private study | | | |
| | ⊠ None | | hours) | | | |
| | | Duration | Workload | | | |
| | | 1 semester | 125 hours | | | |
| Recommendations for | Preparation | | | | | |
| | are themselves with books like "Brent E. Nelson, De re Design Using VHDL, A John Wiley & Sons, Inc, P | | ems, 2005" and "Pon | g | | |
| | | | | | | |
| | f digital system design is towards hardware descrip | | | | | |
| | rdware constructs. The module provides a sound i multiplexers, decoders, flip-flops and registers as | | | | | |
| | ents. Methods and principle of designing comp | | | - | | |
| hierarchical design, | pipelined design, RTL design methodology and pa | rameterized design | will also be introduc | ed. Students | | |
| | programming FPGA boards to realize small digit | - | | | | |
| | Id be adders, multiplexers, control units, multipot for the module, the students should be able to designate the students and the students are able to designate and the st | | | | | |
| (OAN). At the church | | sind simple digital sy | | TT GA board. | | |
| Intended Learning Out | | | | | | |
| - | nodule, students will be able to | | | | | |
| , | | andard building blo | cks and components: | | | |
| understand the principle of digital system design based on standard building blocks and components; design a complex digital system; | | | | | | |
| understand the limitations of a given hardware platform (here FPGAs), modify algorithms where | | | | | | |
| | and structure them suitably in order to optimize | performance and co | omplexity; | | | |
| | al development system; | | | | | |
| 5. program in | | | | | | |
| 6. program a | n FPGA board. | | | | | |
| Indicative Literature | | | | | | |
| Brent E. Nelson, D | esigning Digital Systems with SystemVerilog, 20 |)18, ISBN-13: 978-1 | 1980926290 Pong P. | Chu, | | |
| | | | | | | |

RTL Hardware Design Using VHDL, Wiley-IEEE Press, 2006, ISBN-13: 978-0471720928

Usability and Relationship to other Modules

• This module introduces how to design digital systems and how to realize them on a FPGA board which could also serve as a specialization module for students from Computer Science and Robotics and Intelligent Systems.

Examination Type: Module Examination

Assessment Type: Written examination Scope: All intended learning outcomes of the module Duration: 120 min Weight: 100%

7.24 PCB Design and Measurement Automation

| Module Name | | | Module Code | Level (type) | СР |
|--|---|---|-------------------|---|-------------|
| PCB Design and Measurement Automation CO-527 | | | Year 2 (CORE) | 5 | |
| Module Component | s | | | | |
| Number | Name | | | Туре | СР |
| CO-527-A | PCB Design and | Measurement Automation | | Lab | 5 |
| Module Coordinator | Program Affiliation | ı | | Mandatory Status | |
| Prof. DrIng. Werner Henkel | Electrical and Computer Engineering (ECE) | | | Mandatory for ECE Mandatory elective for RIS | |
| Entry | | | Frequency | Forms of L | earning and |
| Requirements | | | | Teaching | 0 |
| | | | Annually (Spring) | | |
| Pre-requisites | Co-requisites | Knowledge, Abilities, or Skills | | Lab (59.5 hdPrivate Stud | - |
| ⊠ General Electrical | 🛛 None | Knowledge of Fourier series and | | hours) | |
| Engineering I | | transforms | Duration | Workload | |
| ⊠ General Electrical Engineering II | | Basic knowledge of electronics components and | 1 semester | 125 hours | |
| OR | | circuits • Matlab | | | |
| Mathematical and | | | | | |
| Physical | | | | | |
| Foundations of Robotics I & II | | | | | |
| Recommendations fo | | | | <u> </u> | |

Recommendations for Preparation

Download material from corresponding Web pages and get to know the tasks and how the tools and equipment works.

Content and Educational Aims

The module (lab) covers mainly two aspects that are seen to be important for employability. One share of the lab deals with measurement automation. Similar tasks, one also finds in industrial automation or monitoring, sometimes using the same tools. Students will learn to use Matlab and Labview for measurement automation tasks. In there, students will also get acquainted with more advanced measurement equipment, like high-end digital scopes, network, and spectrum analyzers. The students will measure standard telephone cables in their properties, which will require a treatment of transmission line theory and transformers/baluns. These theoretical aspects will also be covered.

The second major aspect handled in the lab makes students aware that electrical/electronic components have non-ideal behaviors, e.g., that a capacitor can act as an inductor in some frequency range. It makes students also aware of the problems in selecting the right component for a certain function inside a circuit, caring not just for the frequency range and the variation of properties with frequency, but also power, current, and voltage limits. Then, a typical circuit design path will be taught, starting from schematics to placement of components and routing. Important aspects of printed circuit board design are treated, like how analog and digital power supplies have to be realized, how mass connections should look like, what measures have to be taken to block unwanted signal coupling is avoided, e.g., blocking capacitors, star-like power supply wiring.

Students also practice scientific writing in line with scientific writing rules as a preparation for their BSc thesis.

| Intended Learni | ing Outcomes | | | | | |
|----------------------|--|--|--|--|--|--|
| By the end of | f this module, students should be able to | | | | | |
| 1. | use vector network analyzers, spectrum analyzers, and m | ore advanced digital scopes; | | | | |
| 2. | 2. learn how to program with LabVIEW; | | | | | |
| 3. | 3. remotely control measurement equipment using Matlab or LabVIEW; | | | | | |
| 4. | 4. describe principles of remote control; | | | | | |
| 5. | | | | | | |
| 6. | . measure and determine line parameters; | | | | | |
| 7. | taking non-ideal behavior of passive and active compone | ents into account and be able to select | | | | |
| | components according to their parameters and limitation | ons; | | | | |
| 8. | design printed circuit boards (PCB) with typical tools and | d a typical design cycle consisting of | | | | |
| | schematics, placement, and routing; | | | | | |
| 9. | design analog and digital power routes, shielding ground | connections, use measures to block | | | | |
| | unwanted ingress and coupling; | | | | | |
| 10. | . organize work contributions of group members in the lab | and in reporting; | | | | |
| 11. | . write reports in line with scientific writing rules as a prep | paration for their BSc thesis. | | | | |
| Usability and Re | Relationship to other Modules | | | | | |
| app forn • The | ving learned to use Matlab in earlier modules, mostly for s plication and provides a view into graphical programming as m of Simulink e module prepares students for a thesis with PCB design as rves as a mandatory elective 3 rd year Specialization module | sanother option which they have seen earlier in the pects. | | | | |
| Indicative Litera | | | | | | |
| Hank Zumbah | hlen Ed., Basic Linear Design, Analog Devices, 2007. Walt J | Jung | | | | |
| Ed., Op Amp A | Applications, Analog Devices, 2005. | | | | | |
| Tim Williams, | , The Circuit Designer's Companion, 3 rd ed., Newnes, 2012. | | | | | |
| National Instru | ruments, LabVIEW, Getting Started with LabVIEW, 2007. | | | | | |
| Examination Ty | ype: Module Examination | | | | | |
| Assessment C | Assessment Component 1: Written examination Duration: 120 min Weight: 50% | | | | | |
| Scope: Intend | ded learning outcomes of the lecture/theory component (4 | , 5, 7, 9). | | | | |
| Assessment C | | ngth: 5-10 pages per experiment session eight: 50% | | | | |
| Scope: Intend | ded learning outcomes of the lab (1-3, 6-11). | | | | | |
| Completion: | This module is passed with an assessment-component weig | ghted average grade of 45% or higher. | | | | |

7.25 Information Theory

| Module Name Information Theory | | | Module Code CO-525 | Level (type) Year 2 (CORE) | СР 5 |
|-----------------------------------|---------------------|---|-----------------------|---|---------------------------|
| Module Component | S | | | | |
| Number | Name | | | Туре | СР |
| CO-525-A | Information The | ory | | Lecture | 5 |
| Module Coordinator | Program Affiliation | | | Mandatory Status | |
| Prof. DrIng. Werner Henkel | Electrical an | nd Computer Engineering (ECE) | | Mandatory for ECE Mandatory elective for CS, PHDS and RIS | |
| Entry Requirements | | | Frequency | Forms of I Teaching | earning and |
| Pre-requisites | | | Annually (Spring) | | |
| | Co-requisites | Knowledge, Abilities, or Skills | | Lectures (3)Private Stud | 5 hours) dy (90 hours) |
| 🗵 None | | Constants | Duration | Workload | |
| | ⊠ None | Signals and Systems contents, | Duration | workidad | |
| | | such as DFT and convolution Notion of probability, combinatorics basics as taught in Methods module "Probability and Random Processes" | 1 semester | 125 hours | |

Recommendations for Preparation

Some basic knowledge of communications and sound understanding of probability is recommended. Hence, it is strongly advised to take the methods and skills course Probability and Random Processes prior to this module. Nevertheless, probability basics will also be revised within the module.

Content and Educational Aims

Information theory serves as the most important foundation for communication systems. The module provides an analytical framework for modeling and evaluating point-to-point and multi-point communication. After a short rehearsal of probability and random variables and some excursion to random number generation, the key concept of information content of a signal source and information capacity of a transmission medium are precisely defined, and their relationships to data compression algorithms and error control codes are examined in detail. The module aims to install an appreciation for the fundamental capabilities and limitations of information transmission schemes and to provide the mathematical tools for applying these ideas to a broad class of communications systems.

The module contains also a coverage of different source-coding algorithms like Huffman, Lempel-Ziv-(Welch), Shannon-Fano-Elias, Arithmetic Coding, Runlength Encoding, Move-to-Front transform, PPM, and Context Tree Weighting. In Channel coding, finite fields, some basic block and convolutional codes, and the concept of iterative decoding will be introduced. Aside from source and channel aspects, an introduction to security is given, including public-key cryptography. Information theory is a standard module in every communications-oriented Bachelor's program.

Intended Learning Outcomes

By the end of this module, students should be able to

- 1. explain what is understood as the information content of data and the corresponding limits of data compression algorithms;
- 2. design and apply fundamental algorithms in data compression;
- 3. explain the information theoretic limits of data transmission;
- 4. apply the mathematical basics of channel coding and cryptography;
- 5. implement some channel coding schemes;
- 6. differentiate the principles of encryption and authentication schemes and implement discussed procedures.

Indicative Literature

Thomas M. Cover, Joy A. Thomas, Elements of Information Theory, 2nd ed., Wiley, Sept. 2006. David

Salomon, Data Compression, The Complete Reference, 4th ed., Springer, 2007.

Usability and Relationship to other Modules

- Although not a mandatory prerequisite, this module is ideally taken before Coding Theory (CA-ECE-802)
- All communications-related modules are naturally based on information theory
- Students from Computer Science or related programs, also students taking Bio-informatics modules, profit from information-theoretic knowledge and source coding (compression) algorithms. Students from Computer Science would also be interested in the algebraic basics for error-correcting codes and cryptology, fields which area also introduced shortly.
- Serves as a mandatory elective 3rd year Specialization module for CS and RIS major students.

Examination Type: Module Examination

Assessment Type: Written examination

Duration: 120 min Weight: 100%

Scope: All intended learning outcomes of the module.

7.26 Stochastic Processes

| Module Name | | | Module Code | Level (type) | СР |
|---|--|--|---|---|---|
| Stochastic Processes | | | CA-S-MMDA-805 | Year 2/3 (Specialization) | 5 |
| Module Components | | | | | |
| Number | Name | | | Туре | СР |
| CA-MMDA-805 | Stochastic Process | es | | Lecture | 5 |
| Module Coordinator | Program Affiliation | 1 | | Mandatory Status | 5 |
| Dr. Keivan Mallahi Karai | Mathematics | , Modeling and Data Analytics | (MMDA) | Mandatory electiv MMDA, and RIS | ve for |
| Entry Requirements | | | Frequency | Forms of Learning | g and |
| Pre-requisites ⊠ Matrix Algebra and | Co-requisites ⊠None | Knowledge, Abilities, or Skills | Biennially (Spring) | Lectures (35 Private study | |
| Advanced Calculus II and Probability and | | None beyond formal pre-requisites | Duration | Workload | |
| Random Processes | | | 1 semester | 125 hours | |
| Recommendations for I | Preparation | | | | |
| Review of Probability ar | nd Analysis | | | | |
| probability spaces and c Cantelli Lemma, Kolmog large numbers, and the Markov chains, Galton-N | n introduction to the continues by providing gorov's zero-one law Central limit theore Watson trees, and the he application of Ma | e theory of stochastic processe ng a rigorous treatment of topi , random variables, expected v m. More advanced topics that le Wiener process. Several rele arkov chains to sampling proble athematical finance. | ics such as the indep value and variance, t will follow include fi evant applications th | endence of events a he weak and strong nite and countable at will be discussed | and Borel- ; laws of state are |
| Intended Learning Outo By the end of the modu | | ble to | | | |
| develop a analyze t | ability to use stochas he definition of basi e and design methoo | f basic stochastic methods; stic processes to model real-wo c probabilistic objects, and the ds and algorithms for solving a | ir numerical feature | s; | ochastic |
| | | Examples. Cambridge: Cambrid obability and Random Process | | | |

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment Type: Written examination

Scope: All intended learning outcomes of this module

Completion: To pass this module, the examination has to be passed with at least 45%.

Duration: 120 min Weight: 100%

7.27 Stochastic Modeling and Financial Mathematics

| Module Name Stochastic Modeling | g and Financial Mathematic | S | Module Code CA-S-MMDA-803 | Level (type) Year 2 and 3 (Specialization) | СР 5 |
|--|--|--|--|---|--|
| Module Component | ts | | | | |
| Number | Name | | | Туре | СР |
| CA-MMDA-803 | Stochastic Modeling and | Financial Mathematics | | Lecture | 5 |
| Module | Program Affiliation | | | Mandatory Statu | s |
| Coordinator Prof. Dr. Sören | Mathematics, | Modeling, and Data Analytic | s (MMDA) | Mandatory electi PHDS, SDT and RI | |
| Petrat Entry Requirements | | | Frequency | Forms of Learnin | g and Teaching |
| Pre-requisites | Sk | nowledge, Abilities, or kills ood command of Calculus, | Annually (Spring/Fall) | Lectures (35 Private Study | |
| ☑ Matrix Algebra and Advanced Calculus I & II | Li | near Algebra, and basic robability basic Python | Duration | Workload | |
| | | ogramming | 1 semester | 125 hours | |
| Mathematics, so th Mathematical Econo interactive computa Topics include a sho stochastic integrals a introduction to time Uhlenbeck processe physics and other a | irst hands-on introduction nat this module plays a co- omics. The module is taugh ition and computer experim- ort introduction to the basic and ODEs, Ito's Lemma, Mo- e series analysis, parameter es, and nonlinear Stochasti areas of mathematics are | to stochastic modeling. Exertral role in the education at as an integrated lecture-inents. c notions of financial mather porte-Carlo methods, finite d estimation, and calibration. ic Partial Differential Equat made. Students will prog porithms to real data whener | n of students intere ab, where short theo matics, binomial tree ifferences solutions, Towards the end, the ions are discussed, a ram and explore all | sted in Quantitativ pretical units are int e models, discrete B the Black-Scholes ec Fokker-Planck equa and connections to | re Finance and erspersed with rownian paths quation, and ar ation, Ornstein applications ir |
| Intended Learning C Upon completion of | Dutcomes this module, students will | be able to | | | |
| designation analy write integration comp | n, conduct, and interpret concepts of fine type the basic concepts of fine computer code for basic rals and time series analysis pare their programs and pres | deterministic and stochastic ontrolled in-silico scientific e nancial mathematics and the financial calculations, binor s; edictions in the context of re- sion control system for colla | experiments; ir role in finance; mial trees, stochastic al data; | | |
| Indicative Literature | - | | | | |
| • YD. Lyuu University | | ing and Computation - Princ | iples, Mathematics, A | Algorithms. Cambrid | lge: Cambridg |

- J.C. Hull (2015). Options, Futures and other Derivatives, 9th edition. New York: Pearson.
- A. Etheridge (2002). A Course in Financial Calculus. Cambridge: Cambridge University Press.
- D.J. Higham (2001). An Algorithmic Introduction to Numerical Simulation of Stochastic Differential Equations, SIAM Rev. 43(3):525-546.
- D.J. Higham (2004). Black-Scholes Option Valuation for Scientific Computing Students, Computing in Science & Engineering 6(6):72-79.

Usability and Relationship to other Modules

- This module is part of the core education in Mathematics, Modeling and Data Analytics.
- It is also valuable for students in Physics and Data Science, Computer Science, Data Engineering, RIS, and ECE, either as part of a minor in Mathematics, or as an elective module.

Examination Type: Module Examination

Assessment Type: Portfolio Assessment

Weight: 100%

Scope: All intended learning outcomes of this module

7.28 Operations Research

| Module Name | | Module Code | Level (type) | СР |
|---|---|---|---|------------------------------------|
| Operations Research | | CO-583 | Year 2 (CORE) | 5 |
| Module Components | | | | |
| Number | Name | | Туре | СР |
| CO-583-A | Operations Research | | Lecture | 5 |
| Module Coordinator | Program Affiliation | | Mandatory Status | |
| Dr. Stanislav Chankov | Industrial Engineering & Management (I | IEM) | Mandatory for IEM elective for RIS | Mandatory |
| Entry Requirements Pre-requisites | Co-requisites Knowledge, Abilities, o Skills | Duration | Teaching Lectures (35 hd) Private Study (9) Workload | |
| ⊠ None | None Basic spreadsheet software skills (e.g. MS Excel) basic calculus and matrix algebra basic knowledge in logistics | 1 semester | 125 hours | |
| Recommendations for F | | 1 | | |
| Revise basic calculus, | matrix algebra and spreadsheet software function | 15. | | |
| Content and Education | al Aims | | | |
| organizations. By em operations research concerned with dete (of loss, risk, or cost) and the use of quant | is an interdisciplinary mathematical science t ploying techniques such as mathematical modelir finds optimal or near-optimal solutions to comp rmining the maximum (of profit, performance, or y of some real-world objective. This module intro- citative methods and techniques for effective deci | ng, statistical analysi lex decision-making rield) or the minimun duces students to th | s, and mathematical problems. Operatio 1 | l optimization, ons Research is |
| Intended Learning Outc | omes | | | |
| calculate o methods; design mat apply techn problems resolve cor | hematical models for business problems; niques such as linear programming, dynamic progr | ramming or stochast | ic programming to s | olve business |
| Indicative Literature | | | | |
| Hillier, F. S. & Lieberr | nan, G.J. (2009). Introduction to Operations Resea | arch. McGraw-Hill. N | lew York, NY. | |
| Usability and RelationslServes as a | hip to other Modules 3 rd year Specialization module for major students i | in RIS | | |

Examination Type: Module Examination

Assessment Type: Written examination

Duration: 120 minutes Weight: 100 %

Scope: All intended learning outcomes of the module.

7.29 Web Application Development

| Module Name | | Module Code | Level (type) | СР |
|---|---|---|---|----------------------------------|
| Web Application De | evelopment | CA-S-CS-804 | Year 3 (Specialization) | 5 |
| Module Component | 5 | | | |
| Number | Name | | Туре | СР |
| CA-CS-804-A | Web Application Development | | Lecture | 2.5 |
| CA-CS-804-B | Web Application Development - Project | | Project | 2.5 |
| Module Coordinator | Program Affiliation | | Mandatory Status | |
| Prof. Dr. Jürgen Schönwälder | Computer Science (CS) | | Mandatory elect and RIS | tive for CS |
| Entry Requirements Pre-requisites Databases and Web Services | Co-requisites Knowledge, Abilities, or Skills ⊠ None | Frequency Annually (Spring) Duration | Forms of Learn Teaching Class attend (17.5 hours) Private stud hours) Project work hours) Exam prepare (17.5 hours) Workload | ance y (40 < (50 ration |
| | | 1 semester | 125 hours | |
| Recommendations for None Content and Educatio | | | | |
| runs in a web brows | s a client-server computer program where the clie ser or as an app running on a mobile device such as ication logic and data storage is realized by a serv | a smart phone or a | a tablet. A key charac | teristic is th |
| interactive user inter | es on the client side of web application and intro erfaces and client side logic. It builds on the modul ts and server side logic of web applications. | - | | |
| and frameworks that and frameworks be | ts of a lecture and an associated project. The lec at are widely used for implementing the client side of uilt on top of them. In the project component, si accessible web services. | f web applications s | uch as Java, Kotlin, Sw | ift, JavaScri |
| Intended Learning Ou | tcomes this module, students will be able to | | | |

By the end of this module, students will be able to

- $1. \quad \text{explain the document object model behind HTML and its relation to CSS;}$
- 2. discuss the principles and basic mechanisms of reactive website design;
- 3. analyze the interactions between web applications and web services.

- 4. use languages such as Java, Kotlin, or Swift to implement mobile web applications;
- 5. use web standards such as HTML, CSS, and JavaScript to implement web applications running in standard web browsers.

Indicative Literature

Stoyan Stefanov: JavaScript Patterns, O'Reilly Media, 2010.

Alexey Soshin: Hands-on Design Patterns with Kotlin, Packt Publishing, 2018.

Alex Banks, Eve Porcello: Learning React: Functional Web Development.with React and Flux, O'Reilly, 2017.

Usability and Relationship to other Modules

Examination Type: Module Component Examinations Module

Component 1: Lecture

Assessment Type: Written examination

Scope: First group of intended learning outcomes of the module

Module Component 2: Project

Assessment Type: Project Assessment

Scope: Second group of intended learning outcomes of the module

Completion: To pass this module, the examination of each module component has to be passed with at least 45%.

Duration: 120 min Weight: 50%

Weight: 50%

7.30 Parallel and Distributed Computing

| Parallel and Distribut | | Module Code | Level (type) | СР |
|--|---|--|--|--|
| | ed Computing | MDE-CS-02 | Year 2 (Elective) | 5 |
| Module Components | | | | |
| Number | Name | | Туре | СР |
| MDE-CS-02 | Parallel and Distributed Computing | | Lecture | 5 |
| Module Coordinator | Program Affiliation | | Mandatory Status | - |
| Prof. Dr. Stefan Kettemann | MSc Data Engineering (DE) | | Mandatory electiv CSSE (MSc), RIS (E CS (BSc) | |
| Entry Requirements | | Frequency | Forms of Learnir Teaching | ng and |
| Pre-requisites | Co-requisites Knowledge, Abilities, or Skills ⊠ None ■ Basic | Annually (Fall) | Lecture hours) | e (35 e study (90 |
| | knowledge in C/C++ • Mandatory proficiency in Python | Duration 1 semester | Workload 125 hours | |
| In the recent years, th | | | | i processin |
| This module aims at p parallel computing, w SIMD, SIMT), get to k aim at understanding knowledge will then b (Spark / Hadoop Mag Facto standards for Bi at developing the nece | | elization models (shar for high performance ak vs. strong scaling, I computing, where di yment infrastructures these technologies fro | ed-memory,distribut dataanalysis (OpenM Amdahl's law).This f stributed processing , are in the process to | n tradition ed-memor P / MPI) an undament frameworl become D |
| This module aims at p parallel computing, w SIMD, SIMT), get to k aim at understanding knowledge will then k (Spark / Hadoop Map Facto standards for Bi at developing the neck knowledge to carry ou | we aim to develop notions for different parall now appropriate programming methodologies of g performance and scalability in this field (weat be carried over to recent developments in cloud pReduce / Dask), based on appropriated deplo ig Data processing and analysis. We will approach essary ut scalable machine learning and data processing | elization models (shar for high performance ak vs. strong scaling, I computing, where di yment infrastructures these technologies fro | ed-memory,distribut dataanalysis (OpenM Amdahl's law).This f stributed processing , are in the process to | n tradition ed-memor P / MPI) an undament frameworl become D |
| This module aims at p parallel computing, w SIMD, SIMT), get to k aim at understanding knowledge will then b (Spark / Hadoop Map Facto standards for Bi at developing the neck knowledge to carry ou Intended Learning Outco | we aim to develop notions for different parall now appropriate programming methodologies of g performance and scalability in this field (weat be carried over to recent developments in cloud pReduce / Dask), based on appropriated deplo ig Data processing and analysis. We will approach essary ut scalable machine learning and data processing | elization models (shar for high performance ak vs. strong scaling, I computing, where di yment infrastructures these technologies fro | ed-memory,distribut dataanalysis (OpenM Amdahl's law).This f stributed processing , are in the process to | n tradition ed-memor P / MPI) an undament frameworl become D |
| This module aims at p parallel computing, w SIMD, SIMT), get to k aim at understanding knowledge will then k (Spark / Hadoop Map Facto standards for Bi at developing the neck knowledge to carry ou Intended Learning Outco By the end of this mod 1. understand t 2. explain and a 3. describe and 4. Understand 5. use distribut calculations | we aim to develop notions for different parall now appropriate programming methodologies of g performance and scalability in this field (weat be carried over to recent developments in cloud pReduce / Dask), based on appropriated deplo ig Data processing and analysis. We will approach essary ut scalable machine learning and data processing omes | elization models (shar for high performance ak vs. strong scaling, d computing, where di yment infrastructures these technologies fro g on Big Data. ls (shared-/distributed nMP / MPI) trong scaling,) ting Reduce / Dask) for sca | ed-memory, distribut dataanalysis (OpenM Amdahl's law).This f stributed processing , are in the process to m a practical point of w memory, SIMD, SIMT | n tradition ed-memor P / MPI) an frameworl b become D view and ai |
| This module aims at p parallel computing, w SIMD, SIMT), get to k aim at understanding knowledge will then k (Spark / Hadoop Map Facto standards for Bi at developing the neck knowledge to carry ou Intended Learning Outco By the end of this mod 1. understand t 2. explain and a 3. describe and 4. Understand 5. use distribut calculations | we aim to develop notions for different parall now appropriate programming methodologies of g performance and scalability in this field (weat be carried over to recent developments in cloud pReduce / Dask), based on appropriated deplo ig Data processing and analysis. We will approach essary ut scalable machine learning and data processing omes dule, students should be able to theory and fundamentals of parallelization mode apply parallel programming methodologies (Open analyze performance and scalability (weak vs. st basic principles of distributed and cloud compu- ted processing frameworks (Spark / Hadoop Map | elization models (shar for high performance ak vs. strong scaling, d computing, where di yment infrastructures these technologies fro g on Big Data. ls (shared-/distributed nMP / MPI) trong scaling,) ting Reduce / Dask) for sca | ed-memory, distribut dataanalysis (OpenM Amdahl's law).This f stributed processing , are in the process to m a practical point of w memory, SIMD, SIMT | n tradition ed-memor P / MPI) ar framewor b become E view and ai |
| This module aims at p parallel computing, w SIMD, SIMT), get to k aim at understanding knowledge will then b (Spark / Hadoop Map Facto standards for Bi at developing the neck knowledge to carry ou Intended Learning Outco By the end of this mod 1. understand t 2. explain and a 3. describe and 4. Understand 5. use distribut calculations 6. develop scall | we aim to develop notions for different parall now appropriate programming methodologies of g performance and scalability in this field (weat be carried over to recent developments in cloud pReduce / Dask), based on appropriated deplo ig Data processing and analysis. We will approach essary ut scalable machine learning and data processing omes dule, students should be able to theory and fundamentals of parallelization mode apply parallel programming methodologies (Open analyze performance and scalability (weak vs. st basic principles of distributed and cloud compu- ted processing frameworks (Spark / Hadoop Map | elization models (shar for high performance ak vs. strong scaling, d computing, where di yment infrastructures these technologies fro g on Big Data. ls (shared-/distributed nMP / MPI) trong scaling,) ting Reduce / Dask) for sca | ed-memory, distribut dataanalysis (OpenM Amdahl's law).This f stributed processing , are in the process to m a practical point of w memory, SIMD, SIMT | n tradition ed-memor P / MPI) ar framewor b become I view and ai |

Z. Radtka, D. Miner, Hadoop with Python. Hadoop with Python, O'Reilly.

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment Type: Written Exam

Duration: 120 minutes Weight: 100%

Scope: All intended learning outcomes of this module.

7.31 Internship / Startup and Career Skills

| Module Name | | | Module Code | Level (type) | СР |
|---|---------------------|---|--|--|---|
| Internship / Startup | and Career Skills | | CA-INT-900 | Year 3 (CAREER) | 15 |
| Module Components | S | | | | |
| Number | Name | | | Туре | СР |
| CA-INT-900-0 | Internship | | | Internship | 15 |
| Module Coordinator | Program Affiliation | n | | Mandatory Status Mandatory for all u | undorgraduate |
| Clémentine Senicourt & Dr. Tanja Woebs (SCS Organization); SPC / Faculty Startup Coordinator (Academic responsibility) | CAREER mc | odule for undergraduate study pi | ograms | study programs ex | - |
| Entry Requirements Pre-requisites | Co-requisites | Knowledge, Abilities, or Skills | Frequency Annually (Spring/Fall) | Forms of Learning ar Internship/Sta Internship ev Seminars, inf | art-up ent o-sessions, |
| ⊠ at least 15 CP from CORE | ⊠ None | Information provided on CSC pages (see | | workshops an events Self-study, reconline tutoria | adings, |
| modules in the major | | below) Major specific knowledge and skills | Duration 1 semester | Workload 375 Hours consist Internship (3 Workshops (3 Internship Ev Self-study (32 | 08 hours) 33 hours) ent (2 hours) |

• Please see the section "Knowledge Center" at JobTeaser Career Center for information on Career Skills seminar and workshop offers and for online tutorials on the job market preparation and the application process. For more information, please see https://constructor.university/student-life/career-services

• Participating in the internship events of earlier classes

Content and Educational Aims

The aims of the internship module are reflection, application, orientation, and development: for students to reflect on their interests, knowledge, skills, their role in society, the relevance of their major subject to society, to apply these skills and this knowledge in real life whilst getting practical experience, to find a professional orientation, and to develop their personality and in their career. This module supports the programs' aims of preparing students for gainful, qualified employment and the development of their personality.

The full-time internship must be related to the students' major area of study and extends lasts a minimum of two consecutive months, normally scheduled just before the 5th semester, with the internship event and submission of the internship report in the 5th semester. Upon approval by the SPC and SCS, the internship may take place at other times, such as before teaching starts in the 3rd semester or after teaching finishes in the 6th semester. The Study Program Coordinator or their faculty delegate approves the internship a priori by reviewing the tasks in either the Internship Contract or Internship Confirmation from the respective internship institution or company. Further regulations as set out in the Policies for Bachelor Studies apply. Students will be gradually prepared for the internship in semesters 1 to 4 through a series of mandatory information sessions,

seminars, and career events. The purpose of the Career Services Information Sessions is to provide all students with basic facts about the job market in general, and especially in Germany and the EU, and services provided by the Student Career Support.

In the Career Skills Seminars, students will learn how to engage in the internship/job search, how to create a competitive application (CV, Cover Letter, etc.), and how to successfully conduct themselves at job interviews and/or assessment centers. In addition to these mandatory sections, students can customize their skill set regarding application challenges and their intended career path in elective seminars.

Finally, during the Career Events organized by the Student Career Support (e.g. the annual Constructor Career Fair and single employer events on and off campus), students will have the opportunity to apply their acquired job market skills in an actual internship/job search situation and to gain their desired internship in a high-quality environment and with excellent employers.

As an alternative to the full-time internship, students can apply for the StartUp Option. Following the same schedule as the fulltime internship, the StartUp Option allows students who are particularly interested in founding their own company to focus on the development of their business plan over a period of two consecutive months. Participation in the StartUp Option depends on a successful presentation of the student's initial StartUp idea. This presentation will be held at the beginning of the 4th semester. A jury of faculty members will judge the student's potential to realize their idea and approve the participation of the students. The StartUp Option is supervised by the Faculty StartUp Coordinator. At the end of StartUp Option, students submit their business plan. Further regulations as outlined in the Policies for Bachelor Studies apply.

The concluding Internship Event will be conducted within each study program (or a cluster of related study programs) and will formally conclude the module by providing students the opportunity to present on their internships and reflect on the lessons learned within their major area of study. The purpose of this event is not only to self-reflect on the whole internship process, but also to create a professional network within the academic community, especially by entering the Alumni Network after graduation. It is recommended that all three classes (years) of the same major are present at this event to enable networking between older and younger students and to create an educational

environment for younger students to observe the "lessons learned" from the diverse internships of their elder fellow students

Intended Learning Outcomes

By the end of this module, students should be able to

- 1. describe the scope and the functions of the employment market and personal career development;
- apply professional, personal, and career-related skills for the modern labor market, including selforganization, initiative and responsibility, communication, intercultural sensitivity, team and leadership skills, etc.:
- 3. independently manage their own career orientation processes by identifying personal interests, selecting appropriate internship locations or start-up opportunities, conducting interviews, succeeding at pitches or assessment centers, negotiating related employment, managing their funding or support conditions (such as salary, contract, funding, supplies, work space, etc.);
- 4. apply specialist skills and knowledge acquired during their studies to solve problems in a professional environment and reflect on their relevance in employment and society;
- 5. justify professional decisions based on theoretical knowledge and academic methods;
- 6. reflect on their professional conduct in the context of the expectations of and consequences for employers and their society;
- 7. reflect on and set their own targets for the further development of their knowledge, skills, interests, and values;
- 8. establish and expand their contacts with potential employers or business partners, and possibly other students and alumni, to build their own professional network to create employment opportunities in the future;
- 9. discuss observations and reflections in a professional network.

Indicative Literature

Not specified

Usability and Relationship to other Modules

• This module applies skills and knowledge acquired in previous modules to a professional environment and provides an opportunity to reflect on their relevance in employment and society. It may lead to thesis topics.

Examination Type: Module Examination

Assessment Type: Internship Report or Business Plan and Reflection Scope: All intended learning outcomes Length: approx. 3.500 words Weight: 100%

7.32 Bachelor Thesis and Seminar

| Module Name | | | Module Code | Level (type) | СР |
|---|-------------------------|--|---------------------------------------|---|------------------|
| Bachelor Thesis and | d Seminar RIS | | CA-RIS-800 | Year 3 (CAREER) | 15 |
| Module Components | S | | | | |
| Number | Name | | | Туре | СР |
| CA-RIS-800-T | Thesis RIS | | | Thesis | 12 |
| CA-RIS-800-S | Thesis Seminar F | RIS | | Seminar | 3 |
| Module Coordinator | Program Affiliation | n | | Mandatory Status | 3 |
| Study Program Chair | • All undergra | aduate programs | | Mandatory undergraduate p | for a rograms |
| Entry Requirements Pre-requisites Yere-requisites Yere-requisites | Co-requisites ⊠ None | Knowledge, Abilities, or Skills • comprehensive | Frequency Annually (Spring) | Forms of Learn Teaching • Self-study/ (350 hours | lab work) |
| must have taken and successfully passed a total of at least 30 CP from advanced modules, and of those, at least 20 CP from advanced modules in the major. | | knowledge of the subject and deeper insight into the chosen topic; ability to plan and undertake work independently; skills to identify and critically review literature. | Duration 14-week lecture period | Seminars (: Workload 375 hours | 25 hours) |
| | a or a topic of inte | rest and discuss this with your p ding a research plan to ensure tir | | l or in a timely manne | er. |

• Ensure you possess all required technical research skills or are able to acquire them on time.

• Review the University's Code of Academic Integrity and Guidelines to Ensure Good Academic Practice.

Content and Educational Aims

This module is a mandatory graduation requirement for all undergraduate students to demonstrate their ability to address a problem from their respective major subject independently using academic/scientific methods within a set time frame. Although supervised, this module requires students to be able to work independently and systematically and set their own goals in exchange for the opportunity to explore a topic that excites and interests them personally and that a faculty member is interested in supervising. Within this module, students apply their acquired knowledge about their major discipline and their learned skills and methods for conducting research, ranging from the identification of suitable (short-term) research projects, preparatory literature searches, the realization of discipline-specific research, and the documentation, discussion, interpretation, and communication of research results.

This module consists of two components, an independent thesis and an accompanying seminar. The thesis component must be supervised by a Constructor University faculty member and requires short-term research work, the results of which must be documented in a comprehensive written thesis including an introduction, a justification of the methods, results, a discussion of the results, and a conclusion. The seminar provides students with the opportunity to practice their ability to present, discuss, and justify their and other students' approaches, methods, and results at various stages of their research in order to improve their academic writing, receive and reflect on formative feedback, and therefore grow personally and professionally.

Intended Learning Outcomes

On completion of this module, students should be able to

- 1. independently plan and organize advanced learning processes;
- 2. design and implement appropriate research methods, taking full account of the range of alternative techniques and approaches;
- 3. collect, assess, and interpret relevant information;
- 4. draw scientifically-founded conclusions that consider social, scientific, and ethical factors;
- 5. apply their knowledge and understanding to a context of their choice;
- 6. develop, formulate, and advance solutions to problems and debates within their subject area, and defend these through argument;
- 7. discuss information, ideas, problems, and solutions with specialists and non-specialists.

Indicative Literature

Justin Zobel, Writing for Computer Science, 3rd edition, Springer, 2015.

Usability and Relationship to other Modules

• This module builds on all previous modules in the undergraduate program. Students apply the knowledge, skills, and competencies they have acquired and practiced during their studies, including research methods and their ability to acquire additional skills independently as and if required.

Examination Type: Module Component Examinations

Module Component 1: Thesis Assessment type: Thesis Scope: All intended learning outcomes, mainly 1-6.

Module Component 2: Seminar

Assessment type: Presentation

Length: approx. 10,000 – 14,000 words (25–35 pages), excluding front and back matter. Weight: 80%

Duration: approx. 15 to 30 minutes Weight: 20%

Scope: The presentation focuses mainly on ILOs 6 and 7, but by nature of these ILOs it also touches on the others.

Completion: To pass this module, both module component examinations have to be passed with at least 45%.

Two separate assessments are justified by the size of this module and the fact that the justification of solutions to problems and arguments (ILO 6) and discussion (ILO 7) should at least have verbal elements. The weights of the types of assessments are commensurate with the sizes of the respective module components.

8 Constructor Track Modules

8.1 Methods Modules

8.1.1. Elements of Linear Algebra

| Module Name | | | Module Code | Level (type) | СР |
|----------------------------|-------------------|---|--------------------|-----------------------------------|----------|
| Elements of Linear Algebra | а | | CTMS-MAT-24 | Year 1 (Methods) | 5 |
| Module Components | | | | | |
| Number | Name | | | Туре | СР |
| CTMS-24 | Elements of Line | ar Algebra | | Lecture | 5 |
| Module Coordinator | Program Affiliati | on | | Mandatory Status | |
| Dr. Keivan Mallahi Karai | CONSTRUCT | FOR Track Area | | Mandatory elective RIS and SDT | for CS, |
| Entry Requirements | | | Frequency | Forms of Learning a Teaching | ind |
| Pre-requisites | Co-requisites | Knowledge, Abilities, or | Annually (Fall) | Lectures (35 ho | |
| ⊠ None | _ | Skills | Duration | Private study (Workload | 90 hours |
| | ⊠ None | Knowledge of Pre-Calculus at High School level (Functions, inverse functions, sets, real numbers, trigonometric functions, parametric equations, tangent lines, graphs, elementary methods for solving systems of linear and nonlinear equations) Knowledge of Analytic Geometry at High School level (vectors, lines, planes, reflection, rotation, translation, dot product, cross product, normal vector, polar coordinates) | 1 semester | 125 hours | |

Review all of higher-level High School Mathematics, in particular the topics explicitly named in "Entry Requirements – Knowledge, Ability, or Skills" above.

Content and Educational Aims

This module is the first in a sequence introducing mathematical methods at the university level in a form relevant for study and research in the quantitative natural sciences, engineering, Computer Science. The emphasis in these modules is on training operational skills and recognizing mathematical structures in a problem context. Mathematical rigor is used where appropriate. However, a full axiomatic treatment of the subject is provided in the first-year modules "Analysis" and "Linear Algebra".

The lecture comprises the following topics

• Review of elementary analytic geometry

| | Vector spaces, linear independence, bases, coordinates |
|--------|--|
| | Matrices and matrix algebra |
| | Solving linear systems by Gauss elimination, structure of general solution |
| | LU decomposition and matrix inverse |
| | Linear maps and connection to matrices |
| | Determinant |
| | Eigenvalues and eigenvectors |
| | Hermitian and skew-Hermitian matrices |
| | Orthonormal bases, Gram-Schmidt orthonormalization and QR decomposition |
| | Fourier transform |
| | Singular value decomposition |
| | Principal Component Analysis and best low rank approximations |
| Inter | ded Learning Outcomes |
| By th | e end of the module, students will be able to |
| | |
| 1. | apply the methods described in the content section of this module description to the extent that they can solve standard text- |
| | book problems reliably and with confidence; |
| 2. | recognize the mathematical structures in an unfamiliar context and translate them into a mathematical problem statement; |
| 3. | recognize common mathematical terminology and concepts used in textbooks and research papers in computer science, |
| | engineering, and mathematics to the extent that they fall into the content categories covered in this module. |
| 4. | ndependently prove results which are direct consequences of those proved in the lectures; |
| | understand and use fundamental mathematical terminology to communicate mathematical ideas. |
| | ative Literature |
| indic | ative Literature |
| | Gilbert Strang, Introduction to Linear Algebra, Fifth Edition (2016) |
| | S.A. Leduc Linear Algebra. Hoboken: Wiley (2003) |
| | |
| Usab | ility and Relationship to other Modules |
| • | A rigorous treatment of this topic is provided in the module "Linear Algebra." |
| | |
| Evan | ination Type: Module Examination |
| LAAII | ination type. Module Examination |
| Asses | sment type: Written examination Duration: 120 min |
| , 350. | Weight: 100% |
| | |
| Scop | e: All intended learning outcomes of this module |

Completion: To pass this module, the examination has to be passed with at least 45%.

8.1.2 Elements of Calculus

| Module Name | | Module Code | Level (type) | CF |
|--|---|-----------------------------------|--|-------------|
| Elements of Cal | ulus | CTMS- MAT-25 | Year 1 (Methods) | 5 |
| Module Compo | nents | | | |
| Number | Name | | Туре | CF |
| CTMS-25 | Elements of Calculus | | Lecture | 5 |
| Module Coordinator | Program Affiliation CONSTRUCTOR Track Area | | Mandatory St Mandatory | |
| Dr. Keivan Mallahi Karai | | | elective for CS and SDT | S, RI |
| Entry Requirements Pre-requisites | Co- Knowledge, Abilities, or Skills requisites Knowledge of Pre-Calculus at High School level (Functions, ⊠ None inverse functions, sets, real numbers, polynomials, rational functions, trigonometric functions, logarithm and exponential function, parametric equations, tangent lines, graphs. | Frequency Annually (Spring) | Forms of Lean and Teaching Lectures hours) Private s (90 hour | (35 tudy |
| | Knowledge of Analytic Geometry at High School level (vectors, lines, planes, reflection, rotation, translation, dot product, cross product, normal vector, polar coordinates) Some familiarity with elementary Calculus (limits, derivative) is helpful, but not strictly required. | Duration 1 semester | Workload | |
| Content and Ed This module is t and research in operational skill | ent of Linear Algebra ucational Aims he second in a sequence introducing mathematical methods at the university le the quantitative natural sciences, engineering, Computer Science. The emphasi s and recognizing mathematical structures in a problem context. Mathematical axiomatic treatment of the subject is provided in the first-year modules "Analys | s in these mod rigor is used w | lules is on traini | ng |
| The lecture com | prises the following topics | | | |

- Functions of several variables, representations using graphs and level curves
- Basic ideas of multivariable calculus
- Partial derivatives and directional derivatives, total derivative
- Optimization in several variables, gradient descent, Lagrange multipliers
- Ordinary differential equations with several variables, simple examples
- Linear constant-coefficient ordinary differential equations
- Fourier series and their applications

Intended Learning Outcomes

By the end of the module, students will be able to

- 1. apply the methods described in the content section of this module description to the extent that they can solve standard textbook problems reliably and with confidence;
- 2. recognize the mathematical structures in an unfamiliar context and translate them into a mathematical problem statement;
- 3. recognize common mathematical terminology and concepts used in textbooks and research papers in computer science, engineering, and mathematics to the extent that they fall into the content categories covered in this module.
- 4. independently prove results which are direct consequences of those proved in the lectures;
- 5. understand and use fundamental mathematical terminology to communicate mathematical ideas.

Indicative Literature

- James Stewart, Calculus: Early Transcendentals, (2015)
- S.I. Grossman, Calculus of one variable, 2nd edition, (2014)

Usability and Relationship to other Modules

• A rigorous treatment of this topic is provided in the module "Analysis".

Examination Type: Module Examination

Assessment type: Written examination

Duration: 120 min Weight: 100%

Scope: All intended learning outcomes of this module

8.1.3 Matrix Algebra and Advanced Calculus I

| d Advanced Calculus I | CTMS-MAT-22 | Year 1 (Methods) | 5 |
|---|---|---|---|
| ts | | | |
| Name | | Туре | СР |
| Matrix Algebra and Advanced Calculus I | | Lecture | 5 |
| Program Affiliation | | Mandatory Statu | s |
| CONSTRUCTOR Track Area | | MMDA, PHDS. | |
| | Frequency | Forms of Lear Teaching | ning and |
| | Annually | | |
| Co-requisites Knowledge, Abilities, or | (Spring/Fall) | | |
| Knowledge of pre- | Duration | 125 hours | |
| functions, elementary functions, polynomials) and analytic geometry (equations of lines, systems of linear equations, dot product, polar coordinates) at High School level. Familiarity with ideas of calculus is helpful. | 1 semester | | |
| | | | |
| onal Aims | | | |
| alculus and Linear Algebra I. The course comprises t | | | evel higher |
| cept of function, composition of functions, inverse fue as of calculus: Archimedes to Newton | unctions | | |
| | ts Name Matrix Algebra and Advanced Calculus I Program Affiliation CONSTRUCTOR Track Area Co-requisites CONSTRUCTOR Track Area Co-requisites Co-requisites Constructions, Constructions, Intersection Constructions, | ts Name Matrix Algebra and Advanced Calculus I Program Affiliation CONSTRUCTOR Track Area Co-requisites Knowledge, Abilities, or Skills Co-requisites Knowledge, Abilities, or Skills Co-requisites Knowledge, Abilities, or Calculus ideas (sets and functions, elementary functions, polynomials) and analytic geometry (equations, dot product, polar coordinates) at High School level. Familiarity with ideas of calculus is helpful. Preparation ool mathematics. Onal Aims first in a sequence including advanced mathematical methods at the ur alculus and Linear Algebra I. The course comprises the following topics systems, complex numbers cept of function, composition of functions, inverse functions and sequences and series | ts Type Matrix Algebra and Advanced Calculus 1 Lecture Program Affiliation Mandatory Statu • CONSTRUCTOR Track Area Mandatory for I MADA, PHDS. Mandatory elec and RIS Co-requisites Knowledge, Abilities, or Skills Frequency Forms of Lear Teaching Forms of Lear Teaching Ø none • Knowledge of pre- calculus ideas (sets and functions, elementary functions, polynomials) and analytic geometry (equations of linear equations dot product, polar coordinates) at High School level. Familiarity with ideas of calculus is helpful. 1 semester ool mathematics. I aemutersity level at a l alculus and Linear Algebra 1. The course comprises the following topics: systems, complex numbers seas of calculus: Archineed so Newton on of limit for functions, and sequences and series |

- Derivatives: rate of change, velocity and applications
- Mean value theorem and estimation, maxima and minima, convex functions

Integration, change of variables, Fundamental Theorem of Calculus

- Applications of the integral: work, area, average value, centre of mass
- Improper Integrals, Mean value theorem for integrals
- Taylor series
- Ordinary differential equations, examples, solving first order linear differential equations
- Basic ideas of numerical analysis, Newton's method, asymptotic formulas
- Review of elementary analytic geometry, lines, conics
- Vector spaces, linear independence, bases, coordinates
- Linear maps, matrices and their algebra, matrix inverses
- Gaussian elimination, solution space

Intended Learning Outcomes

Determinants

Upon completion of this module, students will be able to

- 1. apply the methods described in the content section of this module description to the extent that they can
- 2. solve standard text-book problems reliably and with confidence;
- **3.** recognize the mathematical structures in an unfamiliar context and translate them into a mathematical problem statement;
- 4. recognize common mathematical terminology used in textbooks and research papers in the quantitative sciences, engineering, and mathematics to the extent that they fall into the content categories covered in this module.

Indicative Literature

Advanced Calculus, G.B. Folland (Pearson, 2002) Linear

Algebra, S. Lang (Springer Verlag, 1986) Mathematical

Methods for Physics and Engineering,

K. Riley, M. Hobson, S. Bence (Cambridge University Press, 2006)

Usability and Relationship to other Modules

- Calculus and Linear Algebra I can be substituted with this module after consulting academic advisor
- A more advanced treatment of multi-variable Calculus, in particular, its applications in Physics and Mathematics, is provided in the second-semester module "Applied Mathematics". All students taking "Applied Mathematics" are expected to take this module as well as the module topics are closely synchronized.
- The second-semester module "Linear Algebra" provides a complete proof-driven development of the theory of Linear Algebra. Diagonalization is covered more abstractly, with particular emphasis on degenerate cases. The Jordan normal form is also covered in "Linear Algebra", not in this module.

Examination Type: Module Examination

Assessment Type: Written examination

Duration: 120 min

Weight: 100%

Scope: All intended learning outcomes of the module.

8.1.4 Matrix Algebra and Advanced Calculus II

| Module Name Matrix Algebra and | d Advanced Calculus II | Module Code CTMS-MAT-23 | Level (type) Year 1 | СР 5 |
|--|--|--|---|----------------|
| | | | (Methods) | |
| Module Componen | ts | | | |
| Number | Name | | Туре | СР |
| CTMS-23 | Matrix Algebra and Advanced Calculus II | | Lecture | 5 |
| Module Coordinator Dr. Keivan Mallahi Karai | Program Affiliation CONSTRUCTOR Track Area | | Mandatory Status Mandatory for SI MMDA and PHD Mandatory elect RIS | S |
| Entry Requirements Pre-requisites Matrix | Co-requisites Knowledge, Abilities, or Skills ⊠ none • None beyond | Frequency Annually (Spring) | Forms of Learn Teaching Lectures (35) Private stud hours) | 5 hours) |
| Algebra and Advanced | formal pre- requisites | Duration | Workload | |
| Calculus I | | 1 semester | 125 hours | |
| Minima Multiple Vector fi Potentia Paramet Vector p Integral Basics of Eigenval Inner pro Matrix fi decomp Linear co | erivatives and Maxima of functions of several variables, Lagra integrals, iterated integrals, integration over stand elds, parametric representation of curves, line integ- ils, Green's theorem in the plane ric representation of surfaces roducts and normal surface integrals theorems by Stokes and Gauss, physical interpretat f differential forms and their calculus, connection t ues and eigenvectors, diagonalisable matrices poduct spaces, Hermitian and unitary matrices actorizations: Singular value decomposition with a osition postant-coefficient ordinary differential equations, al oscillations | ard regions, change grals and arc length, ions to gradient, curl, and pplications, LU deco | conservative vector divergence mposition, QR | fields |
| Periodic Intended Learning Of | functions, Fourier series | | | |
| understar multivari apply the evaluate evaluate | of this module, students will be able to nd the definitions of continuity, derivative of a func able integrals, eigenvalues and eigenvectors and a methods described in the content section of this n multivariable integrals using definitions or by apply various decompositions of matrices adard text-book problems reliably and with confider | ssociated notions. nodule description to ring Green and Stoke | o the extent that the | ey can |

- 6. recognize the mathematical structures in an unfamiliar context and translate them into a mathematical problem statement;
- 7. recognize common mathematical terminology used in textbooks and research papers in the quantitative sciences, engineering, and mathematics to the extent that they fall into the content categories covered in this module.

Indicative Literature

Advanced Calculus, G.B. Folland (Pearson, 2002) Linear

Algebra, S. Lang (Springer Verlag, 1986) Mathematical

Methods for Physics and Engineering,

K. Riley, M. Hobson, S. Bence (Cambridge University Press, 2006) Vector

Calculus, Linear Algebra, and Differential Forms: A Unified

Approach, J.H. Hubbard, B. Hubbard (Pearson, 1998)

Usability and Relationship to other Modules

- This module can substitute Calculus and Linear Algebra II after consulting academic advisor.
- Methods of this course are applied in the module Mathematical Modeling.
- The second-semester module Linear Algebra provides a more rigorous and more abstract treatment of some of the notions discussed in this module.

Examination Type: Module Examination

Assessment type: Written examination

Length/duration: (120min) Weight: 100 %

Scope: All intended learning outcomes of this module

8.1.5 Probability and Random Processes

| Module Name Probability and Random Processes | | | Module Code CTMS-MAT-12 | Level (type) Year 2 | СР 5 |
|---|------------------------|---|----------------------------|---|----------------|
| Module Components | | | | (Methods) | |
| Number | Name | | | Туре | СР |
| CTMS-12 | | I random processes | | Lecture | 5 |
| Module Coordinator | Program Affiliation | | | Mandatory Statu | |
| Dr. Keivan Mallahi Karai | CONSTRUCTOR Track Area | | | Mandatory for CS, SDT ECE, MMDA, PHDS and RIS | |
| Entry Requirements | | | Frequency | Forms of Learning | g and |
| Pre-requisites | Co- requisites | Knowledge, Abilities, or Skills | Annually (Fall) | Teaching Lectures (35 hours) Private study (90 hours) | |
| | ⊠ None | • Knowledge of calculus at | Duration | Workload | |
| ⊠ Matrix Algebra and Advanced Calculus II or Elements of Algebra and Elements of Calculus | | the level of a first year calculus module (differentiation, integration with one and several variables, trigonometric functions, logarithms and exponential functions). Knowledge of linear algebra at the level of a first-year university module (eigenvalues and eigenvectors, diagonalization of matrices). Some familiarity with elementary probability theory at the high school level. | 1 semester | Workload 125 hours | |

Skills" above.

Content and Educational Aims

This module aims to provide a basic knowledge of probability theory and random processes suitable for students in engineering, Computer Science, and Mathematics. The module provides students with basic skills needed for formulating real-world problems dealing with randomness and probability in mathematical language, and methods for applying a toolkit to solve these problems. Mathematical rigor is used where appropriate. A more advanced treatment of the subject is deferred to the third-year module Stochastic Processes.

The lecture comprises the following topics

- Brief review of number systems, elementary functions, and their graphs
- Outcomes, events and sample space.
- Combinatorial probability.
- Conditional probability and Bayes' formula.
- Binomials and Poisson-Approximation
- Random Variables, distribution and density functions.
- Independence of random variables.
- Conditional Distributions and Densities.
- Transformation of random variables.
- Joint distribution of random variables and their transformations.
- Expected Values and Moments, Covariance.
- High dimensional probability: Chebyshev and Chernoff bounds.
- Moment-Generating Functions and Characteristic Functions,
- The Central limit theorem.
- Random Vectors and Moments, Covariance matrix, Decorrelation.
- Multivariate normal distribution.
- Markov chains, stationary distributions.

Intended Learning Outcomes

By the end of the module, students will be able to

- 1. command the methods described in the content section of this module description to the extent that they can solve standard text-book problems reliably and with confidence;
- 2. recognize the probabilistic structures in an unfamiliar context and translate them into a mathematical problem statement;
- 3. recognize common mathematical terminology used in textbooks and research papers in the quantitative sciences, engineering, and mathematics to the extent that they fall into the content categories covered in this module.

Indicative Literature

J. Hwang and J.K. Blitzstein (2019). Introduction to Probability, second edition. London: Chapman & Hall.

S. Ghahramani. Fundamentals of Probability with Stochastic Processes, fourth edition. Upper Saddle River: Prentice Hall.

Usability and Relationship to other Modules

Students taking this module are expected to be familiar with basic tools from calculus and linear algebra.

Examination Type: Module Examination

Assessment type: Written examination

Duration: 120 min Weight: 100%

Scope: All intended learning outcomes of this module

8.1.6 Numerical Methods

| Module Name | | | Module Code | Level (type) | СР |
|-----------------------------|---|--|------------------------------|---|----------|
| Numerical Methods | | | CTMS-MAT-13 | Year 2 (Methods) | 5 |
| Module Components | | | | | |
| Number | Name | | | Туре | СР |
| CTMS-13 | Numerical Met | hods | | Lecture | 5 |
| Module Coordinator | Program Affiliation | on | | Mandatory Stat | us |
| Dr. Keivan Mallahi Karai | CONSTRUCTOR Track Area | | | Mandatory for ECE Mandatory elective f CS and RIS | |
| Entry Requirements | | | Frequency Annually | Forms of Learr Teaching | ning and |
| Pre-requisites | Co-requisites | Knowledge, Abilities, or Skills Knowledge of Calculus (functions, inverse | (Spring) | Lectures (35 hours) Private study (90 hours) | |
| | (functions, inverse functions, sets, real numbers, sequences and limits, polynomials, rational functions, trigonometric | | Duration | hours) Workload | |
| | | 1 semester | 125 hours | | |
| | | functions, logarithm and exponential function, parametric equations, | | | |
| | tangent lines, graphs, derivatives, anti- derivatives, elementary techniques for solving equations) • Knowledge of Linear Algeb (vectors, matrices, lines, planes, n- dimensional Euclidean vector space, rotation, translation, dot product (scalar product), cross product, normal | derivatives, anti- | | | |
| | | techniques for solving equations) | | | |
| | | (vectors, matrices, lines, planes, n- dimensional Euclidean vector space, | | | |
| | | | | | |
| | | cross product, normal | | | |
| | | vector, eigenvalues, eigenvectors, elementary | | | |
| | | techniques for solving systems of linear | | | |
| | | equations) | | | |

Taking Calculus and Elements of Linear Algebra II before taking this module is recommended, but not required. A thorough review of Calculus and Elements of Linear Algebra, with emphasis on the topics listed as "Knowledge, Abilities, or Skills" is recommended.

Content and Educational Aims

This module covers calculus-based numerical methods, in particular root finding, interpolation, approximation, numerical differentiation, numerical integration (quadrature), and a first introduction to the numerical solution of differential equations.

The lecture comprises the following topics

- number representations
- Gaussian elimination
- LU decomposition
- Cholesky decomposition
- iterative methods
- bisection method
- Newton's method
- secant method
- polynomial interpolation
- Aitken's algorithm
- Lagrange interpolation
- Newton interpolation
- Hermite interpolation
- Bezier curves
- De Casteljau's algorithm
- piecewise interpolation
- Spline interpolation
- B-Splines
- Least-squares approximation
- polynomial regression
- difference schemes
- Richardson extrapolation
- Quadrature rules
- Monte Carlo integration
- time stepping schemes for ordinary differential equations
- Runge Kutta schemes
- finite difference method for partial differential equations

Intended Learning Outcomes

By the end of the module, students will be able to

- 1. describe the basic principles of discretization used in the numerical treatment of continuous problems;
- 2. command the methods described in the content section of this module description to the extent that they can solve standard text-book problems reliably and with confidence;
- 3. recognize mathematical terminology used in textbooks and research papers on numerical methods in the quantitative sciences, engineering, and mathematics to the extent that they fall into the content categories covered in this module;
- 4. implement simple numerical algorithms in a high-level programming language;
- 5. understand the documentation of standard numerical library code and understand the potential limitations and caveats of such algorithms.

Indicative Literature

D. Kincaid and W. Cheney (1991). Numerical Analysis: Mathematics of Scientific Computing. Pacific Grove: Brooks/Cole Publishing.

W. Boehm and H. Prautzsch (1993). Numerical Methods. Natick: AK Peters.

Usability and Relationship to other Modules

• This module is a co-recommendation for the module "Applied Dynamical Systems Lab", in which the actual implementation in a high-level programming language of the learned methods will be covered.

Examination Type: Module Examination

Assessment type: Written examination

Duration: 120 min

Weight: 100%

Scope: All intended learning outcomes of this module.

8.1.7 Discrete Mathematics

| Module Name | | | Module Code | Level (type) | СР |
|--|--|---|------------------------|---|----|
| Discrete Mathematics | | | CO-501 | Year 2 (CORE) | 5 |
| Module Components | | | I | | |
| Number | Name | | | Туре | СР |
| CO-501-A | Discrete Mathematics | | | Lecture | 5 |
| Module Coordinator Dr. Keivan Mallahi-Karai | Program Affiliation Mathematics, Modeling and Data Analytics (MMDA) | | | Mandatory Status Mandatory for MMDA Mandatory elective for SDT, CS and RIS | |
| Entry Requirements | | | Frequency | Forms of Learning and Teaching | |
| Pre-requisites ⊠ None | Co-requisites | Co-requisites Knowledge, Abilities, or Skills | | Lectures (35Private Study | |
| ⊠ None | | Basic university mathematics: can be acquired via the Methods Modules "Calculus and Elements of Linear Algebra I + II" or Matrix Algebra and Advanced Calculus. | Duration 1 semester | Workload 125 hours | |

- Some basic familiarity with linear algebra is useful, but not technically required.
- It is recommended to have taken the Methods module: Calculus and Elements of Linear Algebra I + II

Content and Educational Aims

This module is an introductory lecture in discrete mathematics. The lecture consists of two main components, enumerative combinatorics and graph theory. The lecture emphasizes connections of discrete mathematics with other areas of mathematics such as linear algebra and basic probability, and outlines applications to areas of computer science, cryptography, etc. where employment of ideas from discrete mathematics has proven to be fruitful. The first part of the lecture—enumerative combinatorics—deals with several classical enumeration problems (Binomial coefficients, Stirling numbers), counting under group actions and generating function. The second half of the lecture—graph theory—includes a discussion of basic notions such as chromatic number, planarity, matchings in graphs, Ramsey theory, and expanders, and their applications.

Intended Learning Outcomes

By the end of the module, students will be able to

- 1. demonstrate their mastery of basic tools in discrete mathematics.
- 2. develop the ability to use discrete mathematics concepts (such as graphs) to model problems in computer science.
- 3. analyze the definition of basic combinatorial objects such as graphs, permutations, partitions, etc.
- 4. formulate and design methods and algorithms for solving applied problems based on concepts from discrete mathematics.

Indicative Literature

J.H. van Lint and R.M. Wilson (2001). A Course in Combinatorics, second edition. Cambridge: Cambridge University Press.

B. Bollobas (1998). Modern Graph Theory, Berlin: Springer.

Usability and Relationship to other Modules

- This module is recommended for students pursuing a minor in Mathematics
- This module is a good option as an elective module for students in RIS.

Examination Type: Module Examination

Assessment Type: Written examination

Scope: All intended learning outcomes of this module

Completion: To pass this module, the examinations must be passed with at least 45%.

Duration: 120 min Weight: 100%

8.2 New Skills

8.2.1 Logic (perspective I)

| Module Name Logic (perspective I) | | | Module Code | Level (type) | СР |
|---|--|---|------------------------------|--|------|
| | | | CTNS-NSK-01 | Year 2 New Skills | 2.5 |
| Module Component | S | | | | |
| Number | Name | | | Туре | СР |
| CTNS-01 | Logic (perspective I) | | | Lecture (online) | 2.5 |
| Module Coordinator Prof. Dr. Jules Coleman | Program Affiliation CONSTRUCTOR Track Area | | | Mandatory Status Mandatory elective for all UG students (one perspective must be chosen) | |
| Entry Requirements Pre-requisites Inone | Co-requisites ⊠ none | Knowledge, Abilities, or Skills • | Frequency Annually (Fall) | Forms of Learnin Teaching Online lecture (17 Private study (45h | .5h) |
| Recommendations fo | | | Duration 1 semester | Workload 62.5 hours | |

Content and Educational Aims

Suppose a friend asks you to help solve a complicated problem? Where do you begin? Arguably, the first and most difficult task you face is to figure out what the heart of the problem actually is. In doing that you will look for structural similarities between the problem posed and other problems that arise in different fields that others may have addressed successfully. Those similarities may point you to a pathway for resolving the problem you have been asked to solve. But it is not enough to look for structural similarities. Sometimes relying on similarities may even be misleading. Once you've settled tentatively on what you take to be the heart of the matter, you will naturally look for materials, whether evidence or arguments, that you believe is relevant to its potential solution. But the evidence you investigate of course depends on your formulation of the problem, and your formulation of the problem likely depends on the tools you have available – including potential sources of evidence and argumentation. You cannot ignore this interactivity, but you can't allow yourself to be hamstrung entirely by it. But there is more. The problem itself may be too big to be manageable all at once, so you will have to explore whether it can be broken into manageable parts and if the information you have bears on all or only some of those parts. And later you will face the problem of whether the solutions to the particular sub problems can be put together coherently to solve the entire problem taken as a whole.

What you are doing is what we call engaging in computational thinking. There are several elements of computational thinking illustrated above. These include: Decomposition (breaking the larger problem down into smaller ones); Pattern recognition (identifying structural similarities); Abstraction (ignoring irrelevant particulars of the problem): and Creating Algorithms), problem-solving formulas.

But even more basic to what you are doing is the process of drawing inferences from the material you have. After all, how else are you going to create a problem-solving formula, if you draw incorrect inferences about what information has shown and what, if anything follows logically from it. What you must do is apply the rules of logic to the information to draw inferences that are warranted.

We distinguish between informal and formal systems of logic, both of which are designed to indicate fallacies as well as warranted inferences. If I argue for a conclusion by appealing to my physical ability to coerce you, I prove nothing about the truth of what I claim. If anything, by doing so I display my lack of confidence in my argument. Or if the best I can do is berate you for your skepticism, I have done little more than offer an ad hominem instead of an argument. Our focus will be on formal systems of logic, since they are at the heart of both scientific argumentation and computer developed algorithms. There are in fact many different kinds of logic and all figure to varying degrees in scientific inquiry. There are inductive types of logic, which purport to formalize the relationship between premises that if true offer evidence on behalf of a conclusion and the conclusion and are represented as claims about the extent to which the conclusion is confirmed by the premises. There are deductive types of logic, which introduce a different relationship between premise and conclusion. These variations of logic consist in rules that if followed entail that if the premises are true then the conclusion too must be true.

There are also modal types of logic which are applied specifically to the concepts of necessity and possibility, and thus to the relationship among sentences that include either or both those terms. And there is also what are called deontic logic, a modification of logic that purport to show that there are rules of inference that allow us to infer what we ought to do from facts about the circumstances in which we find ourselves. In the natural and social sciences most of the emphasis has been placed on inductive logic, whereas in math it is placed on deductive logic, and in modern physics there is an increasing interest in the concepts of possibility and necessity and thus in modal logic. The humanities, especially normative discussions in philosophy and literature are the province of deontic logic.

This module will also take students through the central aspects of computational thinking, as it is related to logic; it will introduce the central concepts in each, their relationship to one another and begin to provide the conceptual apparatus and practical skills for scientific inquiry and research.

Intended Learning Outcomes

Students acquire transferable and key skills in this module. By the

end of this module, the students will be able to

- 1 apply the various principles of logic and expand them to computational thinking.
- 2 understand the way in which logical processes in humans and in computers are similar and different at the same time.
- 3 apply the basic rules of first-order deductive logic and employ them rules in the context of creating a scientific or social scientific study and argument.
- 4 employ those rules in the context of creating a scientific or social scientific study and argument

Indicative Literature

Frege, Gottlob (1879), Begriffsschrift, eine der arithmetischen nachgebildete Formelsprache des reinen Denkens [Translation: A Formal Language for Pure Thought Modeled on that of Arithmetic], Halle an der Salle: Verlag von Louis Nebert.

Gödel, Kurt (1986), Russels mathematische Logik. In: Alfred North Whitehead, Bertrand Russell: Principia Mathematica. Vorwort, S. V–XXXIV. Suhrkamp.

Leeds, Stephen. "George Boolos and Richard Jeffrey. Computability and logic. Cambridge University Press, New York and London1974, x+ 262 pp." The Journal of Symbolic Logic 42.4 (1977): 585-586.

Kubica, Jeremy. Computational fairy tales. Jeremy Kubica, 2012.

McCarthy, Timothy. "Richard Jeffrey. Formal logic: Its scope and limits. of XXXVIII 646. McGraw-Hill Book Company, New York etc. 1981, xvi+ 198 pp." The Journal of Symbolic Logic 49.4 (1984): 1408-1409.

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment Type: Written Examination

Duration/Length: 60 min Weight: 100%

Scope: All intended learning outcomes of the module.

8.2.2 Logic (perspective II)

| Module Name | | | Module Code | Level (type) | СР |
|--------------------------|------------------------|---|-----------------------------------|---|-----|
| Logic (perspective II) | | | CTNS-NSK-02 | Year 2 New | 2.5 |
| | | | | Skills | |
| Module Component | S | | | | |
| Number | Name | | | Туре | СР |
| CTNS-02 | Logic (perspective II) | | | Lecture (online) 2.5 | |
| Module Coordinator | Program Affiliation | | | Mandatory Status | |
| NN | CONSTRUCTOR Track Area | | | Mandatory elective for all UG students (one perspective must be chosen) | |
| Entry Requirements | | Frequency | Forms of Learning and Teaching | | |
| Pre-requisites ⊠ none | Co-requisites | Knowledge, Abilities, or Skills • | Annually (Fall) | Online lecture (17.5h) Private study (45h) | |
| | ⊠ none | | D | | |
| | | | Duration | Workload | |
| | | | 1 semester | 62.5 hours | |
| Recommendations fo | r Preparation | | 1 | 1 | |

Content and Educational Aims

The focus of this module is on formal systems of logic, since they are at the heart of both scientific argumentation and computer developed algorithms. There are in fact many kinds of logic and all figure to varying degrees in scientific inquiry. There are inductive types of logic, which purport to formalize the relationship between premises that if true offer evidence on behalf of a conclusion and the conclusion and are represented as claims about the extent to which the conclusion is confirmed by the premises. There are deductive types of logic, which introduce a different relationship between premise and conclusion. These variations of logic consist in rules that if followed entail that if the premises are true then the conclusion too must be true.

This module introduces logics that go beyond traditional deductive propositional logic and predicate logic and as such it is aimed at students who are already familiar with basics of traditional formal logic. The aim of the module is to provide an overview of alternative logics and to develop a sensitivity that there are many different logics that can provide effective tools for solving problems in specific application domains.

The module first reviews the principles of a traditional logic and then introduces many-valued logics that distinguish more than two truth values, for example true, false, and unknown. Fuzzy logic extends traditional logic by replacing truth values with real numbers in the range 0 to 1 that are expressing how strong the believe into a proposition is. Modal logics introduce modal operators expressing whether a proposition is necessary or possible. Temporal logics deal with propositions that are qualified by time. Once can view temporal logics as a form of modal logics where propositions are qualified by time constraints. Interval temporal logic provides a way to reason about time intervals in which propositions are true.

The module will also investigate the application of logic frameworks to specific classes of problems. For example, a special subset of predicate logic, based on so-called Horn clauses, forms the basis of logic programming languages such as Prolog. Description logics, which are usually decidable logics, are used to model relationships and they have applications in the semantic web, which enables search engines to reason about resources present on the Internet.

Intended Learning Outcomes

Students acquire transferable and key skills in this module. By the

end of this module, the students will be able to

- 1. apply the various principles of logic
- 2. explain practical relevance of non-standard logic
- 3. describe how many-valued logic extends basic predicate logic
- 4. apply basic rules of fuzzy logic to calculate partial truth values
- 5. sketch basic rules of temporal logic
- 6. implement predicates in a logic programming language
- 7. prove some simple non-standard logic theorems

Indicative Literature

Bergmann, Merry. "An Introduction to Many-Valued and Fuzzy Logic: Semantics, Algebras, and Derivation Systems", Cambridge University Press, April 2008.

Sterling, Leon S., Ehud Y. Shapiro, Ehud Y. "The Art of Prolog", 2nd edition, MIT Press, March 1994. Fisher,

Michael. "An Introduction to Practical Formal Methods Using Temporal Logic", Wiley, Juli 2011.

Baader, Franz. "The Description Logic Handbook: Theory Implementation and Applications", Cambridge University Press, 2nd edition, May 2010.

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment Type: Written Examination

Duration/Length: 60 min

Weight: 100%

Scope: All intended learning outcomes of the module.

8.2.3 Causation and Correlation (perspective I)

| Module Name | | | Module Code | Level (type) | СР |
|-----------------------------------|---------------------|------------------------------------|--------------------------------|--|------|
| Causation and Correla | ation (perspective | 1) | CTNS-NSK-03 | Year 2 New Skills | 2.5 |
| Module Components | | | | | |
| Number | Name | | Туре | СР | |
| CTNS-03 | Causation and C | Correlation | | Lecture (online) | 2.5 |
| Module Coordinator | Program Affiliation | n | Mandatory Status | | |
| Prof. Dr. Jules Coleman | • CONS | TRUCTOR Track Area | | Mandatory electiv UG students (one perspective must b | |
| Entry Requirements Pre-requisites | Co-requisites | Knowledge, Abilities, or Skills | Frequency Annually (Spring) | Forms of Learnin Teaching Online lecture (17 Private study (45h | .5h) |
| ⊠ none | ⊠ none | | Duration | Workload | |
| | | | 1 semester | 62.5 hours | |

Content and Educational Aims

In many ways, life is a journey. And also, as in other journeys, our success or failure depends not only on our personal traits and character, our physical and mental health, but also on the accuracy of our map. We need to know what the world we are navigating is actually like, the how, why and the what of what makes it work the way it does. The natural sciences provide the most important tool we have developed to learn how the world works and why it works the way it does. The social sciences provide the most advanced tools we have to learn how we and other human beings, similar in most ways, different in many others, act and react and what makes them do what they do. In order for our maps to be useful, they must be accurate and correctly reflect the way the natural and social worlds work and why they work as they do.

The natural sciences and social sciences are blessed with enormous amounts of data. In this way, history and the present are gifts to us. To understand how and why the world works the way it does requires that we are able to offer an explanation of it. The data supports a number of possible explanations of it. How are we to choose among potential explanations? Explanations, if sound, will enable us to make reliable predictions about what the future will be like, and also to identify many possibilities that may unfold in the future. But there are differences not just in the degree of confidence we have in our predictions, but in whether some of them are necessary future states or whether all of them are merely possibilities? Thus, there are three related activities at the core of scientific inquiry: understanding where we are now and how we got here (historical); knowing what to expect going forward (prediction); and exploring how we can change the paths we are on (creativity).

At the heart of these activities are certain fundamental concepts, all of which are related to the scientific quest to uncover immutable and unchanging laws of nature. Laws of nature are thought to reflect <u>a causal</u> nexus between a previous event and a future one. There are also true statements that reflect universal or nearly universal connections between events past and present that are not laws of nature because the relationship they express is that of <u>a correlation</u> between events. A working thermostat accurately allows us to determine or even to predict the temperature in the room in which it is located, but it does not explain why the room has the temperature it has. What then is the core difference between causal relationships and correlations? At the same time, we all recognize that given where we are now there are many possible futures for each of us, and even had our lives gone just the slightest bit differently than they have, our present state could well have been very different than it is. The relationship between possible pathways between events that have not materialized but could have is expressed through the idea of <u>counterfactual</u>.

Creating accurate roadmaps, forming expectations we can rely on, making the world a more verdant and attractive place requires us to understand the concepts of causation, correlation, counterfactual explanation, prediction, necessity, possibility, law of nature and universal generalization. This course is designed precisely to provide the conceptual tools and intellectual skills to implement those concepts in our future readings and research and ultimately in our experimental investigations, and to employ those tools in various disciplines.

Intended Learning Outcomes

Students acquire transferable and key skills in this module. By the

end of this module, the students will be able to

- 1. formulate testable hypotheses that are designed to reveal causal connections and those designed to reveal interesting, important and useful correlations.
- 2. distinguish scientifically interesting correlations from unimportant ones.
- 3. apply critical thinking skills to evaluate information.
- 4. understand when and why inquiry into unrealized possibility is important and relevant.

Indicative Literature

Thomas S. Kuhn: The Structure of Scientific Revolutions, Nelson, fourth edition 2012; Goodman,

Nelson. Fact, fiction, and forecast. Harvard University Press, 1983;

Quine, Willard Van Orman, and Joseph Silbert Ullian. The web of belief. Vol. 2. New York: Random house, 1978.

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment Type: Written Examination

Scope: All intended learning outcomes of the module

Completion: To pass this module, the examination has to be passed with at least 45%

Duration/Length: 60 min Weight: 100%

8.2.4 Causation and Correlation (perspective II)

| Module Name | | Level (type) | СР | | | | | | |
|---|-------------------------|---|-------------------|---|---------------|--|--|--|--|
| Causation and Corr | elation (perspective II |) | CTNS-NSK-04 | Year 2 New 2.5 Skills | | | | | |
| Module Component | S | | | | | | | | |
| Number | Name | | | Туре | СР | | | | |
| CTNS-04 | Causation and Corr | elations | | Lecture (online) 2.5 | | | | | |
| Module Coordinator | Program Affiliation | | Mandatory Status | | | | | | |
| Dr. Keivan Mallahi-Karai, Dr. Eoin Ryan, Dr. Irina Chiaburu | • CONSTRU | JCTOR Track Area | | Mandatory electiv students (one per must be chosen) | | | | | |
| Entry Requirements | | | Frequency | Forms of Learning a | nd Teaching | | | | |
| Pre-requisites ⊠ none | Co-requisites ⊠ none | Knowledge, Abilities, or Skills • Basic | Annually | Online lecture (17 study (45h | 7.5h) Private | | | | |
| | | probability theory | (Spring) Duration | Workload | | | | | |
| | | | 1 semester | 62.5 hours | | | | | |

Content and Educational Aims

Causality or causation is a surprisingly difficult concept to understand. David Hume famously noted that causality is a concept that our science and philosophy cannot do without, but it is equally a concept that our science and philosophy cannot describe. Since Hume, the problem of cause has not gone away, and sometimes seems to get even worse (e.g., quantum mechanics confusing previous notions of causality). Yet, ways of doing science that lessen our need to explicitly use causality have become very effective (e.g., huge developments in statistics). Nevertheless, it still seems that the concept of causality is at the core of explaining how the world works, across fields as diverse as physics, medicine, logistics, the law, sociology, and history – and ordinary daily life – through all of which, explanations and predictions in terms of cause and effect remain intuitively central.

Causality remains a thorny problem but, in recent decades, significant progress has occurred, particularly in work by or inspired by Judea Pearl. This work incorporates many 20th century developments, including statistical methods – but with a reemphasis on finding the why, or the cause, behind statistical correlations –, progress in understanding the logic, semantics and metaphysics of conditionals and counterfactuals, developments based on insights from the likes of philosopher Hans Reichenbach or biological statistician Sewall Wright into causal precedence and path analysis, and much more. The result is a new toolkit to identify causes and build causal explanations. Yet even as we get better at identifying causes, this raises new (or old) questions about causality, including metaphysical questions about the nature of causes (and effects, events, objects, etc), but also questions

about what we really use causality for (understanding the world as it is or just to glean predictive control of specific

outcomes), about how causality is used differently in different fields and activities (is cause in physics the same as that in history?), and about how other crucial concepts relate to our concept of cause (space and time seem to be related to causality, but so do concepts of legal and moral responsibility).

This course will introduce students to the mathematical formalism derived from Pearl's work, based on directed acyclic graphs and probability theory. Building upon previous work by Reichenbach and Wright, Pearl defines a "a calculus of interventions" of "do-calculus" for talking about interventions and their relation to causation and counterfactuals. This model has been applied in various areas ranging from econometrics to statistics, where acquiring knowledge about causality is of great importance.

At the same time, the course will not forget some of the metaphysical and epistemological issues around cause, so that students can better critically evaluate putative causal explanations in their full context. Abstractly, such issues involve some of the same philosophical questions Hume already asked, but more practically, it is important to see how metaphysical and epistemological debates surrounding the notion of cause affect scientific practice, and equally if not more importantly, how scientific practice pushes the limits of theory. This course will look at various ways in which empirical data can be transformed into explanations and theories, including the variance approach to causality (characteristic of the positivistic quantitative paradigm), and the process theory of causality (associated with qualitative methodology). Examples and case studies will be relevant for students of the social sciences but also students of the natural/physical world as well.

Intended Learning Outcomes

Students acquire transferable and key skills in this module.

- 1. By the end of this module, the students will be able to
- 2. have a clear understanding of the history of causal thinking. form a critical understanding of the key debates and controversies surrounding the idea of causality.
- 3. recognize and apply probabilistic causal models.
- 4. explain how understanding of causality differs among different disciplines.
- 5. demonstrate how theoretical thinking about causality has shaped scientific practices.

Indicative Literature

Paul, L. A. and Ned Hall. Causation: A User's Guide. Oxford University Press 2013.

Pearl, Judea. Causality: Models, Reasoning and Inference. Cambridge University Press 2009

Pearl, Judea, Glymour Madelyn and Jewell, Nicolas. Causal Inference in Statistics: A Primer. Wiley 2016

Ilari, Phyllis McKay and Federica Russo. Causality: Philosophical Theory Meets Scientific Practice. Oxford University Press 2014.

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment: Written examination

Duration/Length: 60 min

Weight: 100 %

Scope: All intended learning outcomes of the module

8.2.5 Linear Model and Matrices

| Module Name | | | Module Code | Level (type) | СР | | | | |
|----------------------------------|---------------------------|------------------------------------|-----------------|----------------------|--------------|--|--|--|--|
| Linear Model and N | Matrices | | CTNS-NSK-05 | Year 3 New Skills | 5 | | | | |
| Module Component | S | | | | | | | | |
| Number | Name | | | Туре | СР | | | | |
| CTNS-05 | Linear models ar | nd matrix | Seminar | 5 | | | | | |
| Module Coordinator | Program Affiliation | 1 | | Mandatory Status | | | | | |
| Prof. Dr. Marc- Thorsten Hütt | CONST | RUCTOR Track Area | | Mandatory elective | | | | | |
| Entry Requirements | I | | Frequency | Forms of Learning | and Teaching | | | | |
| Pre-requisites Logic | Co-requisites ⊠ none | Knowledge, Abilities, or Skills | Annually (Fall) | Online lecture (35h) | | | | | |
| Causation & Correlation | | | | Private Study (9 | 0h) | | | | |
| | | | Duration | Workload | | | | | |
| | | | 1 Semester | 125 hours | | | | | |

Content and Educational Aims

There are no universal 'right skills'. But the notion of linear models and the avenue to matrices and their properties can be useful in diverse disciplines to implement a quantitative, computational approach. Some of the most popular data and systems analysis strategies are built upon this framework. Examples include principal component analysis (PCA), the optimization techniques used in Operations Research (OR), the assessment of stable and unstable states in nonlinear dynamical systems, as well as aspects of machine learning.

Here we introduce the toolbox of linear models and matrix-based methods embedded in a wide range of transdisciplinary applications (part 1). We describe its foundation in linear algebra (part 2) and the range of tools and methods derived from this conceptual framework (part 3). At the end of the course, we outline applications to graph theory and machine learning (part 4). Matrices can be useful representations of networks and of system of linear equations. They are also the core object of linear stability analysis, an approach used in nonlinear dynamics. Throughout the course, examples from neuroscience, social sciences, medicine, biology, physics, chemistry, and other fields are used to illustrate these methods.

A strong emphasis of the course is on the sensible usage of linear approaches in a nonlinear world. We will critically reflect the advantages as well as the disadvantages and limitations of this method. Guiding questions are: How appropriate is a linear approximation of a nonlinear system? What do you really learn from PCA? How reliable are the optimal states obtained via linear programming (LP) techniques?

This debate is embedded in a broader context: How does the choice of a mathematical technique confine your view on the system at hand? How, on the other hand, does it increase your capabilities of analyzing the system

(due to software available for this technique, the ability to compare with findings from other fields built upon the same technique and the volume of knowledge about this technique)?

In the end, students will have a clearer understanding of linear models and matrix approaches in their own discipline, but they will also see the full transdisciplinarity of this topic. They will make better decisions in their choice of data analysis methods and become mindful of the challenges when going from linear to nonlinear thinking.

Intended Learning Outcomes

Upon completion of this module, students will be able to

- 1. apply the concept of linear modeling in their own discipline
- 2. distinguish between linear and nonlinear interpretation strategies and understand the range of applicability of linear models
- 3. make use of data analysis / data interpretation strategies from other disciplines, which are derived from linear algebra
- 4. be aware of the ties that linear models have to machine learning and network theory

Note that these four ILOs can be loosely associated with the four parts of the course indicated above

Indicative Literature

Part 1:

material from Linear Algebra for Everyone, Gilbert Strang, Wellesley-Cambridge Press, 2020 Part 2:

material from Introduction to Linear Algebra (5th Edition), Gilbert Strang, Cambridge University Press, 2021 Part 3:

Mainzer, Klaus. "Introduction: from linear to nonlinear thinking." Thinking in Complexity: The Computational Dynamics of Matter, Mind and Mankind (2007): 1-16.

material from Mathematics of Big Data: Spreadsheets, Databases, Matrices, and Graphs, Jeremy Kepner, Hayden Jananthan, The MIT Press, 2018

material from Introduction to Linear Algebra (5th Edition), Gilbert Strang, Cambridge University Press, 2021 Part 4:

material from Linear Algebra and Learning from Data, Gilbert Strang, Wellesley-Cambridge Press, 2019

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment: Written examination

Duration/Length: 120 min

Weight: 100 %

Scope: All intended learning outcomes of the module

8.2.6 Complex Problem Solving

| Module Name | | | Module Code | Level (type) | СР | | | |
|---|----------------------------|---|--|--|-------------|--|--|--|
| Complex Problem S | olving | | CTNS-NSK-06 | Year 3 New Skills | 5 | | | |
| Module Components | 5 | | | | | | | |
| Number | Name | | | Туре | СР | | | |
| CTNS-06 | Complex Problem | Solving | Lecture (online) | 5 | | | | |
| Module Coordinator Prof. Dr. Marco Verweij | Program Affiliation CONSTR | RUCTOR Track Area | Mandatory Status Mandatory elective | | | | | |
| Entry Requirements | | | Frequency | Forms of Learning ar | nd Teaching | | | |
| Pre-requisites Logic Causation & Correlation | Co-requisites ⊠ none | Knowledge, Abilities, or Skills • Project Management • Complex Problem Solving | Annually (Fall) Duration | Online Lectures (3 Private Study (90h Workload | | | | |
| | | | 1 semester | 125 hours | | | | |

Wherever possible intuition will be emphasized over technical detail. Technical readings will be made available and discussed with students in class.

Content and Educational Aims

Complex problems are, by definition, non-linear and/or emergent. Some fifty years ago, scholars such as Herbert Simon began to argue that societies around the world had developed an impressive array of tools with which to solve simple and even complicated problems, but still needed to develop methods with which to address the rapidly increasing number of complex issues. Since then, a variety of such methods has emerged. These include 'serious games' developed in computer science, 'multisector systems analysis' applied in civil and environmental engineering, 'robust decision-making' proposed by the RAND Corporation, 'design thinking' developed in engineering and business studies, 'structured problem solving' used by McKinsey & Co., 'real-time technology assessment' advocated in science and technology studies, and 'deliberative decision-making' emanating from political science.

In this course, students first learn to distinguish between simple, complicated and complex problems. They also become familiar with the ways in which a particular issue can sometimes shift from one category into another. In addition, the participants learn to apply several tools for resolving complex problems. Finally, the students are introduced to the various ways in which natural and social scientists can help stakeholders resolve complex problems. Throughout the course examples and applications will be used. When possible, guest lectures will be

offered by experts on a particular tool for tackling complex issues. For the written, take-home exam, students will

have to select a specific complex problem, analyse it and come up with a recommendation – in addition to answering several questions about the material learned.

Intended Learning Outcomes

Upon completion of this module, students will be able to

- 1. Identify a complex problem;
- 2. Develop an acceptable recommendation for resolving complex problems.
- 3. Understand the roles that natural and social scientists can play in helping stakeholders resolve complex problems;

Indicative Literature

Camillus, J. (2008). Strategy as a wicked problem. Harvard Business Review 86: 99-106.

Chia, A. (2019). Distilling the essence of the McKinsey way: The problem-solving cycle. Management Teaching Review 4(4): 350-377.

Den Haan, J., van der Voort, M.C., Baart, F., Berends, K.D., van den Berg, M.C., Straatsma, M.W., Geenen, A.J.P., & Hulscher, S.J.M.H. (2020). The virtual river game: Gaming using models to collaboratively explore river management complexity, Environmental Modelling & Software 134, 104855,

Folke, C., Carpenter, S., Elmqvist, T., Gunderson, L., Holling, C.S., & Walker, B. (2002). Resilience and sustainable development: Building adaptive capacity in a world of transformations. AMBIO: A Journal of the Human Environment 31(5): 437-440.

Ostrom, E. (2010). Beyond markets and states: Polycentric governance of complex economic systems. American Economic Review 100(3): 641-72.

Pielke, R. Jr. (2007). The honest broker: Making sense of science in policy and politics. Cambridge: Cambridge University Press.

Project Management Institute (2021). A guide to the project management body of knowledge (PMBOK® guide). Schon, D.

A., & Rein, M. (1994). Frame reflection: Toward the resolution of intractable policy controversies. New York: Basic Books.

Simon, H. A. (1973). The structure of ill structured problems. Artificial Intelligence 4(3-4): 181-201.

Verweij, M. & Thompson, M. (Eds.) (2006). Clumsy solutions for a complex world. London: Palgrave Macmillan.

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment Type: Written examination

Duration: 120 min Weight:

100%

Scope: All intended learning outcomes of the module.

8.2.7 Argumentation, Data Visualization and Communication (perspective I)

| Module Name | | Module Code CTNS-NSK-07 | Level (type) Year 3 New | СР 5 | | | | |
|---|---|--|---|---|--|--|--|--|
| Argumentation, (perspective I) | Data Visualization and Communication | | Skills | 5 | | | | |
| Module Components | | | | | | | | |
| Number | Name | | Туре | СР | | | | |
| CTNS-07 | Argumentation, Data Visualization and Commur | nication | Lecture (online) | 5 | | | | |
| Module Coordinator | Program Affiliation | | Mandatory Status | | | | | |
| Prof. Dr. Jules Coleman, Prof. Dr. Arvid Kappas | Mandatory elect UG students (on perspective mus chosen) | e | | | | | | |
| Entry Requirements | | Frequency | Forms of Learn | ing and | | | | |
| | | Appually (Fall) | Teaching | | | | | |
| Pre-requisites Logic | Co-requisites Knowledge, Abilities, or | Annually (Fall) | Online Lectures (35h) P | | | | | |
| | Skills | | Study (90h) | | | | | |
| | | Duration | Workload | | | | | |
| Causation & Correlation | | Duration | workload | | | | | |
| | | 1 semester | 125h | | | | | |
| whereas the forme nypothesis, or a jud discourse is govern an argument or the in n its most general r well as in defense of with different cont conditions and mor more importantly, i argumentation req | Preparation not to confuse argumentation with being argument r is a requirement of publicly holding a belief, as ligment of the value of a person or an asset. It is ed by norms and one of those norms is that those responsibility of another for wrongdoing open them neaning, argumentation is the requirement that of the judgments and assessments they reach. There exets and disciplines. Legal arguments have a s al character. In each case, there are differences n the standards of assessment for whether a case uire can call for different modes of reasoning. W gments we make and hypotheses we offer, but w | serting the truth of a s an essential compo e who assert the trut selves up to good fait one offer evidence in s e are different modal tructure of their ow in the kind of evide e has been successfu e not only offer reas | a proposition, the p onent of public disc h of a proposition of h requests to defen upport of the claims ities of argumentat m as do assessmer nce that is thought Ily made. Different ons in defense of o | lausibility of ourse. Pub the validity d their claim they make, on associate ts of medic relevant an modalities | | | | |
| unstructured yet ap | informal and sometimes even appear unstruppropriate what we usually have in mind is that it From A we infer B, and from A and B we infer C, v | is not linear. Most | reasoning we are fa pport our commitm | miliar with | | | | |

Especially in cases where reasoning can be supported by quantitative data, wherever quantitative data can be obtained either directly or by linear or nonlinear models, the visualization of the corresponding data can become

key in both, reasoning and argumentation. A graphical representation can reduce the complexity of argumentation and is considered a must in effective scientific communication. Consequently, the course will also focus on smart and compelling ways for data visualization - in ways that go beyond what is typically taught in statistics or mathematics lectures. These tools are constantly developing, as a reflection of new software and changes in state of the presentation art. Which graph or bar chart to use best for which data, the use of colors to underline messages and arguments, but also the pitfalls when presenting data in a poor or even misleading manner. This will also help in readily identifying intentional misrepresentation of data by others, the simplest to recognize being truncating the ordinate of a graph in order to exaggerate trends. This frequently leads to false arguments, which can then be readily countered.

There are other modalities of reasoning that are not linear however. Instead they are coherentist. We argue for the plausibility of a claim sometimes by showing that it fits in with a set of other claims for which we have independent support. The fit is itself the reason that is supposed to provide confidence or grounds for believing the contested claim.

Other times, the nature of reasoning involves establishing not just the fit but the mutual support individual items in the evidentiary set provide for one another. This is the familiar idea of a web of interconnected, mutually supportive beliefs. In some cases, the support is in all instances strong; in others it is uniformly weak, but the set is very large; in other cases, the support provided each bit of evidence for the other is mixed: sometimes strong, sometimes weak, and so on.

There are three fundamental ideas that we want to extract from this segment of the course. These are (1) that argumentation is itself a requirement of being a researcher who claims to have made findings of one sort or another; (2) that there are different forms of appropriate argumentation for different domains and circumstances; and (3) that there are different forms of reasoning on behalf of various claims or from various bits of evidence to conclusions: whether those conclusions are value judgments, political beliefs, or scientific conclusions. Our goal is to familiarize you with all three of these deep ideas and to help you gain facility with each.

Intended Learning Outcomes

Students acquire transferable and key skills in this module. By the

end of this module, the students will be able to

- 1. Distinguish among different modalities of argument, e.g. legal arguments, vs. scientific ones.
 - 2. Construct arguments using tools of data visualization.
- 3. Communicate conclusions and arguments concisely, clearly and convincingly.

Indicative Literature

- Tufte, E.R. (1985). The visual display of quantitative information. The Journal for Healthcare Quality (JHQ), 7(3), 15.
- Cairo, A (2012). The Functional Art: An introduction to information graphics and visualization. New Ridders.
- Knaflic, C.N. (2015). Storytelling with data: A data visualization guide for business professionals. John Wiley & Sons.

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment Type: Written Examination

Duration/Length: 120 (min) Weight: 100%

Scope: All intended learning outcomes of the module

8.2.8 Argumentation, Data Visualization and Communication (perspective II)

| Module Name | | Module Code | Level (type) | СР | | | |
|--|-------------------------|--|--------------|--|-------------|--|--|
| Argumentation, Da | ata Visualization and | Communication (perspective II) | CTNS-NSK-08 | Year 3 New Skills | 5 | | |
| Module Component | ts | | L | | | | |
| Number | Name | | | Туре | СР | | |
| CTNS-08 | Communication, Ir | nteraction, and Argumentation | | Lecture (online) | 5 | | |
| Module Coordinator | Mandatory Status | | | | | | |
| Prof. Dr. Jules Coleman, Prof. Dr. Arvid Kappas | | UG students (one perspective must be chosen) | | | | | |
| Entry Requirements | | | Frequency | Forms of Learning | and Teachin | | |
| Pre-requisites Logic | Co-requisites ⊠ none | Knowledge, Abilities, or Skills • ability and | annually | Lecture (3! Tutorial of (10 hours) Private stu | the lecture | | |
| Causation & Correlation | | openness to engage in | | lecture (80 | | | |
| | | interactionsmedia literacy, | Duration | Workload | | | |
| | | critical thinking and a proficient handling of data sources own research in academic literature | 1 semester | 125 hours | | | |

Content and Educational Aims

Humans are a social species and interaction is crucial throughout the entire life span. While much of human communication involves language, there is a complex multichannel system of nonverbal communication that enriches linguistic content, provides context, and is also involved in structuring dynamic interaction. Interactants achieve goals by encoding information that is interpreted in the light of current context in transactions with others. This complexity implies also that there are frequent misunderstandings as a sender's intention is not fulfilled. Students in this course will learn to understand the structure of communication processes in a variety of formal and informal contexts. They will learn what constitutes challenges to achieving successful communication. These aspects will be discussed also in the scientific context, as well as business, and special cases, such as legal context – particularly with view to argumentation theory.

Communication is a truly transdisciplinary concept that involves knowledge from diverse fields such as biology, psychology, neuroscience, linguistics, sociology, philosophy, communication and information science. Students will learn what these different disciplines contribute to an understanding of communication and how theories from these fields can be applied in the real world. In the context of scientific communication, there will also be a focus on visual communication of data in different disciplines. Good practice examples will be contrasted with

typical errors to facilitate successful communication also with view to the bachelor's thesis.

Intended Learning Outcomes

Upon completion of this module, students will be able to

- 1. Analyze communication processes in formal and informal contexts.
- 2. Identify challenges and failures in communication.
- 3. Design communications to achieve specified goals to specific target groups.
- 4. Understand the principles of argumentation theory.
- 5. Use data visualization in scientific communications.

Indicative Literature

- Joseph A. DeVito: The Interpersonal Communication Book (Global edition, 16th edition), 2022
- Steven L. Franconeri, Lace M. Padilla, Priti Shah, Jeffrey M. Zacks, and Jessica Hullman: The Science of Visual Data Communication: What Works Psychological Science in the Public Interest, 22(3), 110–161, 2022
- Douglas Walton: Argumentation Theory A Very Short Introduction. In: Simari, G., Rahwan, I. (eds) Argumentation in Artificial Intelligence. Springer, Boston, MA, 2009

Examination Type: Module Examination

Assessment Type: Digital submission of asynchronous presentation, including reflection Duration/Length:

Asynchronous/Digital submission

Weight: 100%

Scope: All intended learning outcomes of the module

Module achievement: Asynchronous presentation on a topic relating to the major of the student, including a reflection including concept outlining the rationale for how arguments are selected and presented based on a particular target group for a particular purpose. The presentation shall be multimedial and include the presentation of data

The module achievement ensures sufficient knowledge about key concepts of effective communication including a reflection on the presentation itself

8.2.9 Agency, Leadership, and Accountability

| Module Name | | Level (type) | СР | | | | |
|-------------------|--|------------------------|----------------------|---------------|--|--|--|
| Agency, Leadersr | ip, and Accountability | CTNS-NSK-09 | Year 3 New Skills | 5 | | | |
| Module Compone | nts | | | 4 | | | |
| Number | Name | | Туре | СР | | | |
| CTNS-09 | Agency, Leadership, and Accountability | | Lecture (online) | 5 | | | |
| Module | Program Affiliation | | Mandatory Status | | | | |
| Coordinator | | | Mandatory for C | CCE | | | |
| Prof. Dr. Jules | CONSTRUCTOR Track Area | | Mandatory for C | 55E | | | |
| Coleman | | | Mandatory elect | | | | |
| | | | other UG study p | programs | | | |
| Entry Requirement | 5 | Frequency | Forms of Learn | ing and | | | |
| | | | Teaching | | | | |
| Pre-requisites | Co-requisites Knowledge, Abilities, or | Annually (Spring) | Online Lectures (| s (35h) Priva | | | |
| The requisites | Skills | (Spring) | Study (90h) | , | | | |
| 🛛 none | ⊠ none | Duration | Workload | | | | |
| | | | | | | | |
| | | | 125 hours | | | | |
| Recommendations | for Preparation | | | | | | |
| | | | | | | | |
| Content and Educa | <mark>tional Aims</mark> ed by the actions we undertake and held to account | for the consequence | es of them Sometim | es we may | | | |
| | d acts don't have harmful effects on others. Other | | | - | | | |
| | pected or unforeseen adverse consequences for c | | | | | | |
| | utcomes. In either case, accountability expresses th | | | | | | |
| | as as a result. But our responsibility and our account | ability in these case | s is closely connect | ed to the id | | | |
| that we have age | ncy. | | | | | | |
| Agency presume | s that we are the source of the choices we make and | I the actions that res | sult from those choi | ces. For som | | | |
| - | e idea that we have free will. But there is scientific | | | | | | |
| - | t explain them, which is the idea that if we knew the | - | | | | | |
| | would make even before you made it. If that is so, nsible for it? And if you cannot be responsible, how o | | | | | | |
| | express the centuries old questions about the related the conflict between a scientific world view and a more | | free will and a dete | erminist wo | | | |
| loosely organize | ways act as individuals. In society we organize ourse d market economies, political societies, companie ven the responsibility of leading the group and of e | es, and more. The | se groups have stru | ucture. Sor | | | |

Exercising authority is not the same thing as being a leader? For one can lead by example or by encouraging others to exercise personal judgment and authority. What then is the essence of leadership?

over others in a group merely by giving orders and threatening punishment for non- compliance.

The module has several educational goals. The first is for students to understand the difference between actions that we undertake for which we can reasonably held accountable and things that we do but which we are not responsible for. For example, a twitch is an example of the latter, but so too may be a car accident we cause as a result of a heart attack we had no way of anticipating or controlling. This suggests the importance of control to responsibility. At the heart of personal agency is the idea of control. The second goal is for students to understand what having control means. Some think that the scientific view is that the world is deterministic, and if it is then we cannot have any personal control over what happens, including what we do. Others think that the quantum scientific view entails a degree of indeterminacy and that free will and control are possible, but only in the sense of being unpredictable or random. But then random outcomes are not ones we control either. So, we will devote most attention to trying to understand the relationships between control, causation and predictability.

But we do not only exercise agency in isolation. Sometimes we act as part of groups and organizations. The law often recognizes ways in which groups and organizations can have rights, but is there a way in which we can understand how groups have responsibility for outcomes that they should be accountable for. We need to figure out then whether there is a notion of group agency that does not simply boil down to the sum of individual actions. We will explore the ways in which individual actions lead to collective agency.

Finally we will explore the ways in which occupying a leadership role can make one accountable for the actions of others over which one has authority.

Intended Learning Outcomes

Students acquire transferable and key skills in this module. By the

end of this module, the students will be able to

- 1. Understand and reflect how the social and moral world views that rely on agency and responsibility are compatible, if they are, with current scientific world views.
- 2. understand how science is an economic sector, populated by large powerful organizations that set norms, fund research agendas.
- 3. identify the difference between being a leader of others or of a group whether a research group or a lab or a company and being in charge of the group.
- 4. learn to be a leader of others and groups. Understand that when one graduates one will enter not just a field of work but a heavily structured set of institutions and that one's agency and responsibility for what happens, what work gets done, its quality and value, will be affected accordingly.

Indicative Literature

Hull, David L. "Science as a Process." Science as a Process. University of Chicago Press, 2010; Feinberg, Joel.

"Doing & deserving; essays in the theory of responsibility." (1970).

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment Type: Written examination

Duration/Length: 120 min Weight: 100%

Scope: All intended learning outcomes of the module

8.2.10 Community Impact Project

| Module Name | | Module Code | Level (type) | СР | | | | |
|---|--------------------|---|----------------------------|---|----------------|--|--|--|
| Community Impact Project | t | | CTNC-CIP-10 | Year 3 New Skills | 5 | | | |
| Module Components | | | | | | | | |
| Number | Name | | | Туре | СР | | | |
| CTNC-10 | Community Imp | act Project | | Project | 5 | | | |
| Module Coordinator | Program Affiliatio | n | | Mandatory Statu | s | | | |
| CIP Faculty Coordinator | CONSTRUC | CTOR Track Area | | Mandatory elective | | | | |
| Entry Requirements | | | Frequency | Forms of Learni Teaching | ing and | | | |
| Pre-requisites | Co-requisites | Knowledge, Abilities, or Skills | Annually (Fall /Spring) | Introducto accompan | ying, and | | | |
| ⊠ at least 15 CP from CORE modules in the major | ⊠ None | Basic knowledge of the main concepts and methodological instruments of the respective disciplines | | final event hours • Self-organ teamwork practical w communit | ized and/or | | | |
| | | uscipinies | Duration | Workload | | | | |
| | | | 1 semester | 125 hours | | | | |

Develop or join a community impact project before the 5th or 6th semester based on the introductory events during the 4th semester by using the database of projects, communicating with fellow students and faculty, and finding potential companies, organizations, or communities to target.

Content and Educational Aims

CIPs are self-organized, major-related, and problem-centered applications of students' acquired knowledge and skills. These activities will ideally be connected to their majors so that they will challenge the students' sense of practical relevance and social responsibility within the field of their studies. Projects will tackle real issues in their direct and/or broader social environment. These projects ideally connect the campus community to other communities, companies, or organizations in a mutually beneficial way.

Students are encouraged to create their own projects and find partners (e.g., companies, schools, NGOs), but will get help from the CIP faculty coordinator team and faculty mentors to do so. They can join and collaborate in interdisciplinary groups that attack a given issue from different disciplinary perspectives.

Student activities are self-organized but can draw on the support and guidance of both faculty and the CIP faculty coordinator team.

Intended Learning Outcomes

The Community Impact Project is designed to convey the required personal and social competencies for enabling students to finish their studies at Jacobs as socially conscious and responsible graduates (part of the Constructor University'smission) and to convey social and personal abilities to the students, including a practical awareness of the societal context and relevance of their academic discipline.

By the end of this project, students will be able to

- understand the real-life issues of communities, organizations, and industries and relate them to concepts in their own discipline;
- enhance problem-solving skills and develop critical faculty, create solutions to problems, and communicate these solutions appropriately to their audience;
- apply media and communication skills in diverse and non-peer social contexts;
- develop an awareness of the societal relevance of their own scientific actions and a sense of social responsibility for their social surroundings;
- reflect on their own behavior critically in relation to social expectations and consequences;
- work in a team and deal with diversity, develop cooperation and conflict skills, and strengthen their empathy and tolerance for ambiguity.

Indicative Literature

Usability and Relationship to other Modules

• Students who have accomplished their CIP (6th semester) are encouraged to support their fellow students during the development phase of the next year's projects (4th semester).

Examination Type: Module Examination

Project, not numerically graded (pass/fail) Scope: All intended learning outcomes of the module

8.3 Language and Humanities Modules

The descriptions of the language modules are provided in a separate document, the "Language Module Handbook" that can be accessed from the Constructor University's Language & Community Center internet sites https://constructor.university/student-life/language- community-center.

8.3.1 Humanities

8.3.1.1 Introduction to Philosophical Ethics

| Module Name | | | Module Code | Level (type) | СР | | | |
|---|--|--|--|--|---|--|--|--|
| Introduction to Phil | osophical Ethics | | CTHU-HUM- 001 | Year 1 | 2.5 | | | |
| Module Components | | | | | | | | |
| Number | Name | | Туре | СР | | | | |
| CTHU-001 | Introduction to P | hilosophical Ethics | | Lecture (online) | 2.5 | | | |
| Module Coordinator | Program Affiliation | | | Mandatory Status | | | | |
| Dr. Eoin Ryan | CONST | RUCTOR Track Area | | Mandatory electiv | /e | | | |
| Entry Requirements | | | Frequency | Forms of Learni | ng and | | | |
| Pre-requisites ⊠ none | Co-requisites ⊠ none | Knowledge, Abilities, or Skills | Annually (Fall or Spring) | Teaching Online lectures (17.5 h) P Study (45h) | | | | |
| | | | Duration | Workload | | | | |
| | | | 1 semester | 62.5 hours | | | | |
| Recommendations for | | | | | | | | |
| Content and Educatio | | | | | | | | |
| debate in philosoph introduce students consequentialism of from metaethics (an actually do or expla | ny since the time of to some of the ke r utilitarianism, deo re useful and gener in) and moral psych cribe ideas that are | life that is good for yourself, and f Socrates, and it is a topic that y aspects of philosophical ethic ntology, virtue ethics, natural la ralizable ethical claims even pos hology (how do abstract ethical e key factors in ethics (free will, | continues to be vigor cs, including leading w ethics, egoism) as v ssible; what do ethica principles do when r | rously discussed. Th normative theories vell as some importa al speech and ethica ealized by human p | iis course wi of ethics (e.g ant question I judgement sychologies | | | |

to progress in understanding ethics, as well as some of their difficulties.

Intended Learning Outcomes

Upon completion of this module, students will be able to

- 1. Describe normative ethical theories such as consequentialism, deontology and virtue ethics.
- 2. Discuss some metaethical concerns.
- 3. Analyze ethical language.
- 4. Highlight complexities and contradictions in typical ethical commitments.
- 5. Indicate common parameters for ethical discussions at individual and social levels.
- 6. Analyze notions such as objectivity, subjectivity, universality, pluralism, value.

Indicative Literature

Simon Blackburn, Being Good (2009)

Russ Shafer-Landay, A Concise Introduction to Ethics (2019)

Mark van Roojen, Metaethicas: A Contemporary Introduction (2015)

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment Type: Written Examination

Scope: All intended learning outcomes of the module.

Duration/Length: 60 min Weight: 100%

8.3.1.2 Introduction to the Philosophy of Science

| Module Name | Level (type) | СР | | | | | | | |
|--|--|--|--|--|--|--|--|--|--|
| Introduction to the | Philosophy of Science | | CTHU-HUM- 002 | Year 1 | 2.5 | | | | |
| Module Components | 5 | | | | | | | | |
| Number | Name | | | Туре | СР | | | | |
| CTHU-002 | Introduction to the Phi | ilosophy of Science | | Lecture (online) | 2.5 | | | | |
| Module Coordinator | Module Coordinator Program Affiliation | | | | | | | | |
| Dr. Eoin Ryan | CONSTRUCT | Mandatory electiv | e | | | | | | |
| Entry Requirements Pre-requisites ⊠ none | • | nowledge, Abilities, or kills | Frequency Annually (Fall or Spring) | Forms of Learning and Teaching Online lectures (17.5h) Pr Study (45h) | | | | | |
| | | | Duration | Workload | | | | | |
| | | | 1 semester | 62.5 hours | | | | | |
| | nal Aims odule will introduce stud | dents to some of the centr | | | | | | | |
| and anti-realism, t sciences, scientism physics, biology). The course aims to | he role of explanation, and the values of scier give students an underst | e, types of inference and th , the nature of scientific of nce, as well as some exan tanding of how science pro- er entirely transparent, ne | change, the differer nples from philosop oduces knowledge, a | nce between natura hy of the special so nd some of the vario | al and socia iences (e.g ous context | | | | |

and issues which mean this process is never entirely transparent, neutral, or unproblematic. Students will gain a critical understanding of science as a human practice and technology; this will enable them both to better understand the importance and success of science, but also how to properly critique science when appropriate.

Intended Learning Outcomes

Upon completion of this module, students will be able to

- 1. Understand key ideas from the philosophy of science.
- 2. Discuss different types of inference and rational processes.
- 3. Describe differences between how the natural sciences, social sciences and humanities discover knowledge.
- 4. Identify ways in which science can be more and less value-laden.
- 5. Illustrate some important conceptual leaps in the history of science.

Indicative Literature

Peter Godfrey-Smith, Theory and Reality (2021)

James Ladyman, Understanding Philosophy of Science (2002)

Paul Song, Philosophy of Science: Perspectives from Scientists (2022)

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment Type: Written Examination

Scope: All intended learning outcomes of the module.

Duration/Length: 60 min Weight: 100%

8.3.1.3 Introduction to Visual Culture

| Module Name | | | Module Code | Level (type) | СР | | | | |
|-----------------------|-----------------------|--------------------------|---------------------------|------------------------------|--------|--|--|--|--|
| Introduction to Visi | ual Culture | | CTHU-HUM- 003 | Year 1 | 2.5 | | | | |
| Module Component | s | | | | | | | | |
| Number | Name | | | Туре | СР | | | | |
| CTHU-003 | Introduction to Visua | l Culture | | Lecture (online) | 2.5 | | | | |
| Module Coordinator | Program Affiliation | | | Mandatory Status | | | | | |
| | CONSTRUC | TOR Track Area | | | | | | | |
| Dr. Irina Chiaburu | | | Mandatory elective | | | | | | |
| Entry Requirements | | | Frequency | Forms of Learnin Teaching | ng and | | | | |
| Pre-requisites | Co-requisites K | (nowledge, Abilities, or | Annually (Spring/Fall) | Online Lecture | | | | | |
| | S | kills | | | | | | | |
| 🗵 none | | • | Duration | Workload | | | | | |
| 🖾 none | ⊠ none | | 1 semester | | | | | | |

Content and Educational Aims

Of the five senses, the sense of sight has for a long time occupied the central position in human cultures. As John Berger has suggested this could be because we can see and recognize the world around us before we learn how to speak. Images have been with us since the earliest days of the human history. In fact, the earliest records of human history are images found on cave walls across the world. We use images to capture abstract ideas, to catalogue and organize the world, to represent the world, to capture specific moments, to trace time and change, to tell stories, to express feelings, to better understand, to provide evidence and more. At the same time, images exert their power on us, seducing us into believing in their 'innocence', that is into forgetting that as representations they are also interpretations, i.e., a particular version of the world.

The purpose of this course is to explore multiple ways in which images and the visual in general mediate and structure human experiences and practices from more specialized discourses, e.g., scientific discourses, to more informal and personal day-to-day practices, such as self-fashioning in cyberspace. We will look at how social and historical contexts affect how we see, as well as what is visible and what is not. We will explore the centrality of the visual to the intellectual activity, from early genres of scientific drawing to visualizations of big data. We will examine whether one can speak of visual culture of protest, look at the relationship between looking and subjectivity and, most importantly, ponder the relationship between the visual and the real.

Intended Learning Outcomes

Upon completion of this module, students will be able to

- 1. Understand a range of key concepts pertaining to visual culture, art theory and cultural analysis
- 2. Understand the role visuality plays in development and maintenance of political, social, and intellectual discourses
- 3. Think critically about images and their contexts
- 4. Reflect critically on the connection between seeing and knowing

Indicative Literature

Berger, J., Blomberg, S., Fox, C., Dibb, M., & Hollis, R. (1973). Ways of seeing.

Foucault, M. (2002). The order of things: an archaeology of the human sciences (Ser. Routledge classics). Routledge.

Hunt, L. (2004). Politics, culture, and class in the French revolution: twentieth anniversary edition, with a new preface (Ser. Studies on the history of society and culture, 1). University of California Press.

Miller, V. (2020). Understanding digital culture (Second). SAGE.

Thomas, N. (1994). Colonialism's culture: anthropology, travel and government. Polity Press.

Usability and Relationship to other Modules

Examination Type: Module Examination

Assessment: Written examination

Duration/Length: 60 min.

Weight: 100%

Scope: all intended learning outcomes

9 Appendix

9.1 Intended Learning Outcomes Assessment-Matrix

| | | | | | | | | | | | r – | | _ | _ | _ | _ | | | - 1 | _ | | | | - | _ | | | | | |
|---|-----|------|-------|---|--|--|--------------------------------|--------------------------|----------------------------------|---|----------|------------------|---------|-------------|------------------|-----------------|-----------------|-------------------------|-------------|-----------------|----------------------------|--------------|----------------------------|----------------------|----------------------------------|--|------------|---------------|-----------------------------------|-----------------|
| Robotics and Intelligent Systems | | | | | Mathematics and Physical Foundations of Robotics I | Mathematical and Physical Foundations of Robotics II | Algorithms and Data Structures | Programming in C and C++ | General Electrical Engineering I | Digital Systems and Computer Architecture | Robotics | Machine Learning | RIS Lab | Automatio n | Embedded Systems | Control Systems | Computer Vision | Artificial Intelligence | RIS project | Marine Robotics | Human Computer Interaction | Optimization | Elements of Linear Algebra | Elements of Calculus | Probability and Random Processes | Discrete Mathematics / Numerical Methods | Internship | CT New Skills | CT German Language and Humanities | Bachelor Thesis |
| Semester | | | | | 1 | 2 | 2 | 1 | 1 | 2 | 3 | 4 | 3/4 | 4 | 3 | 3 | 3 | 4 | 4 | 5/6 | 5/6 | 5/6 | 1 | 2 | 3 | 4 | 5 | 3-6 | 1-2 | 6 |
| mandatory/mandatory elective | | | | | m | m | m | m | m | m | m | m | me | me | me | me | me | m | m | me | me | me | m | m | m | me | m | me | me | m |
| Credits | | | | | 7.5 | 7.5 | 7.5 | 7.5 | 7.5 | 7.5 | 5 | 5 | 5 | 5 | 5 | 5 | 5 | 5 | 5 | 5 | 5 | 5 | 5 | 5 | 5 | 5 | 15 | 20 | 5 | 15 |
| | Com | pete | ncies | * | | | | | | | | _ | | | _ | | | - î | | | | | | | | | | | | |
| Program Learning Outcomes | Α | E | Р | S | | | | | | | | | | | | | | | | | | | | | | | | | | |
| design basic electronics circuits | x | x | | | | x | x | x | | x | | | | | | | | | | | | | | | | | | | | |
| think in an analytic way at multiple levels of abstraction | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | | x | | |
| develop, analyze and implement algorithms using modern | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| software engineering methods. | х | х | | | | | х | х | | х | | | | | | | х | | x | х | x | | | | | | | | | |
| demonstrate knowledge of kinematics and dynamics of | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| multi-body systems | x | x | | | x | x | | | | | x | | | | | | | | | | | | | | | | | | | |
| design and develop linear and nonlinear control systems | x | x | | | | | | | | | | | | | | x | | | x | | | | | | | | | | | |
| design basic electronics circuits | x | x | | | x | x | | | x | | | | | | x | ~ | | | ^ | | | | | | | | | | | |
| examine physical problems, apply mathematical skills to | | | | | | ~ | | | | | | | | | ^ | | | | | | | | | | | | | | | |
| find possible solutions and assess them critically | x | х | | | x | | | | | | | | | х | | | | | | | | | | | | | | | | |
| show competence about operational principles of motors | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| and drives | x | х | | | | | | | | | | | | х | | | | | х | | | | | | | | | | | |
| design and develop machine learning algorithms and | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| techniques for pattern-recognition, classification, and | x | x | | | | | | | | | | x | | | | | | | x | | | | | | | | | | | |
| decision-making under uncertainty; | ^ | ^ | | | | | | | | | | ^ | | | | | | | ^ | | | | | | | | | | | |
| o <i>p</i> | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| design and develop computer vision algorithms for inferring 3D information from camera images, and for | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | x | x | | | | | | | | | | | | | | | x | | × | | | | | | | | | | | |
| object recognition and localization | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| model common mechanical and electrical systems that are part of intelligent mobile systems | х | x | | | x | х | | | x | | | | x | | | | | | | | | | | | | | | | | |
| design robotics systems and program them using popular | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| robotics software frameworks | x | х | | | | | | | | | x | | х | | | | | | x | х | | | | | | | | | | |
| use academic or scientific methods as appropriate in the | x | x | x | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| field of Robotics and Intelligent Systems such as defining | ^ | ^ | ^ | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| research questions, justifying methods, collecting, | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| assessing and interpreting relevant information, and | | | | | x | х | х | х | x | х | x | х | x | х | х | x | x | x | х | х | x | х | | | | | | | | |
| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| drawing scientifically founded conclusions that consider | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| social, scientific, and ethical insights | x | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| develop and advance solutions to problems and | x | x | x | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| arguments in their subject area and defend these in | | | | | | | | | | | x | x | x | х | x | x | х | x | x | x | x | x | | | | | х | | | х |
| discussions with specialists and non-specialists; | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| engage ethically with the academic, professional, and | x | | x | x | | | | | | | | | | | | | | | | | | | | | | | | | | |
| wider communities and to actively contribute to a | | | | | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x | x |
| sustainable future, reflecting and respecting different | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| views; | - | | - | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| take responsibility for their own learning, personal, and | x | | x | x | | | | | | | Ι. | | | | | | | | | | | | | | | | | | | |
| professional development and role in society, evaluating | | | | | x | x | х | х | x | x | x | x | x | х | x | x | х | x | × | х | x | x | х | х | х | x | x | x | × | х |
| critical feedback and self-analysis; | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| apply their knowledge and understanding to a professional | x | x | x | | | | | | | | x | x | x | x | х | x | x | x | x | x | | x | | | | | | | | |
| context; work effectively in a diverse team and take responsibility | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | × | | x | | x | x | | | | | | | | x | | | | | x | х | | | | | | | х | | | |
| in a team; adhere to and defend othical, scientific, and professional. | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | _ |
| adhere to and defend ethical, scientific, and professional | x | | x | x | x | x | x | х | x | х | x | x | x | x | х | x | x | x | x | x | x | x | х | x | x | x | x | x | x | x |
| standards. | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Assessment Type | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Written examination | | | | | x | x | x | x | x | х | x | X | | x | | x | x | x | | | | x | x | x | x | x | | x | x | |
| Term paper | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Essay | | | | | | | | | | | | | | | | | | | | | | | | | | | | | x | |
| Project report | | | | | | | | | | | | | | | | | | | x | | | | | | | | x | x | | |
| Poster presentation | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Laboratory report | | | | | | | | | x | | | | x | | | | | | | | | | | | | | | | | |
| Program Code | | | | | | | | x | | | | | | | | | | | | | | | | | | | | | | |
| Oral examination | | | | | | | | | | | | | | | | | | | | x | | | | | | | | | x | |
| Presentation | | | | | | | | | | | | | | | | | | | x | | | | | | | | | x | x | x |
| Practical Assessments | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Project Assessments | | | | | | | | | | | | | | | x | | | | | | x | | | | | | | | | |
| Portfolio Assessments | | | | | | | | | | | I | | | | | | | | | | | | | | | | | | | |
| Bachelor Thesis | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | x |
| Module achievements | | | _ | ļ | x | x | | | | х | | | | | | | х | | | | | | | | | | | x | x | L |
| | 1 | | 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | _ |

*Competencies: A-scientific/academic proficiency; E-competence for qualified employment; P-development of personality; S-competence for engagement in society

Figure 3: Intended Learning Outcomes Assessment-Matrix